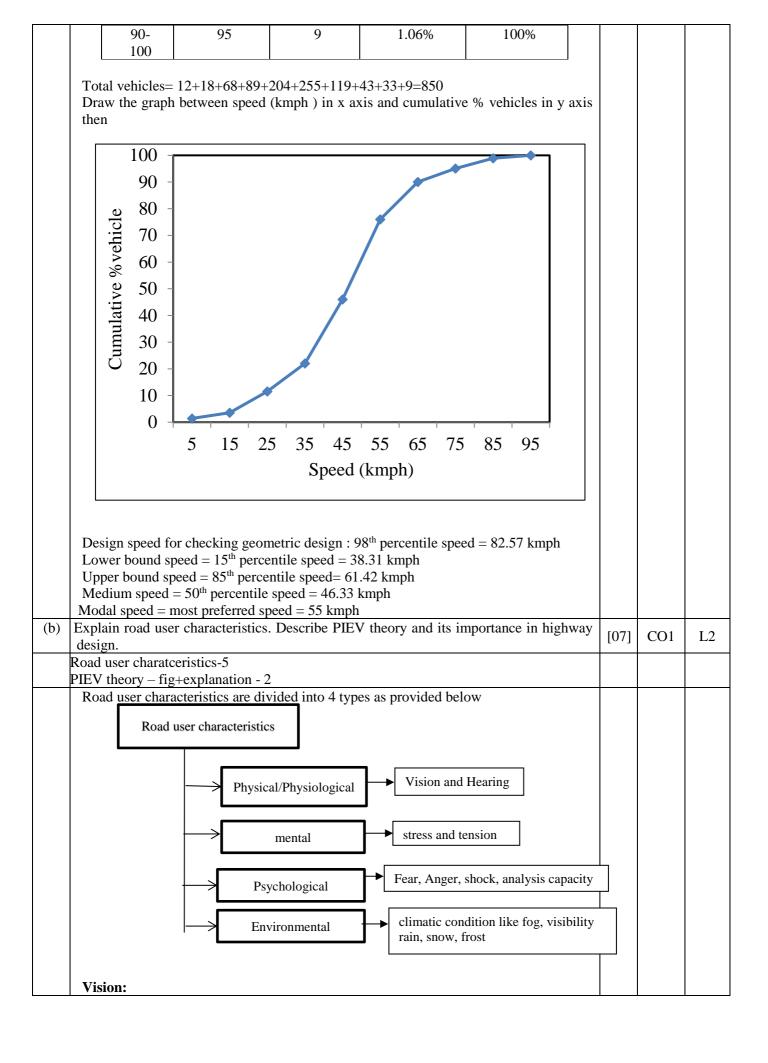
## TRAFFIC ENGINEERING-IAT-1 (Sept 2019) **PART A** Discuss various urban traffic problems that India is facing. List some remedial [07+0]CO<sub>4</sub> L2 measure also. Traffic problems – 7 Solutions - 3 Urban Traffic Problems 1. Urbanization: An urban area is an area with an increased density of human-created structures in comparison to the areas surrounding it. In Indian context urban area is one with the following characteristics: • All places having 5000 or more inhabitants • A density of not less than 400 per square kilometre • At least three fourths of the adult male population employed in pursuits other than agriculture, are treated as urban areas'. 2. Motorization Booming economy, aspirations to own a car, unmatched public transport (with respect to demand, comfort or both), the government's encouraging policies (open car market, easy loan schemes), etc. are a few reasons for increasing motorization at a rapid rate. Modal share A major portion of vehicular composition during peak hour on important corridors in the metropolitan cities consists of cars, two wheelers and Intermediate Public Transport (IPT) (even though their mode share is less compared to PT), which clearly indicates the reason for extreme congestion on Indian urban roads during peak hours 3. Effects on mobility Mobility can be assessed in terms of speed, travel times, delays, etc. along the important corridors of the city. The average journey speed on important city corridors is in the range of 17-26 kmph. For the major cities, 0.25 is the average congestion Index index on a scale of 0-0.6, where '0' indicates good and '0.6' indicates poor index value, the congestion index is calculated as (1 - x/y), where x is the observed speed and y is the expected speed. The average volume to capacity (V/C) ratio on major corridors within cities (in 2007) has already reached values closer to or exceeding 1. **4. Effects on safety** According to WHO, India topped in road accident fatalities, than any other country in the world. **5. Effects on environment** Transport sector has a major share of 26% of total carbon emissions as compared to other sectors. Also, within the emissions from the transport sector, road transport has a major share of 65% as compared to rail, air and water transport. The major share of fuel consumption as well as emissions is by cars and two-wheelers as compared to buses. This scenario clearly results from the prevailing imbalance in modal split, which is not only affecting mobility, but also the environment. **Solutions:** Transport planning and modelling One of the reasons for unregulated urban growth and sprawl in India is the lack of integration of land-use and transportation planning. Traditional demand modelling techniques which adopt trip-based approach and uses 'trips' as the basic unit of analysis have limitations of dealing with behavioural issues, for instance, modelling multistop tours, etc. Top-down approach should be resorted to wherein we start with a set of goals/ objectives. **Non-motorized transport**

