

Scheme of Evaluation Internal Assessment Test II– April.2019

S	ub:	Me	Mechanical Measurements & Metrology Code: 17ME46B									
					Max		Sem:	IV	Branch:	ME		
D	ate:	15/04/2019	Duration:	90mins	Marks:	50	Sem.	1 4	Diancii.	IVIL		

Note: Answer Any Five Full Questions.

Qı	uestion #	Description	Marks D	Max Marks	
	a)	What are comparators? Explain any one type of mechanical comparator with neat sketch.			
	Solu.	Definition of Comparator	2M	10 M	
1		Mechanical Comparator – Sigma comparator or Dial Indicator or Johansson Mikrokator			10 M
		- Sketch	4 M		
		- Explanation	4 M		
	a)	Design a plug and ring gauge to control the production of 90mm shaft and hole part of H_8e_9 . Data given a) i= $0.45^3\sqrt{D} + 0.001D$. b) The upper deviations for 'e' shaft =-11D ^{0.41} c) The value for standard tolerance grade IT8=25i and IT9=40i and d) 90mm lies in the diameter step of 80mm and 100mm.			
	Solu.	• Finding,			
		D = 89.44 mm	1 M	10 M	10 M
2		$i(\mu) = 2.102 \mu$	1 M		
2		Hole dimensions are :		10 IVI	10 W1
		Upper limit = 90.0525 mm	2 M		
		Lower limit = 90 mm			
		Shaft dimensions are:			
		Upper limit = 89.9305 mm			
		Lower limit = 89.847 mm	2 M		
		 Design of Plug gauge 			
		Limits of Go gauge			

		Upper limit of Go = 90.00577 mm	2 M		
		Lower limit of $Go = 90.000525 \text{ mm}$			
		Upper limit of No go = 90. 0577 mm			
		Lower limit of NO go = 90.0525 mm			
		Design of Ring gauge			
		Upper limit of Go = 89.927 mm			
		Lower limit of Go = 89.921 mm	2 M		
		Upper limit of No go = 89. 847 mm			
		Lower limit of NO go = 89.838 mm			
	a)	Write a short notes on:			
	u)	(i)Interchangeability, (ii) selective assembly and (iii)Indian standards (IS 919-1963) systems of limits and fits.			
	Solu.	• Interchangeability – (2 M each)			
3		a) Local Interchangeability	4 M	10M	10 M
		b) Universal Interchangeability		TOW	10 101
		• selective assembly	2 M		
		• Indian standards – (2 Marks each)			
		a) Fundamental Tolerance	4 M		
		b) Fundamental Deviation			
	a)	Explain measurement of effective diameter using 2 wire method.			
4	Solu.	 Sketch P = p/2 cot (theta/2) - d cosec(theta/2 -1) P for Metric thread, P = 0.866p - d P for Whitworth tread, P = 0.96 p - 1.165d 	2 M 4 M 2 M 2 M	10 M	10 M
	a)	Sketch and explain the following comparators:			
		a) Zeiss Optimeter			
	Solu.	• Sketch	2 M	5 M	
5	Bolu.	Explanation	3 M		10 M
<i>J</i>	b)	b) Solex Comparators			10 1/1
	Solu.	• Clastah	2 M		
	Soiu.	SketchExplanation	3 M	5 M	
		-	J 1V1		
6	a)	With a neat sketch explain the principle of LVDT.			

	Solu.	• Sketch	2 M	10 M	10 M
		Explanation	2 M		
		• Cases (2 mark each)			
		a) When there is no plunger movement	6 M		
		b) When plunger moves up			
		c) when plunger moves down			
	a)	Illustrate the principle of GO and NOGO gauges.			
		How the Taylor's principle is used in designing			
		them?			
	Solu.	• Sketch (2 Marks each)	4 M		
7		a) Plug gauge			
'		b) Ring/ snap gauge		10M	10 M
		Explanation :	4 M		
		a) Go gauge			
		b) No go gauge			
		• Example	2 M		

