CMR INSTITUTE OF TECHNOLOGY		USN	USN					CMR		
ub:	KINEMATIC		al Assesment Test - I	I	C-1-					
Date:		S OF MACHINES			Code:		15ME42			
	17/04/2018	Duration: 90 mins	Max Marks: 50	Sem: IV – A, B	Branc	:h:	MECI			
nswa	te the missing da	ta wherever required.	All Parts of the sam	e question should	l be	Marks	OI			
	red at one place						CO			
	t-A: Answer any	of a diesel engine has a lift	662.0	. 11		15	CO5	01 L		
1	cam rotation. The radial. Minimum r maximum velocity cam is 300rpm clo	during opening and closing follower is provided with a adius of the cam is 25mm. I and acceleration of the followise.  Accement Da acceleration of the followise.	or roller of 20mm diame Draw the cam profile. Hower during outward	ter and its line of st Also determine the stroke, if the speed	roke is	ak e	ach			
2	Draw the cam prof passes through the Roller diameter = 1 Minimum radius o Total lift = 30mm. The cam has to lift follower to drop su	Tile for cam with roller recipants of the cam. Particular 20mm;  If the cam = 25mm;	procating follower. The s of the cam and follow aring 180° of cam rotation return with uniform vates in anti-clock wise	e axis of the follower are the following ons, and then allow relocity during the direction.	r g:		COS	L3		
	fourth, remains at re remainder of a com profile as 25mm and ascent and descent, period. The axis of direction.	upplied with a plane horizony rotating shaft. The spindlest in one fourth, is lowered plete revolution. Draw the did that the spindle moves with the spindle passes through the spindle	ontal face at its lower ele is raised through a did in one third and rema profile assuming the leith uniform acceleration deceleration period is high the cam axis. The cam	nd is actuated by a distance of 30mm in ins at rest for the east radius of the car and retardation or alf the acceleration is rotates in anti-clock.	one m n both		CO5	L3		

t - B:	B: Answer any two questions.			20]
S 4	tate and derive the law of gearing.	10	CO3	L1
	Statement 2 marks.  Diagram - 1 mark:  Explanation - 2 marks.  Derivation - 5 marks.	10	CO3	LI
5	Define the following with a neat sketch of a gear:  a. Working depth  b. Addendun  c. Root Circle  d. Flank  e. Tooth thickness  f. Circular pitch  Sketch - 4 marks  Definition - 1 mark each  = 1 × 6 = 6 marks	10		
6 a.	Define the following with a neat sketch of a cam:  a. Pressure angle b. Pitch curve c. Prime circle d. Pitch point  Sketch - 2 marks  Definitions - 0.5 mark each  = 0.5×4 = 2 marks.	04	COS	
6 b.	With neat sketches explain the different types of cam classified according to its shape.  3 Classes — Sketch — I mark  Explanation — I mark  eac  i. 3 × 2 marks = 6		s fo	le

## SOLUTION OF KINEMATICS OF MACHINES. 15 ME 42.

Vagt-H

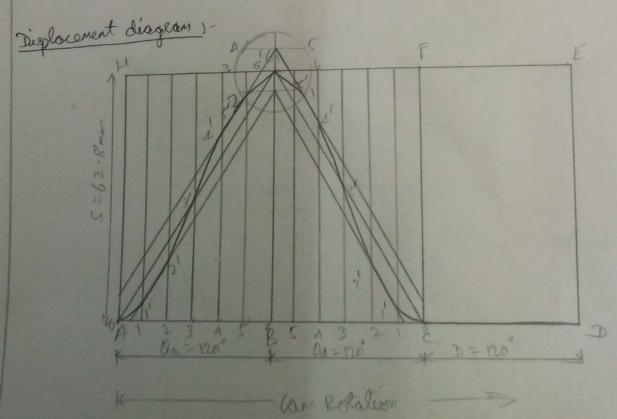
1. The exhaust value of a diesel engine has a lift of 62.8 mm. It is operated by a can to give cycloidal notion during opening & closing pseuds each of which corresponds to 120° of can rotation. The follower is provided with a roller of 20 mm dianoter & its line of stacke is radial. Minimum radius of the can is 25 mm. Derow the can profile. Also determine the maximum of the can is 25 mm. Derow the can profile. Also determine the maximum of the can is 300 rpm clockwise.