In Indian cities, CBD's are the most congested/polluted parts and NMT unfriendly because the private vehicles are allowed to enter a CBD and it is perceived as good

	for businesses located inside a CBD. Study on impact of NMT and/or PT zones on the overall mobility within and outside a CBD, and on the businesses in general. Improve pedestrian facilities.  Public transport  An affordable, networked public transport with a desired minimum level of service			
	would always attract ridership in Indian cities Good integration of multi-modal mass transit systems to serve the overall mobility needs of the city. Inter- and intra-connectivity that utilizes public and private mode and develop an efficient transport system.			
	Driver behaviour and road safety Introducing an effective and comprehensive driver licensing and testing programme all over the country Effective and comprehensive driver education courses.			
	Traffic management Leving parking charges in CBDs and other busy areas. Develop a clear parking policy which would guide the fixation of tariffs and other restraints on vehicular parking.			
	Congestion pricing is another good instrument to control travel demand.			
	PART B			
2 (a)	A vehicle of weight 1800 Newton has to accelerate at 3 m/s2 from a speed of 10			
	Kmph to 15 Kmph in the first gear. The gradient has $+1.2\%$ and coefficient of			
	rolling resistance is 0.025. The frontal area and coefficient of air resistance are 2.38			
	m2 and 0.39 kg/m2 respectively. The transmission and rear axle gear ratios are	[08]	CO1	L3
	2.85:1 and 3.87:1 respectively. The radius and deformation factor of the tyres are			
	$0.35\ \mathrm{m}$ and $0.945\ \mathrm{respectively}.$ Determine the engine horse power required and the			
	speed of the engine if transmission efficiency is 0.9.			
	Total resistance – 4 Engine power -2			
	Speed of the engine -2			
	Weight = $1800 \text{ N}$ ; mg = $1800$ ; m = $183.48 \text{ kg}$			
	Average speed = $12.5 \text{ kmph} = 12.5 *5/18 = 3.47 \text{ mps}$ Tractive force $Pp = Pf + Pa \pm Pi \pm Pj$ Pf = mgf = 183.48 *9.81 *.025 = 44.99  N			
	$Pa = Ca*A v^2 = 0.39 *2.38 * (3.47)^2 = 11.176 N$			
	Pa = Ca*A $v^2$ = 0.39 *2.38 * (3.47) <sup>2</sup> = 11.176 N Pi = mgi = 183.48*9.81*1.2/100 =21.599 N			
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		ı	T 1	
	$\lambda$ : tyre deformation factor			
	n = 1105.54  rpm			
( <b>b</b> )	List the different methods for conducting traffic volume studies. Explain			
	•	[07]	CO2	L2
	Registration number plate method and enumerate its advantages and limitations.			
	Listing – 3			
	Registration number plate with advantages and disadvantages -2+1+1			
	<ul><li>Manual method</li><li>Combination of manual and mechanical</li></ul>			
	Multiple pen recorder			
	Automatic/mechanical counter methods			
	> Pneumatic tube			
	Electric contact devices			
	Coaxial cable			
	<ul> <li>Photoelectric devices</li> </ul>			
	Radar			
	Moving Observed method			
	<ul> <li>Photographic/video graphic method</li> </ul>			
	Registration number plate method			
	Used for measurements of running and journey speed:			
	✓ Observers are stationed at the ends of measuring section say 0.5 km -1 km			
	✓ Time and registration no of the vehicle are recorded as and when they enter and			
	leave the section			
	✓ By matching registration nos later, journey time and speed can be determined			
	Advantages:			
	No sophisticated instruments are required			
	Easy			
	Disadvantages:			
	1) Laborious, time consuming			
	2) Cannot be used for urban roads with many intersections, Hence convenient only			
	for rural roads			
	3) Only journey speed can be determined not running speed			
(c)	Write a short note on 30th highest hourly volume and explain its significance.	[05]	CO2	L1
	Explanation+fig – 3+2			
	Thirtieth highest hourly volume is the hourly volume that will be reached only			
	thirty times in a year or exceeded only 29 times in a year and all other hourly			
	volumes of this year will be less than this value.			
	<b>Significance:</b> the highway facility design with respect to 30th highest hourly			
	as cost. This is because cost is less when compared to peak hourly volume and			
	there will be congestion only 29 hours in a year which is a reasonable measure.			
	volume is found to be satisfactory with respect to consideration of facility as well as cost. This is because cost is less when compared to peak hourly volume and			