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Internal Assesment Test -2

			Internal Assesme	ent Test –2				
		Sub:Mech	anical Measuremn	ts & Metorl	ogy	Coc	le: 17N	/IE46B
Date:	15/04/2019	Duration: 90 mins	Max Marks: 50	Sem: IV	Branch (section	ns):ME	(A & E	3)
		Answer	any FIVE FULL q	uestions. Go	ood luck!			
Scheme and Solution								BE
			Marks	СО	RBT			
1	What are coneat sketch	[10]						
Solu.	Comparato	2 Marks						
		Cantilever				4 Marks	CO3	L2
		4 Marks						
	 One the the The rota Thi there the 	a metal strip at the cent e end of the strip is conther end is to the spri e slight movement of the. Is rotation will create to be the strip start to point. E spring ensures that the	onnected to the a ing elbow, in turn the plunger will ension in the strip twist & untwist	adjustable of connected make the of and cause resulting i	cantilever strip and to the plunger. bell crank lever to s the strip to rotate n the movement of			

2 Design a plug and ring gauge to control the production of 90mm shaft and hole [10] part of H₈e₉. Data given a) $i = 0.45^3 \sqrt{D} + 0.001D$. b) The upper deviations for 'e' shaft = $-11D^{0.41}$ c) The value for standard tolerance grade IT8=25i and IT9=40i and d) 90mm lies in the diameter step of 80mm and 100mm. Given gomm dia lies blu so I womm. Solu. :. D = J 80 X100 = 89.44 mm 1Mark i= 0.453 D+0.001(D) = 0.45 3 89.44 +0.001(89.4) = 2.102 H 1 Mark :. i = 0.002102 mm. Dimensions / limits & hole are: F.T for hade Hy ie. IT8 = 25i = 25 (0.00210) = 0.0525mm. CO₂ L3 F.D for H = 0. · limit wu: UL = 90+0.0525mm . UL = 90.0525mm . UL = 90 mm. Dimemins / limits of shaft all:

F.T fol eq ie. IT9 = 40i = 40 (0.00210)

-2L

F.T = 0.08408 mm.

-2L

F.T = 0.08408 mm.

-2L

F.T = 0.08408 mm.

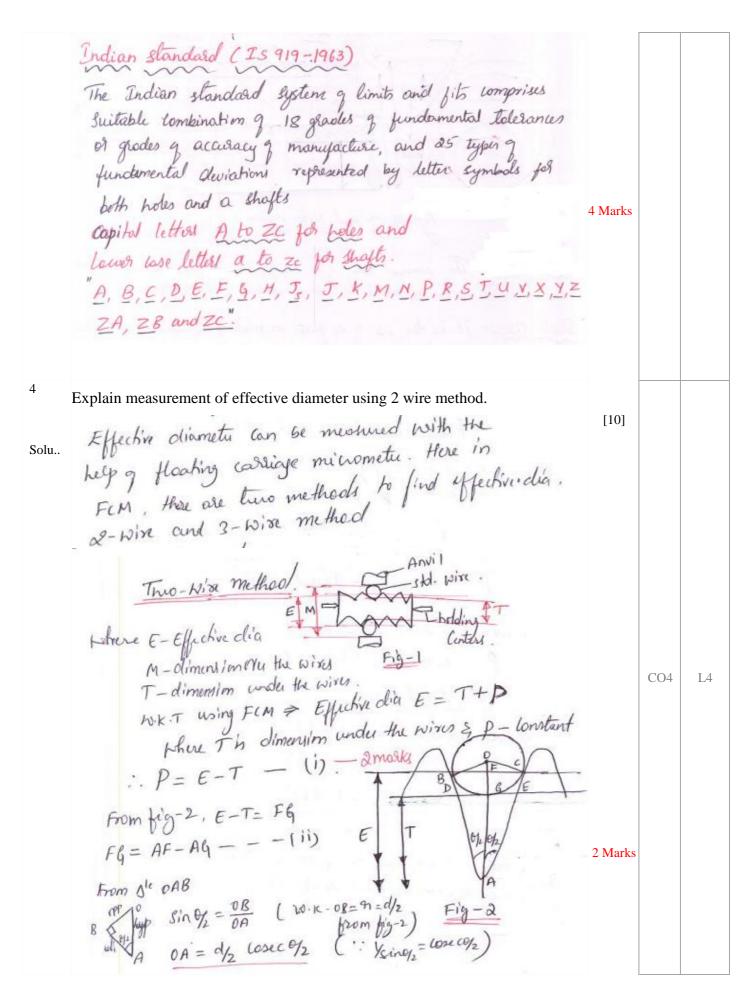
-24

-69.426 \mu = 0.0695mm. 2 Marks limit ar: - uL= 90-0.0695 = 89.9305 mm U = 90-(0.0695-0:08408) = 89.847mm

