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Internal Assessment Test 1 – Aug. 2018

Sub:	Applied Hydraulics	Sub Code:	17CV43	Branch:	CIVIL				
Date:	06/03/19	Duration:	90 min's	Max Marks:	50	Sem/Sec:	IV A & B	OBE	
<u>Attempt five full questions</u>									
							MARKS	CO	RBT
1	a) A uniform body of size 3m long 2m wide and 1 m deep floats in water. What is the weight of the body if depth of immersion is 0.8 m? b) A solid cylinder of diameter 4m has a height of 4 m. Find the meta-centric height of the cylinder when it is floating in water with its axis vertical. Specific gravity of cylinder = 0.6.						5 5	CO1	L2
2	State Buckingham's pi theorem. The pressure difference Δp in a pipe of diameter D and length l due to turbulent flow depends on velocity V, viscosity μ , density ρ and roughness k. Using Buckingham's method, obtain an expression for Δp .						10	CO1	L3
3	a) With a sketch, explain stability of floating bodies? Explain the significance of metacentric height in designing floating bodies. Write expression for meta-centric height. b) What is meant by dimensionally homogeneous equation? Explain with an example.						6 4	CO1	L2
4	What are the types of forces acting in a moving fluid system? Discuss various non-dimensional numbers.						10	CO1	L2
5	Discuss experimental method of determining meta-centric height.						10	CO1	L3

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Solution of IAT-1 Question paper:

1) Question 1

a) Dimension of the body = $3 \times 2 \times 1$

Depth of immersion = 0.8m

Principle of floatation :

Weight of the body = weight of water displaced

= sp. Weight of water * Volume of water displaced

= $\rho g * (3 \times 2 \times 0.8) = 1000 \times 9.81 \times 3 \times 2 \times 0.8 = 47088 \text{ N}$

b) Principle of floatation: weight of the body = buoyant force

Or Weight of the body = weight of fluid displaced

Or $600 \times 9.81 \times \pi(4)^2/4 \times 4 = 1000 \times 9.81 \times \pi(4)^2/4 \times h$ (let depth of immersion is h m)

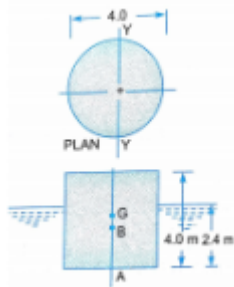
Or h = 2.4 m

Distance of centre of buoyancy (B) from base = $2.4/2 = 1.2 \text{ m}$

Distance of centre of gravity (G) from base = $4/2 = 2 \text{ m}$

Distance BG = $2 - 1.2 = 0.8 \text{ m}$

Metacentric height = GM = BM - BG = $(I_{yy}/V') - 0.8 = [\pi(D)^4/64] / [\pi(4)^2/4 \times 2.4] - 0.8 = -0.3833\text{m}$



2) Buckingham's pi theorem: If there are n variables (independent and dependent) in a physical phenomenon and these variables contain m fundamental dimensions (M,L,T) then the variables are arranged in (n-m) dimensionless terms called π -terms.

Δp is a function of D, l, V, μ, ρ, k

$$\therefore \Delta p = f(D, l, V, \mu, \rho, k) \text{ or } f_1(\Delta p, D, l, V, \mu, \rho, k) = 0 \quad \dots(i)$$

\therefore Total number of variables, $n = 7$.

Writing dimensions of each variable,

$$\begin{aligned} \text{Dimension of } \Delta p &= \text{Dimension of pressure} = ML^{-1}T^{-2} \\ D &= L, l = L, V = LT^{-1}, \mu = ML^{-1}T^{-1}, \rho = ML^{-3}, k = L \end{aligned}$$

\therefore Number of fundamental dimensions, $m = 3$

Number of π -terms $= n - m = 7 - 3 = 4$.

Now equation (i) can be grouped in 4 π -terms as

$$f_1(\pi_1, \pi_2, \pi_3, \pi_4) = 0 \quad \dots(ii)$$

Each π -term contains $m + 1$ or $3 + 1 = 4$ variables. Out of four variables, three are repeating variables. Choosing D, V, ρ as the repeating variables, we have the four π -terms as

$$\pi_1 = D^{a_1} \cdot V^{b_1} \cdot \rho^{c_1} \cdot \Delta p$$

$$\pi_2 = D^{a_2} \cdot V^{b_2} \cdot \rho^{c_2} \cdot l$$

$$\pi_3 = D^{a_3} \cdot V^{b_3} \cdot \rho^{c_3} \cdot \mu$$

$$\pi_4 = D^{a_4} \cdot V^{b_4} \cdot \rho^{c_4} \cdot k$$

First π -term $\pi_1 = D^{a_1} \cdot V^{b_1} \cdot \rho^{c_1} \cdot \Delta p$

Substituting dimensions on both sides,

$$M^0 L^0 T^0 = L^{a_1} \cdot (LT^{-1})^{b_1} \cdot (ML^{-3})^{c_1} \cdot ML^{-1}T^{-2}$$