		Hourly volume as a proportion of AADT	0.15 - 0.14 - 0.13 - 0.12 - 0.11 - 0.10 -		20	Peri 40 Number	r of hou	r a Ty	umes pical F	vith	a One-Year way				
S	data ar	e tab geom dal s	ulated a etric de peed Group	os follo esign ( 0- 10	ows. Su iii) Lov 11- 20	iggest (wer spe	(i) High eed gro 30- 40	40-50	sing consists of the state of t	t for re	period of time a egulation (ii) Sp on (iv) Medium	peed to	[08]	CO2	L3
S	Speed		Group	60-70	70- 80	80-90	90-100	204	255						
	No. of v	ehic	lec	119	43	33	9								
	Table+			117	7.7	33	)								
	Speed 1	limit	s under			•									
		Spectrang (km h)	ge p	Aver Spe (km	eed		No of chicles	,	% vehi (no o vehicles al vehic	f s/tot	Cumulativ e % vehicles				
		0-1		5	j		12		1.41%	,	1.41%				
		10-2		1:			18		2.129		3.53%				
		20-3	30	2.	5		68		8.00%	6	11.53%				
1			1				89		10.479	%	22%				
		30-4	10	3.	3					, -			i	1	1
		30-4 40-5		4:			204		24.009		46%				
			50		5		204 255		24.009 30.009	%	46% 76%				
		40-5 50-6	50	5:	5		255		30.009	% %	76%				
		40-5	60 60 70	4.	5 5 5					% % %					



**Acute or clear vision cone**-3" to 10" around the line of sight; legend can be read only within this narrow field of vision.

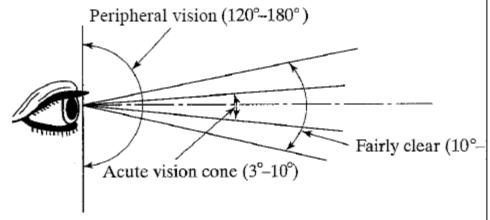
- Traffic signs are placed with in acute vision field
- Driver can see without changing his sight

**Fairly clear vision cone**-10" to 12" around the line of sight; color and shape can be identified in this field.

Color and shapes can be identified

**Peripheral vision**-This field may extend up to 90" to the right and left of the centerline of the pupil, and up to 60" above and 70" below the line of sight.

- > Stationary objects can not be detected but moving object can be
- > Peripheral vision helps the driver for judgment of speed of moving vehicle



**Hearing**: Sound of nearing vehicles can alert the pedestrian. Elderly people with falling eye sight can better perceive through hearing.

## PIEV theory:

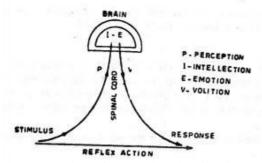
It splits the reaction time of driver into 4 components.

