1. Sketch and Explain high Zin capacitor coupled voltage follower with necessary design steps and show that the input impedance is very high as compared to capacitor coupled voltage follower.



High input impedance capacitor-coupled voltage follower. Feedback **Figure** via  $C_2$  to the junction of  $R_1$  and  $R_2$  gives an input impedance of  $Z_{in} = (1 + M)R_1$ .

- \* The \* Ilp Impedance of the capacitos-coupled voltage follower is set by the value of assistor R. This gives a much smaller tip impedance than the direct compled voltage follower.
- Fig  $\omega$  shows a method by which the Ilp Impedance  $\star$ of the capacitos-compled voltage follower can be substantially increased.
- capacitos c couples the ciscuit of voltage to the  $\ast$ junction of resistans R, & R2.

C2 behaves as an ac short circuit. so that 'Vo'is developed across R.

\n
$$
\mathcal{H} \rightarrow \mathcal{H}
$$
\n

\n\n Applying  $KNL$  from  $Source$   $5$ ,  $R$ ,  $8$ ,  $R$ ,  $9$ ,  $R$ ,  $9$ ,  $R$ ,  $1$ ,  $$ 

$$
V_{s} - V_{t} - V_{0} = 0.
$$

The voltage across  $R_1$  is  $V_1$  is given by,

$$
\mathbf{V}_1 = \mathbf{V}_2 - \mathbf{V}_0
$$

WKT open-loop gain is given by  $M = \frac{V_0}{V_0}$ 

$$
V_6 = M V_1 \rightarrow \textcircled{3}
$$
\n
$$
\frac{Q}{V_1} = V_2 - M V_1
$$
\n
$$
M V_1 + V_1 = V_5
$$

$$
V_{1}(1+M) = V_{s}
$$
\n
$$
V_{1}(1+M) = V_{s}
$$
\n
$$
(1+N)
$$
\n
$$
\left(\frac{V_{s}}{(1+N)}\right) \to \text{G}
$$

The cussent is is given by:  $\ast$ 

$$
\frac{\mathcal{L}_1 = \frac{V_1}{R_1}}{\mathcal{L}_1} \rightarrow \text{(4)}
$$

sub eq 3 in eq 4), we get

$$
\hat{u}_1 = \frac{V_{\rm S}}{(1 + M) R_1} \longrightarrow \textcircled{5}
$$

\* Ip seristance

 $\sim$ 



 $\sim 100$ 

 $\label{eq:2.1} \frac{1}{2} \left( \frac{1}{2} \left( \frac{1}{2} \right) \right) \left( \frac{1}{2} \right)^{\frac{1}{2}} \left( \frac{1}{2} \right)^{\frac{1}{$ 

 $\label{eq:2.1} \frac{1}{\sqrt{2\pi}}\int_{\mathbb{R}^3}\left|\frac{d\mathbf{x}}{d\mathbf{x}}\right|^2\,d\mathbf{x}^2\,d\mathbf{x}^2\,d\mathbf{x}^2\,d\mathbf{x}^2\,d\mathbf{x}^2\,d\mathbf{x}^2\,d\mathbf{x}^2\,d\mathbf{x}^2\,d\mathbf{x}^2\,d\mathbf{x}^2\,d\mathbf{x}^2\,d\mathbf{x}^2\,d\mathbf{x}^2\,d\mathbf{x}^2\,d\mathbf{x}^2\,d\mathbf{x}^2\,d\mathbf$ 

sub eq ® in eq ®, we get

$$
\vec{\lambda}_{in} = \frac{\frac{\lambda}{\sqrt{s}}}{\frac{\lambda}{(1+M)R_1}}
$$
\n
$$
\vec{\lambda}_{in} = (1+M)R_1 \rightarrow \textcircled{1}
$$

since open-loop gain 'M'r very high, this nodifies the ckt has vesy high up impedance.

But if stray capacitance b/w the Ip & ground resent, then Ip Impedance reduces.

Design steps:

\n
$$
r = \frac{0.1 \text{Vg}}{T_{B(\text{max})}}
$$

R1 (max) is split into two equal seriotose R, & R2  $R_1 = R_2 = \frac{R_1 (max)}{s}$ 

$$
z \nbrace \qquad \qquad \mathcal{C}_2 = \frac{1}{2\pi f_1 \left(\frac{R_2}{10}\right)}
$$
\n
$$
4 \sum \left[\frac{C_1 = C_2}{2\pi f_1 R_1}\right]
$$
\n
$$
5 \sum C_3 = \frac{1}{2\pi f_1 R_1}
$$
\n
$$
6 \sum R_{10} = (1 + M)R_1
$$

2) Explain the working of R-2R network DAC and derive expression for output voltage.