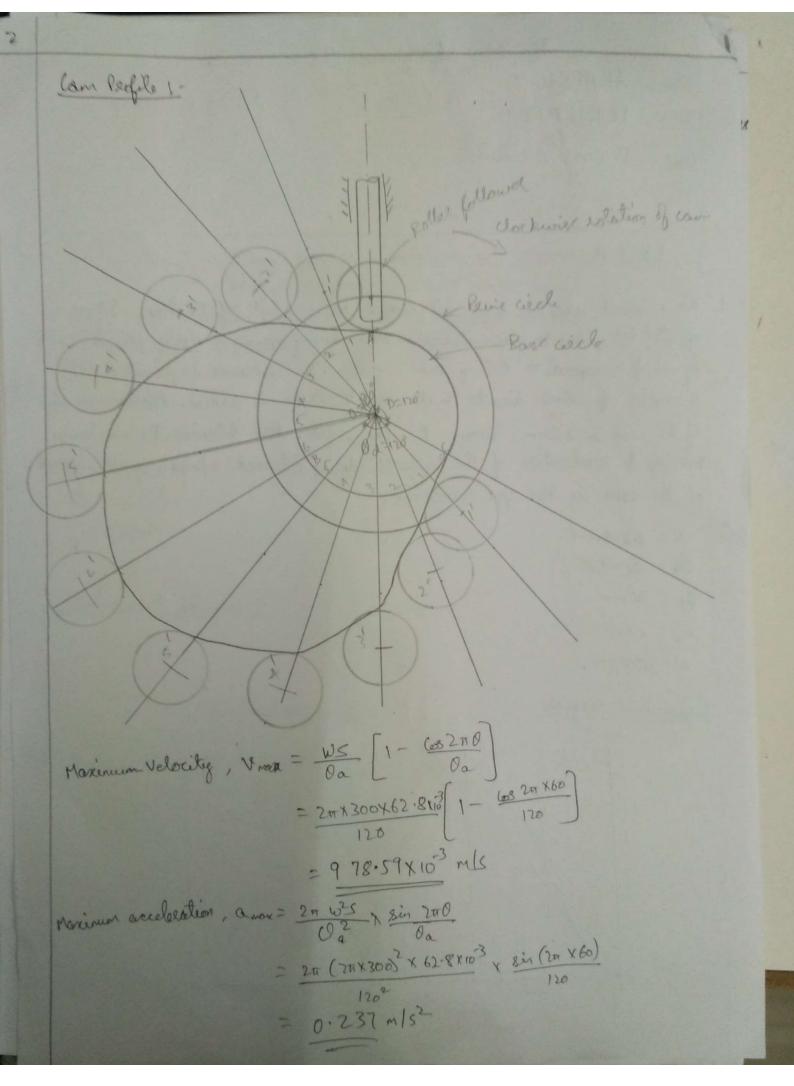
S = 62.8 mm $\partial a = \partial_d = 120^\circ$ 

PR = 20 mm

2 = 25 mm

N=3004pm.





L. Deaw the can peofile for can with roller recipeocating follower.

The axis of the follower passes through the axis of the can. Particulares of the can & follower are the following:

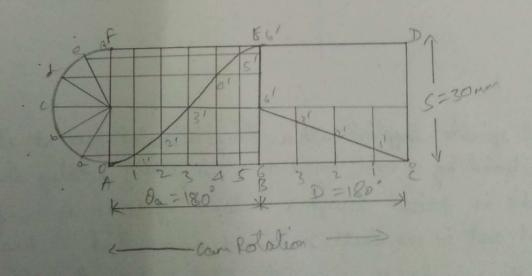
Roller diameter = 20mm Nivinum radius of the com = 25 mm

Total lift = 30mm.
The can has to lift the follower with SHM during 180° of can hotations a then allow the follower to deep suddenly half way & further return with wifam relating during the remaining angle of can rotation.

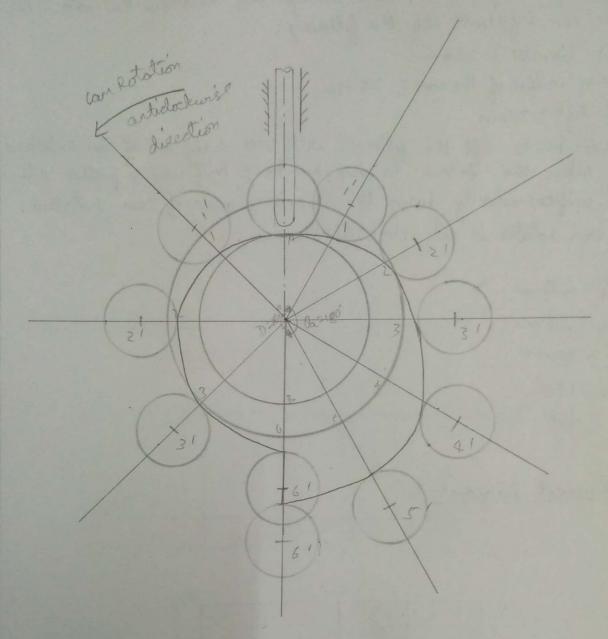
The can rotates in arti-clockwise direction.