Perception: time required to perceive an object or situation. [function of eyes, ears]

Intellection: time required for understanding the situation. [function of brain]

Emotion: based on our emotions at the time [fear, anger etc] we reach the decision weather we want to stop or not. [function of brain]

Volition: once the decision of stopping has been finalised, time required for moving the foot from the gas to the brake peddle. [Obeying orders of brain; function of legs and hands]



The PIEV time which is the summation of perception, intellection, emotion and volition time is known as total reaction time of the driver. The reaction time is considered as 2.5 seconds in urban and 3 seconds in hilly area for designing stopping sight distance (geometric design element) of roads.

L					<b></b>	l
	(c)	With neat sketch explain enoscope method of measuring spot speed study. Discuss its	[05]	CO2	L1	
		advantages and disadvantages.	[obj			
		Figures+explanation – 3+2				

## This is a long base method FIG. 4.8 Principle of Enoscope or lamp @ Base (say, 50 m) -Vehicle FIG. 4.9 Spot speed using one Enoscope Vehicle Obeserver Line of sight FIG. 4.10 Spot speed using two enoscopes The instrument is placed directly opposite to the first reference point and the observer stations himself at the second reference point. > Stop watch is started as soon as the vehicle passes the first point and is stopped as soon as it passes the observer. ➤ If two enoscope is used, the observer stations himself midway between two reference points. ➤ Advantages: o Eliminates parallax error. o Equipment is of low cost, simple and can set up easily ➤ Disadvantages: o Time consuming and under heavy traffic condition it may be difficult to conduct the experiment 4(a) What are the uses of speed and delay studies? The length of a road stretch used for conducting the moving observer test is 0.5 km and the speed with which the test vehicle moved is 20 km/hr in both directions while moving along and against the flow. Given that the number of vehicles encountered in the stream [80] CO<sub>2</sub> L3 while the test vehicle was moving against the traffic stream is 107, number of vehicles that had overtaken the test vehicle is 10, and the number of vehicles overtaken by the test vehicle is 74, find the flow and average speed of the stream. Uses - 4Flow - 2Average speed – 2

Enoscope/mirror box method:

Uses of speed and delay study:			
- Helps in deciding design speed and other geometric elements of the road such as			
curves, horizontal and vertical alignment - For regulation and control of traffic operations			
e.g. signal design and locations of sign board			
- For analysing the causes of accidents			
- Identify relation between speed and accident			
- Before and after road improvement schemes			
- Determining congestion problems and capacity of roads			
- Necessary for economical analysis			
- To evaluate congestion, capacity and level of service			
- Essential for trip assignment			
<ul> <li>This is important for assessing improvement measures</li> <li>Delay studies provide data for the design and installation of traffic control</li> </ul>			
devices			
Time taken by the test vehicle to reach the other end of the stream while it is			
moving along with the traffic is $tw = 0.5/20 = 0.025 \text{ hr}$			
Time taken by the observer to reach the other end of the stream while it is moving	7		
against the			
traffic is $ta = tw = 0.025 \text{ hr}$			
$q_{along} = \frac{x_{opposite} + (over\ taking\ the\ test\ car - overtaken\ by\ test\ car)_{along}}{t_{opposite} + t_{along}}$			
$q = \frac{107 + (10 - 74)}{0.025 + 0.025}$			
q = 860  veh/hr			
Average speed of the traffic stream = (distance)/mean time			
$t_{along} = t_{along} - rac{y_{along}}{q_{along}}$			
$t_{along} = 0.025 - \frac{10-74}{860}$			
4 000 km			
$t_{along} = 0.099 \ hr$	1		
$t_{along} = 0.099  hr$ Speed = Distnace/ t			
	[07]	CO1	L