Equating the powers of M, L, T on both sides,

Power of M , $0 = c_1 + 1 \quad \therefore c_1 = -1$

Power of L , $0 = a_1 + b_1 - 3c_1 - 1, \quad \therefore a_1 = -b_1 + 3c_1 + 1 = 2 - 3 + 1 = 0$

Power of T , $0 = -b_1 - 2, \quad \therefore b_1 = -2$

Substituting the values of a_1, b_1 and c_1 in π_1 ,

$$\pi_1 = D^0 \cdot V^{-2} \cdot \rho^{-1} \cdot \Delta p = \frac{\Delta p}{\rho V^2}$$

Second π -term $\pi_2 = D^{a_2} \cdot V^{b_2} \cdot \rho^{c_2} \cdot l$

Substituting dimensions on both sides,

$$M^0 L^0 T^0 = L^{a_2} \cdot (LT^{-1})^{b_2} \cdot (ML^{-3})^{c_2} \cdot L$$

Equating powers of M, L, T on both sides,

Power of M , $0 = c_2, \quad \therefore c_2 = 0$

Power of L , $0 = a_2 - b_2 - 3c_2 + 1, \quad \therefore a_2 = b_2 + 3c_2 - 1 = -1$

Power of T , $0 = -b_2, \quad \therefore b_2 = 0$

Substituting the values of a_2, b_2, c_2 in π_2 ,

$$\pi_2 = D^{-1} \cdot V^0 \cdot \rho^0 \cdot l = \frac{l}{D}$$

Third π -term $\pi_3 = D^{a_3} \cdot V^{b_3} \cdot \rho^{c_3} \cdot \mu$

Substituting dimensions on both sides,

$$M^0 L^0 T^0 = L^{a_3} \cdot (LT^{-1})^{b_3} \cdot (ML^{-3})^{c_3} \cdot ML^{-1}T^{-1}$$

Equating the powers of M, L, T on both sides,

Power of M , $0 = c_3 + 1, \quad \therefore c_3 = -1$

Power of L , $0 = a_3 + b_3 - 3c_3 - 1, \quad \therefore a_3 = -b_3 + 3c_3 + 1 = 1 - 3 + 1 = -1$

Power of T , $0 = -b_3 - 1, \quad \therefore b_3 = -1$

Substituting the values of a_3, b_3 and c_3 in π_3 ,

$$\pi_3 = D^{-1} \cdot V^{-1} \cdot \rho^{-1} \cdot \mu = \frac{\mu}{DV\rho}$$

Fourth π -term $\pi_4 = D^{a_4} \cdot V^{b_4} \cdot \rho^{c_4} \cdot k$

or $M^0 L^0 T^0 = L^{a_4} \cdot (LT^{-1})^{b_4} \cdot (ML^{-3})^{c_4} \cdot L \quad \text{[Dimension of } k = L]$

Equating the power of M, L, T on both sides,

Power of M , $0 = c_4, \quad \therefore c_4 = 0$

Power of L , $0 = a_4 - b_4 - 3c_4 + 1, \quad \therefore a_4 = b_4 + 3c_4 - 1 = -1$