#### **R-2R LADDER:**

- 1. Wide ranges of resistors are required in binary weighted resistor type DAC. This can be avoided by using R-2R ladder type DAC, Here only two values of resistors are required. The typical value of 'R' range from 2.5KΩ to 10KΩ.
- 2. Consider a 4-bit DAC as shown in figure below, where  $b_3$ ,  $b_2$ ,  $b_1$ ,  $b_0$  are the switches



3. When  $b_3b_2b_1b_0 = 0001$ 











3) What are the advantages of precision rectifier over ordinary rectifier? Discuss the operation of full wave rectifier circuit using bipolar op-amp.

The advantages of precision recovery and output<br>
(a) No clode vottage drop between input and output<br>
(b) The ability to rectify very small vottages (les than 0.7V)<br>
(c) Amplification, if required<br>
(d) low output impedance  $Page - 1$ 







4) Draw the circuit of instrumentation amplifier and explain its operation. Also show how voltage gain can be varied in instrumentation amplifier.

## **INSTRUMENTATION AMPLIFIER:**

Instrumentation amplifier is the front end component of every measuring instrument which receives the signal from the input electrical signal from the transducer. It uses the fact the noise is common to the both output terminals of a transducer across which the output is measured and sent to measuring instrument.



# Differential input differential Output Amplifier:

This circuit accepts a differential input voltage and produces a differential output. The voltage at the junction of  $R_1$  and  $R_2$  is equal to the input voltage. Also, the voltage at the junction of  $R_2$  and  $R_3$  equals input voltage  $V_2$ . The voltage across  $R_2$  is



 $V_{R_2} = V_1 - V_2 = V_t$ 

The circuit current through  $R_2$  as  $I_2 = \frac{V_1}{R_2}$ 

The differential output voltage is

$$
V_o = V_{R_1} + V_{R_2} + V_{R_3} = I_2(R_1 + R_2 + R_3) = \frac{V_i}{R_2}(R_1 + R_2 + R_3)
$$

The circuit differential voltage gain is

$$
A_V = \frac{V_0}{V_1} = \frac{R_1 + R_2 + R_3}{R_2}
$$
 normally  $R_1 = R_3$  hence  $A_V = \frac{2R_1 + R_2}{R_2}$ 

(Voltage gain can be altered by adjusting a single resistor  $R_2$ )

Suppose 2 inputs are connected together and a common mode noise voltage  $V_n$  is applied to the two.. The junction of  $R_1$  and  $R_2$  will be at the same voltage as the non-inverting input terminal of  $A_1$  and the junction of  $R_2$  and  $R_3$  will be at the same potential as the non-inverting input of  $A_2$ . That is both resistor junctions will be at  $V_n$ . There will be no current flow through  $R_1$  ,  $R_2$  or  $R_3$  and the output of the amplifier will be  $V_n$ . This means the common mode gain is

 $A_{V(cmi)} = 1$ 



[A common mode voltage applied to a differential input and differntial output amplifier]

So common mode signals will be passed through but not amplified by the differential input differential output amplifier.

- 1. The differential input and differential output amplifier is used in conjunction with the difference amplifier. The input impedance of differential input differential output amplifier is extremely high because of the non-inverting amplifier configuration. The input impedance of the differential amplifier is  $R_i = R_1$  at the inverting terminal and  $R_i = (R_2 + R_4)$  at the non-inverting terminal.
- 2. The voltage gain of the differential input and differential output stage can be changed by adjusting only one resistor  $R_2$ . Changing the gain of the differential amplifier requires  $R_2$  and  $R_4$ to be adjusted together to maintain equal amplification of both inputs.
- 3. The common mode gain of the differential input/output amplifier is 1, compared to common mode gain of zero for the difference amplifier.
- 4. The differential input/output amplifier operates with a floating load, while the difference amplifier uses a grounded load.

### **Differential Amplifier:**

The instrumentation amplifier is a combination of differential input/output amplifier (stage 1) and difference amplifier (stage 2). The voltage gain of the complete circuit is



 $A_V = A_{V_1}, A_{V_2}$ 

$$
Wehere \ \ A_{\nu_1} = \left(1 + \frac{2R_1}{R_2}\right) \ \ and \ \ A_{\nu_2} = \frac{R_4}{R_3}
$$

$$
A_V = \left(1 + \frac{2R_1}{R_2}\right) \left(\frac{R_4}{R_3}\right)
$$

Instrumentation amplifier is a combination of the differential input/output amplifier (Stage 1) and difference amplifier (stage 2)

$$
A_V = \left(1 + \frac{2R_1}{R_2}\right) \left(\frac{R_4}{R_3}\right)
$$
 The overall gain can be controlled by adjustment of  $R_2$ 

Like difference amplifier the instrumentation amplifier can also use Rcomp resistor (adjustable) in series with  $R_4$  and the DC output voltage level shifting can be controlled by connecting a bias voltage to the  $R_{Comp}$  resistor instead of being directly connected to ground.