Dimensions	Affects on road design			
Length of vehicle	Geometric design, capacity, overtaking distance and maneuver of vehicle, turning radius, parking facility, design of valley and dips			
Width of vehicle	Width of traffic lanes, shoulders and parking, capacity, and traffic flow and traffic density.			
Height of vehicle	Clearance of overhead structure, design of underpasses, height of barricades			
Height of driver seat	Visibility distance			
Height of headlight	Sight distance at valley curves			
Weight	thickness of pavement, the vehicle weight is indirectly dependent upon the size of the vehicle and its turning radius			
overcome all resistance to	ehicles: power developed by the engine should be sufficient to motion at the desired speed and to accelerate at any desired			
Rolling resistance Air resistance Grade resistance	The various forces that are acting are eration and deceleration			
Rolling resistance Air resistance Grade resistance Inertia force during accele Transmission losses Braking system: when br into play and the vehicles and whether it is dry/wet. Acceleration and decele low speeds. Cars have hi caused when the engine is This is dependent upon, interface.	eration and deceleration  rakes are applied, friction between road surface and tyre comes come to a stop. This depends upon the roughness of the surface  ration characteristics: maximum acceleration is achieved at agher acceleration than commercial vehicles. Deceleration is shut off and vehicle is allowed to coast and brakes are applied. the efficiency of brakes and coefficient of friction at the			
Rolling resistance Air resistance Grade resistance Inertia force during accele Transmission losses Braking system: when br into play and the vehicles and whether it is dry/wet. Acceleration and decele low speeds. Cars have hi caused when the engine is This is dependent upon, interface. Speed of the vehicle: the braking sight distance and	eration and deceleration  rakes are applied, friction between road surface and tyre comes come to a stop. This depends upon the roughness of the surface  ration characteristics: maximum acceleration is achieved at agher acceleration than commercial vehicles. Deceleration is shut off and vehicle is allowed to coast and brakes are applied. the efficiency of brakes and coefficient of friction at the his will influence, acceleration and braking characteristics, a different sight distances.			
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Rolling resistance Air resistance Grade resistance Inertia force during accele Transmission losses Braking system: when br into play and the vehicles and whether it is dry/wet. Acceleration and decele low speeds. Cars have hi caused when the engine is This is dependent upon, interface. Speed of the vehicle: the braking sight distance and Define (i) Running speed speed. Each definition – 1.25×4:	eration and deceleration  rakes are applied, friction between road surface and tyre comes come to a stop. This depends upon the roughness of the surface  ration characteristics: maximum acceleration is achieved at the acceleration than commercial vehicles. Deceleration is shut off and vehicle is allowed to coast and brakes are applied. The efficiency of brakes and coefficient of friction at the mis will influence, acceleration and braking characteristics, and different sight distances.  (ii) journey speed (iii) time mean speed (iv) Space mean espeed maintained by a vehicle over a given course while	[05]	CO2	I
Rolling resistance Air resistance Grade resistance Inertia force during accele Transmission losses Braking system: when br into play and the vehicles and whether it is dry/wet. Acceleration and decele low speeds. Cars have hi caused when the engine is This is dependent upon, interface. Speed of the vehicle: th braking sight distance and Define (i) Running speed speed.  Each definition – 1.25×4: Running speed: Average moving. Speed of vehicle	eration and deceleration  rakes are applied, friction between road surface and tyre comes come to a stop. This depends upon the roughness of the surface  ration characteristics: maximum acceleration is achieved at the acceleration than commercial vehicles. Deceleration is shut off and vehicle is allowed to coast and brakes are applied. The efficiency of brakes and coefficient of friction at the mis will influence, acceleration and braking characteristics, and different sight distances.  (ii) journey speed (iii) time mean speed (iv) Space mean espeed maintained by a vehicle over a given course while	[05]	CO2	I

$$Journey speed = \frac{Distance}{Journey time} (kmph)$$

**Space mean speed:** The space mean speed also averages the spot speed, but spatial weightage is given instead of temporal.

Space mean speed for n no of vehicles moving at a speed of  $v_i$  can be given by the following equation

Space mean speed = 
$$\frac{n}{\sum_{i=1}^{n} \frac{1}{v_i}}$$
 (kmph)

**Time mean speed:** Time mean speed is the average of all vehicles passing a point over a duration of time. It is the simple average of spot speed.

Time mean speed 
$$=\frac{1}{n} \left( \sum_{i=1}^{n} v_i \right)$$
 (kmph)