 $\phi_{2} = 20mm$   $A_{b} = 25mm$  S = 30mm  $O_{a} = 180^{\circ}$   $D = 180^{\circ}$ 

## Displacement disagrans 1-



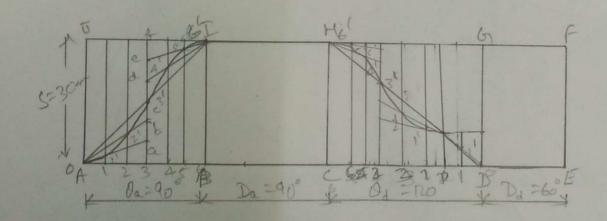
Can Peofele )-

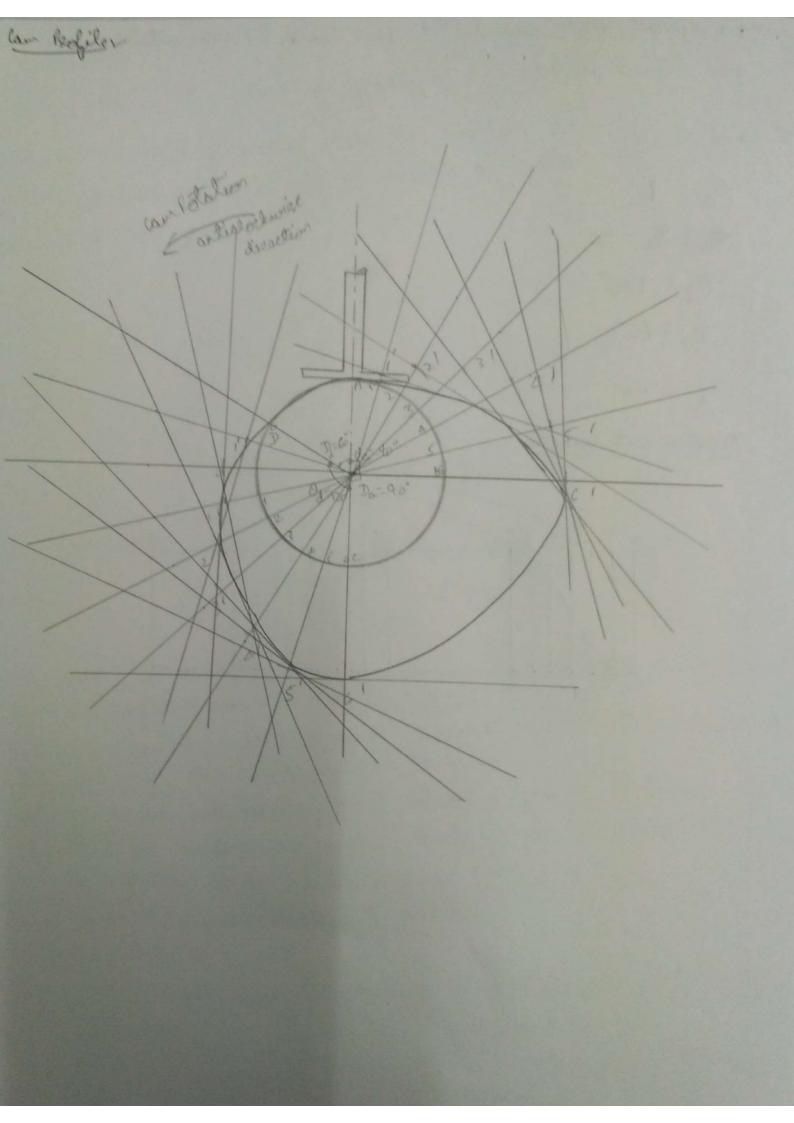


3. A vertical spiralle supplied with a plane hosizontal face at its lower and is actuated by a cam keyed to a uniformly rotating shaft. The spiralle is raised through a distance of 30 mm in one-foreth, semains at rest in one fourth, is lowered in one third I remains at rest for the remainder of a complete rotation. Derew the pefile assuring the least radius of cam peofile as 25 mm & that the spiralle moves with uniform acceleration & rotardation on both ascent & decent. However desiry decent, deceleration presion is half the acceleration period. The axis of

the spiralle passes through the con axis. The can rotates in anti-clockwise direction.

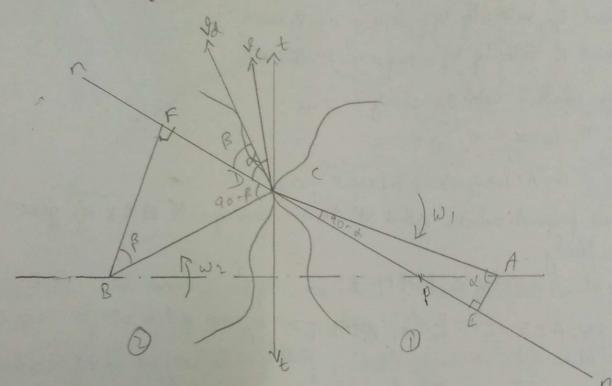
## Displacement diagram:





4. State & desine the law of georing:

Ans. Statements- The law of geneing states the condition which must be fullfilled by the gene tooth profiles in order to maintain a constant angular velocity satioble the two genes.