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Design for hole ( plug gauge)
Garge Tolerance CIT = 10 % of work tolerance of hise
            BT = 0.01 x 0.0525 = 0,00525 mm.
            Wear allowance = 10%. 9 GT
               =0.1x0.00525 = 0.000525mm.
limits of go gauge are:
      UL = 90 + 0.00525 + 0.000525 = 90.00577mm
                                                                 1 Mark
      U = 90 +0. 100525 = 90,000525 mm.
limits of No go gauge are:
        UL = 90+0.0525 +0.00525 = 90.0578 mm
        U = 90 to. 05055 = 90. 0525 mm.
                                                                 1 Mark
Design for shaft ( Snop gauge)
         GT= 10%. & WT = 0.01x0.08408 = 0.00840mm.
WA = 10%. & UT = 0.01x0.00840 = 0.000840mm
   limit of Ge garye all:

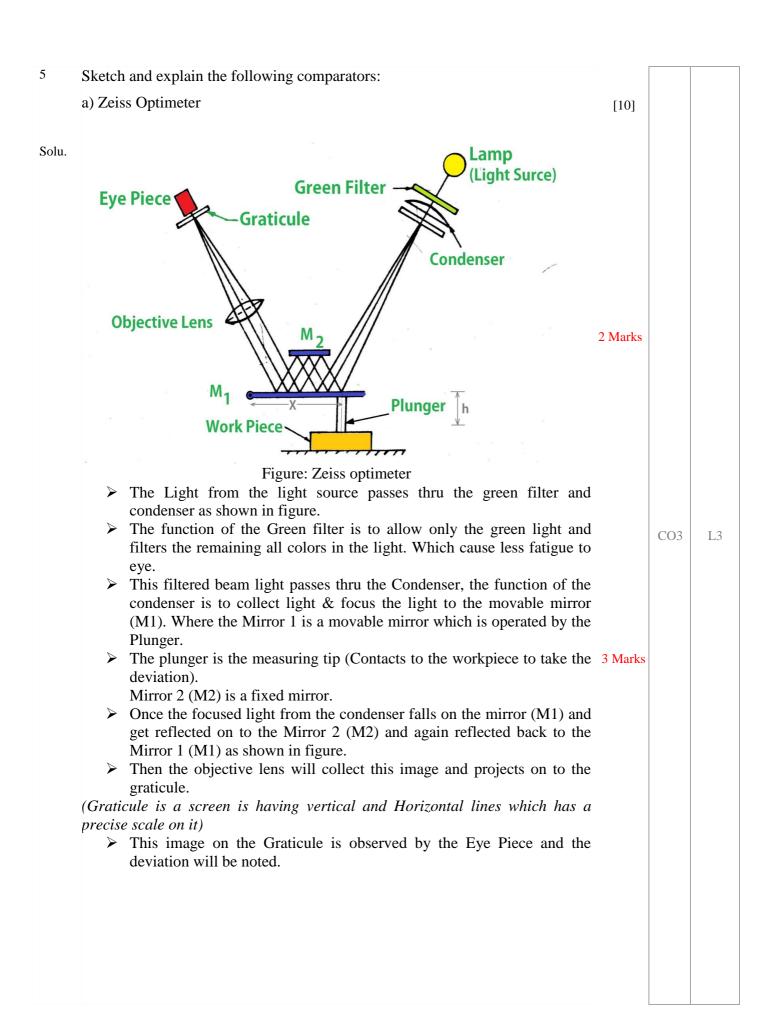
UL = 89.9305-0.0004 = 89.927 mm.