5) A capacitor coupled Non-inverting amplifier is to have a gain, Av=100 and output voltage,  $V_0$ =5V with a load resistor, RL =10k and frequency, F=100Hz. Design a suitable circuit using 741 op-amp.

$$
G_1 \text{V} \cdot \text{A} \cdot \text{A} \cdot \text{B} \cdot \text{A} \cdot \text{A} \cdot \text{B} \cdot \text{A} \cdot \text{A} \cdot \text{B} \cdot \text{B} \cdot \text{A} \cdot
$$

 $\sim 10^7$ 

 $\mathcal{L}$ 

 $\cdot$ 

 $\langle \cdot \rangle$ 

$$
R_{3} = \frac{50 \text{ mV}}{50 \mu A} = 100
$$
\n
$$
R_{2} = \left(\frac{V_{0}}{T_{2}} - R_{3}\right) = \left(\frac{5V_{0}}{50 \mu A} - 101\right)
$$
\n
$$
R_{3} = R_{3}(\mu_{V} - 1)
$$
\n
$$
R_{2} = R_{3}(\mu_{V} - 1)
$$
\n
$$
R_{3} = R_{3}(\mu_{V} - 1)
$$
\n
$$
R_{2} = R_{3}(\mu_{V} - 1)
$$
\n
$$
R_{3} = 1 \text{ kJ}(\text{100 - 1})
$$
\n
$$
R_{3} = 49 \text{ kJ}
$$
\n
$$
R_{3} = 49 \text{ kJ}
$$



6) Explain the operation of Astable multivibrator using 555 timer with relevant functional diagram, waveforms and derive the expression for duty cycle.



## **ASTABLE MULTIVIBRATOR:**

- 1. When the power supply  $V_{cc}$  is connected, the external timing capacitor C charges towards  $V_{cc}$  with a time constant  $(R_A + R_B)C$ . During this time the upper comparator produces the output as LOW and the lower comparator produces the output as HIGH. Hence the output of the S-R flip-flop is HIGH. i.e.  $Q = 1$  (HIGH) and  $\overline{Q} = 0$  (LOW). At the same time transistor  $Q_1$  is OFF.
- 2. When the capacitor voltage is just greater than  $\frac{2}{3}V_{CC}$ , the upper comparator produces HIGH output and the lower comparator output is LOW. Hence the output of the S-R flip –flop is LOW. i.e.  $Q = 0$  (LOW) and  $\overline{Q} = 1$  (HIGH). So the transistor  $Q_1$  is ON and the capacitor starts discharging towards ground through  $R_B$ .
- 3. During the discharge of the capacitor C, as it reaches just less than  $\frac{1}{3}V_{CC}$ , the lower comparator produces the output HIGH and the upper comparator produces the output as LOW. Hence the output of the S-R flip-flop is HIGH. . i.e.  $Q = 1$  (HIGH) and  $\overline{Q} =$ 0 (LOW). At the same time transistor  $Q_1$  is OFF, so the capacitor starts charging.
- 4. The capacitor is thus periodically charged and discharged between  $\frac{2}{3}V_{CC}$  and  $\frac{1}{3}V_{C}$ respectively.



#### **ASYMMETRIC CIRCUIT**





### **APPLICATION OF ASTABLE MULTIVIBRATOR:**

- 1. FSK Generator
- 2. Pulse Position Modulator

7) Design a non-saturation precision half-wave rectifier to produce a 2V peak output from a sine wave input with a peak value of 0.5V and frequency of 1 MHz. Use bipolar op-amp with wave input with a peak value of  $0.5V$  and frequency of supply voltage of 15V.

$$
I_1 \ge I_{B(\text{max})}
$$
  

$$
I_1 = 500 \ \mu\text{A}
$$
 (for adequate diode current)

 $R_1 = \frac{V_i}{I_1} = \frac{0.5 \text{ V}}{500 \mu \text{A}}$ =  $1 k\Omega$  (standard value)  $R_2 = \frac{V_o}{I_1} = \frac{2 V}{500 \mu A}$  $= 4 k\Omega$  (use 3.9 k $\Omega$  standard value)  $R_3 = R_1 || R_2 = 1 k\Omega || 3.9 k\Omega$  $= 796 \Omega$  (use 820  $\Omega$  standard value) For diodes  $D_1$  and  $D_2$ ,  $V_R > [V_{CC} - (-V_{EE})] > [15 \text{ V} - (-15 \text{ V})]$  $>$  30 V  $t_{rr} \ll T$  $t_{rr(max)} = \frac{T}{10} = \frac{1}{10 \times f}$ let  $=\frac{1}{10 \times 1 \text{ MHz}} = 0.1 \text{ \mu s}$ 

Compensate the op-amp as a voltage follower.

**wo-Output Precision Rectifier**