The point ( on the tooth peofile of gear () is in contact with a point Don the tooth peofile of gear ().

The two curves in contact at point CED must have a common normal at that point. Let the common normal be n-n.

Let w, be the instantaneous angular velocity of gear (1) clockwise. we be the instantaneous angular velocity of gear (2) anticlockwise.

of be the linear velocity at point D.

.: V c = W,AC, in the direction I to A( of at an angle of x to n-n.
Vd = W2. BD, in the direction I to BD of at an angle of B to n-n.

If the curved surfaces of the teeth of two glass are to remain in contact, then one surface may slide relative to the other along the common tangent t-t. Hence the relative nation blue the two surfaces along the common normal n-n must be zero to avoid reparation of penetration of the two teeth into each other.

Component of velocity along n-n=0Component of velocity  $v_c$  along  $n-n=v_c$  cos xComponent of velocity  $v_d$  along  $n-n=v_d$  cos x

.. The relative velocity along n-n is:

1/2 (08 X - 1/2 (08 B = 0

w, ALGSL-WZBDGSB=0

Descent perpendiculars AB & BF to n-n from points A&B of glass D&D.
Respectively.

Hence, LCAE = & & LDBF=F

2) W, ACX AG \_ WZ BD X BF ZO
BD

=> w, AE - WZBF = 0

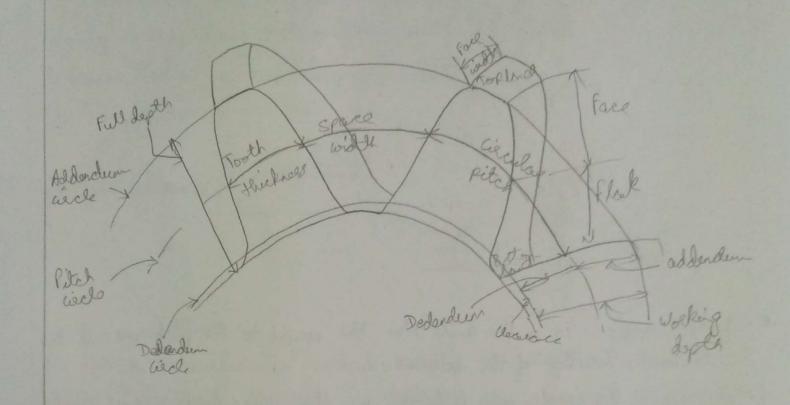
WIAE=WZBF

": De BFP & seA BP are similar, we have

$$\frac{AB}{BP} = \frac{AP}{BP}$$

Thus, it is seen that the centre line AB is devided at point if by the common resemble in the inverse scatio of the angeles velocities of the two grows.

5. Define the following with a rest skatch of a geal:



- g. Working depths. The maximum depth to which a took peretrates into the tooth space of the mating gear is the working depth of teeth.
- h. Addandum: It is the radial height of a tooth above the pitch circle. Its standard value is Involule.
- i. Root wicle: It is the wicle passing through the root of the teeth.
- is. Flank, Toolh surface blo the pitch wick & the bottom land including fillet.
- k. Tooth thickness: It is the thickness of the tooth measured along the petch wick
- 2. Circular pitch. It is the distance measured along the circumference of the pitch circle from a point on one tooth to the corresponding point on the adjacent tooth.

6. a. Define the following with a rest sketch of a com! e. Pressure angle: It is the angle blue the result to the petich while & the instantaneous direction of the followers. 6. liteliment It is the path followed by the trace point. I live wich . It is the circle along the centre of the soller follows h. Pitch point 1-It is the point on the pitch well having maximum plessure angle. different types of can classified 6.6. With next sketches explain the according to its shape

9.11) Flat | Plate | wedge cam;

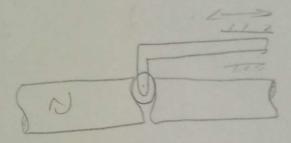
The teanslaterynation of the com is konsmitted as the konslatory motion of the follower.

In such cases hother than having continuous notary motion, they require recipiocating motion. This becomes the limiting factor for its application.

## is Radial coms 1-

The follower is held in position by a specing or by geoutly & the rotary motion of the com is transformed & teansmitted as a translatory or oscillatory motion of the follower.

ii) cylindrical followers



It has a concemperation contour out on the surface of a cylinder which rotates about its axis. The follower may translate or oscillate in the direction of the axis.