UL = 89.9305-(0.0004+0.00440)=89.921 mm
                                                                 1 mark
  limit y Nocro are: UL= 89.847-0.084= 89.838 mm.
                                                                 1 Mark
 Hole delign
                                                  __ ul g hole
__ = 090. 0525mm
                                   Direction gweat
                                         - Go gauge ug hole = gomm
                       FD=-0.069 mm .
                                   Go gauge .
                                           Direction & minsize= 89.867m
                      GTALLIL NOGO gauge.
                Fig :- Schematic of plug & King gauge delign.
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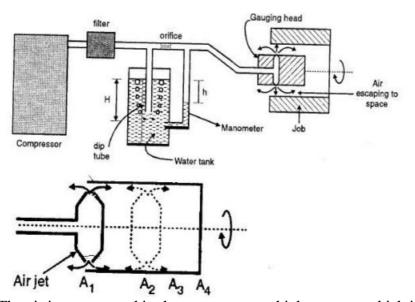


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:. AG = d/2 (0se co/2 - d/2 (:: OG = B1 = d/2)
    AG = DA - OG
          AG = d/2 (we op -1)
 From De ADF
One of lot 1/2 = AF => AF = DF cot 6/2 ( DF = P/4 Prony fig-2)

AF = P/4 cot 6/2 ( DF = P/4 Prony fig-2)
Sub. AF and AG in eq (2)
     FG = P4 cot 0/2 - d/2 (cose co/2-1)
   By considering wire on both the ends of the
  thread P = 2x FG
 .. P= 2[P/n wto2-d/2(cose co/2-1)]
      P = P/2 cot 0/2 - d (cose cop2-1) ].
                                                        4 Marks
For metric thread. 0 = 60°
      p = P/2 cot 0/2 - d (concop-1)
     P= 0.866 p-d.
                                                        2 Marks
 For Whitworth thread 0=55°
   c = Phot 55/2 - d (lose (55/2-1)
                                                        2 Marks
       C = 0.96p - 1.165d.
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b) Solex Comparators



2 Marks

- The air is compressed in the compressor at high pressure which is equal 3 Marks to Water head H.
- The excess air escapes in the form of bubbles.
- ➤ Then the metric amount of air is passed through the orifice at the constant pressure.
- ➤ Due to restricted area, at A1 position, the back pressure is generated by the head of water displaced in the manometer tube.
- ➤ To determine the roundness of the job, the job is rotated along the jet axis, if no variation in the pressure reading is obtained then we can say that the job is perfectly circular at position A1.
- ➤ Then the same procedure is repeated at various positions A2, A3, A4, position and variation in the pressure reading is found out.
- Also the diameter is measured at position A1 corresponding to the portion against two jets and diameter is also measured at various position along the length of the bore.

6 With a neat sketch explain the principle of LVDT. [10] Primary Solu. Coil 1 Motion Difference voltage V = V1 - V2 Constant Insulating AC soltan form or bobbin 2 Marks Difference voltage v. = v1 - v2 (b) (a) 2 Marks The working principle of the **LVDT** is by mutual induction. differential transformer Linear variable which transfer displacement into electrical signals. The working of LVDT circuit diagram can be divided into three cases based on the position of the iron core in the insulated former. CO₃ L2 **CASE I**: (for no displacement) When the core is at null position then the flux linking with both the secondary windings is equal so the induced emf is equal in both the windings. So for no displacement the value of output e_{out} is zero as e₁and e₂ both are equal. 2 Marks i.e., Esec1-Esec2=0 CASE 2: When an external force is applied and if the steel iron core tends to move in the left hand side direction (UP Ward) then the emf voltage induced in the 2 Marks secondary coil 1 is greater when compared to the emf induced in the secondary coil 2. SO POSITIVE. Therefore the net output will be Esec1-Esec2 **CASE 3:** When an external force is applied and if the steel iron core moves in the right hand side direction (Downward) then the emf induced in the secondary coil 2 2 Marks

is greater when compared to the emf voltage induced in the secondary coil 1.

SO NEGATIVE

Therefore the net output voltage will be Esec2-Esec1