Power of T , $0 = -b_4, \quad \therefore b_4 = 0$

Substituting the values of a_4, b_4, c_4 in π_4 ,

$$\pi_4 = D^{-1} \cdot V^0 \cdot \rho^0 \cdot k = \frac{k}{D}$$

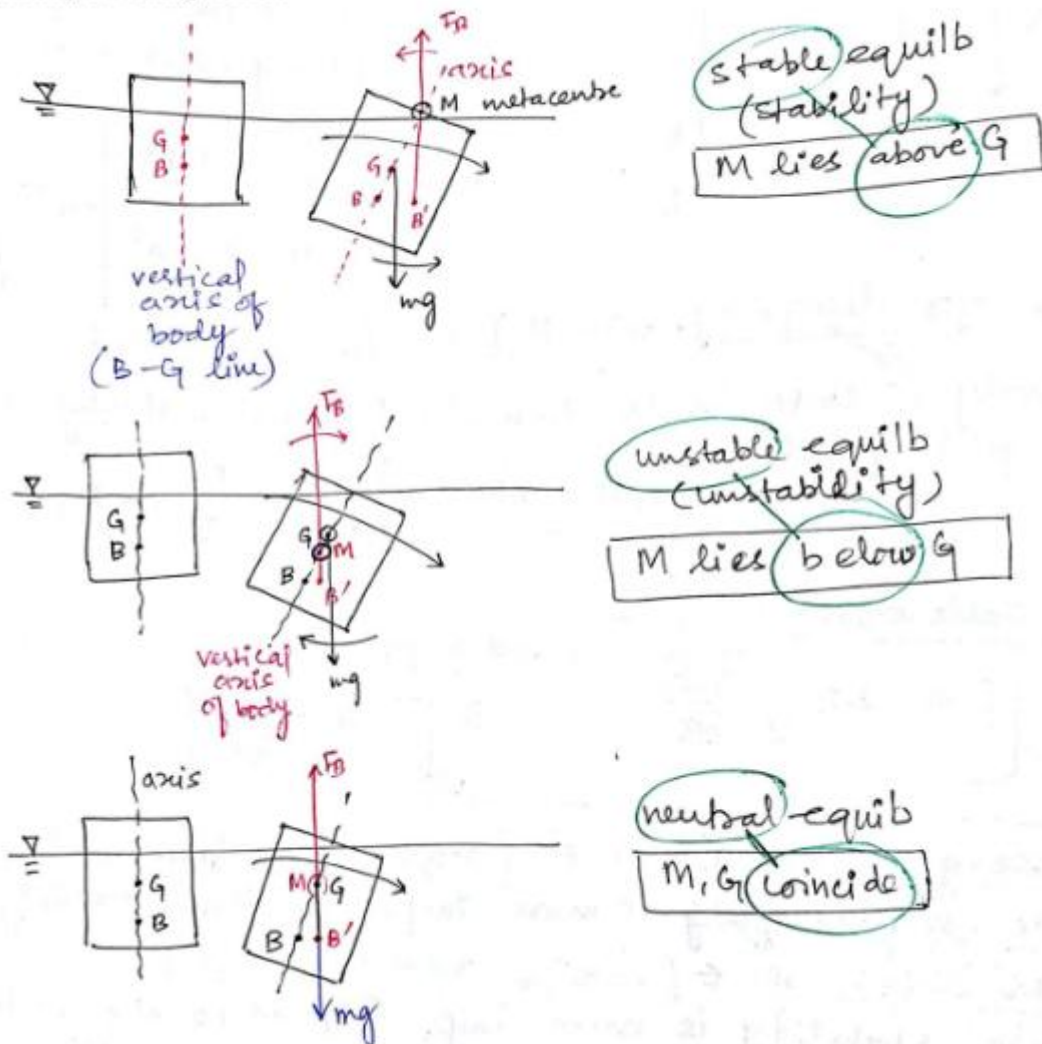
Substituting the values of π_1, π_2, π_3 and π_4 in (ii), we get

$$f_1\left(\frac{\Delta p}{\rho V^2}, \frac{l}{D}, \frac{\mu}{DV\rho}, \frac{k}{D}\right) = 0 \quad \text{or} \quad \frac{\Delta p}{\rho V^2} = \phi\left[\frac{l}{D}, \frac{\mu}{DV\rho}, \frac{k}{D}\right]. \text{ Ans.}$$

3) Question 3

a) Stability of floating bodies: Comparison of M and G

Stability of floating bodies:



Metacentric height is significant in deciding dimensions of a prototype so that it can be made stable while floating in water. We have to ensure that $GM > 0$.

Thus, Metacentric (GM) height is significant in stability analysis of a floating body like a ship.

- a. $GM > 0$: Stable equilibrium
- b. $GM < 0$: Unstable Equilibrium
- c. $GM = 0$: Neutral equilibrium

Expression of metacentric height: $GM = BM - BG = (I_{yy}/V') - BG$ Where B is centre of buoyancy, G is centre of gravity and M is metacentre. I_{yy} is moment of inertia about YY axis and V' is volume of water displaced.

b) Dimensionally homogeneous equation: dimensions of each term in an equation are the same. The powers of fundamental dimensions on both the sides will be identical for a dim. homogeneous equation.

Let us consider the equation, $V = \sqrt{2gH}$

Dimension of L.H.S. $= V = \frac{L}{T} = LT^{-1}$

Dimension of R.H.S. $= \sqrt{2gH} = \sqrt{\frac{L}{T^2} \times L} = \sqrt{\frac{L^2}{T^2}} = \frac{L}{T} = LT^{-1}$

Dimension of L.H.S. $=$ Dimension of R.H.S. $= LT^{-1}$

\therefore Equation $V = \sqrt{2gH}$ is dimensionally homogeneous. So it can be used in any system of units.

4. Forces in a moving fluid:

Inertia force (F_I) = $m \cdot a$

$$F_I = m \cdot a$$

$$= \rho L^2 \cdot \frac{v}{t}$$

$$= \rho L^2 \frac{L}{t} \cdot v$$

$$F_I = \rho L^3 v^2$$

① Viscous force (F_V) = $\tau \cdot A$

$$F_V = \mu \frac{dv}{dy} \cdot A$$

$$= \frac{\mu v}{L} \cdot L^2$$

$$F_V = \mu v L$$

② Pressure force (F_P)

$$F_P = \Delta p \cdot A$$

$$F_P = \Delta p \cdot L^2$$

③ Gravity force (F_g)

$$F_g = mg$$

$$F_g = \rho L^3 \cdot g$$

④ Surface tension force (F_s)

$$F_s = \sigma \cdot L$$

⑤ Compressibility force/
Elastic force ($F_{elastic}$)

$$F_{elastic} = k \cdot A = k L^2$$

elastic stress

Various non-dimensional numbers:

$$Re = \sqrt{\frac{F_I}{F_V}} = \frac{\rho v L}{\mu}$$

$$Fr = \sqrt{\frac{F_I}{F_g}} = \frac{v}{\sqrt{g L}}$$

$$Eu = \sqrt{\frac{F_I}{F_P}} = \frac{v}{\sqrt{\Delta p / \rho}}$$

$$W_b = \sqrt{\frac{F_I}{F_s}} = \frac{v}{\sqrt{\sigma / \rho L}}$$

$$Ma = \sqrt{\frac{F_I}{F_e}} = \frac{v}{\sqrt{k / \rho}} = \frac{v}{c}$$

Re = Reynolds's no.

Fr = Froude's no.

Eu = Euler's no.

W_b = Webber's no.

Ma = Mach no.

F_I = inertia force

F_g = gravity force

F_V = viscous force

F_P = pressure force

F_s = surface tension force

F_e = elastic force

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5. Experimental method:

Experimental method of determining metacentric height.

- * Consider a ship floating in water.
- * Let w be a movable weight placed centrally on the deck of the ship.
 $W =$ total wt. including w (of ship)
- * Initially: ship in equilibrium.
 \Rightarrow deck is horiz.
- * Now, w moved transversely through a distance ' x ' across deck, so that ship tilts through small angle θ , and comes to rest in new position of equilibrium.

$\theta \rightarrow$ measured using long plumbline attached to centre of the deck.

- * In new position, G' & B_1 (new C.G. & new C.O.G.) will be again in vertical line.

Movement of ' w ' through ' x ' causes a parallel shift of total centre of gravity from G to G' . We will equate this moment with the moment caused by movement of w .

$$wx = W(G-G')$$

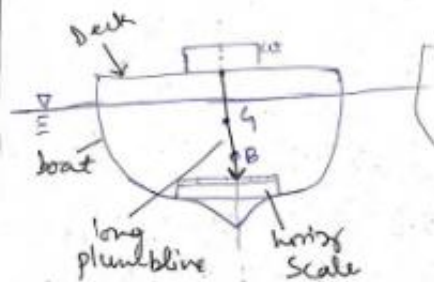
$$wx = W(GM \tan \theta)$$

$$\text{or } GM = \frac{wx}{W \tan \theta}$$

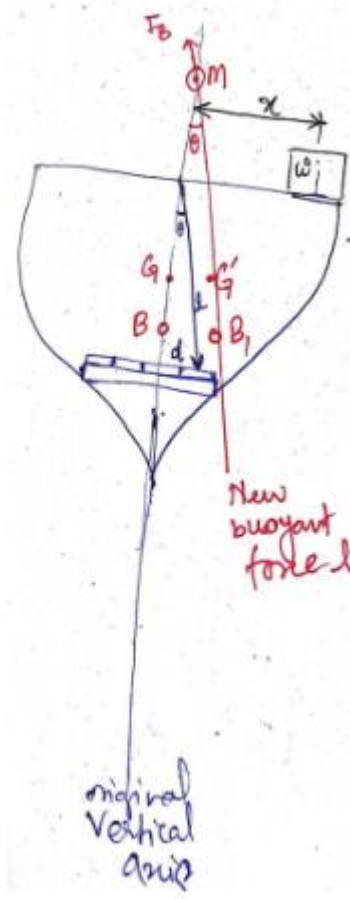
- * If $l =$ length of plumbline & d is the distance moved on by it on horizontal scale,

then, $\tan \theta = \frac{d}{l}$

$$\therefore GM = \frac{wx}{W} \times \frac{l}{d}$$



Situation before tilt



Situation after tilt