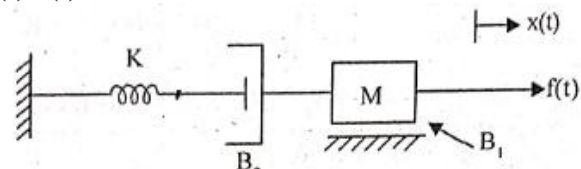
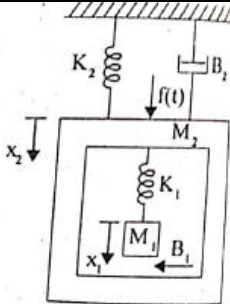
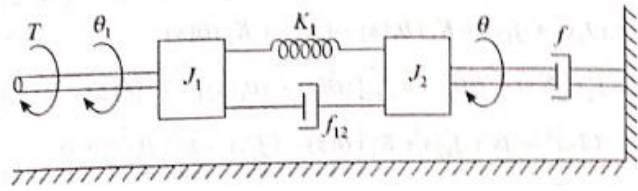
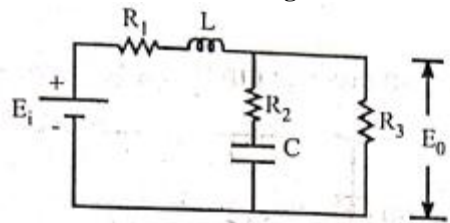


**Scheme Of Evaluation**  
**Internal Assessment Test 1 – March 2019**

<b>Sub:</b>	<b>CONTROL SYSTEMS</b>						<b>Code:</b>	15EE61	
<b>Date:</b>	05/03/2019	<b>Duration:</b>	EEE	<b>Max Marks:</b>	50	<b>Sem:</b>	VI	<b>Branch:</b>	EEE

**Note:** Answer Any Five Questions

Question #	Description	Marks Distribution		Max Marks
1	a) <b>Differentiate open loop and closed loop control system with examples.</b> <ul style="list-style-type: none"> <li>4 differences , Each difference 1 mark</li> <li>Example</li> </ul>	1 *4=4M 1 M	05 M	10 M
	b) <b>What are fundamental components of mechanical rotational systems? Explain with equations</b> <ul style="list-style-type: none"> <li>3 elements</li> <li>3 equations with diagram</li> </ul>	2M 3 M	05 M	
2	a) <b>For the mechanical system shown in Fig 2 obtain the transfer function <math>X(s)/F(s)</math></b> <div style="text-align: center; margin: 10px 0;">  <p>Fig 2</p> </div> <ul style="list-style-type: none"> <li>Free body diagram</li> <li>Differential equations</li> <li>Laplace transformation</li> <li>Final equations</li> </ul>	2M 3M 3M 2M	10M	10M
3	a) <b>Write the differential equations governing the following system shown in Fig 3 and obtain the analogous F-V circuit and F-I circuit.</b>			

		 <p style="text-align: center;"><b>Fig 3</b></p> <ul style="list-style-type: none"> <li>• Differential equations in time and frequency domain</li> <li>• Analogous equations</li> <li>• F-V circuit</li> <li>• F-I circuit</li> </ul>	<p style="text-align: center;">4M 2M 2M 2M</p>	<p style="text-align: center;">10 M</p>	<p style="text-align: center;">10 M</p>
<p style="text-align: center;">4</p>	<p>a)</p>	<p>Write the differential equations governing the following system shown in fig 4 and obtain the transfer function <math>\Theta(s)/T(s)</math></p>  <p style="text-align: center;"><b>Fig 4</b></p> <ul style="list-style-type: none"> <li>• Free body diagram</li> <li>• Differential equations</li> <li>• Laplace transformation</li> <li>• Final equations</li> </ul>	<p style="text-align: center;">2M 3M 3M 2M</p>	<p style="text-align: center;">10M</p>	<p style="text-align: center;">1  10 M</p>
<p style="text-align: center;">5</p>	<p>a)</p>	<p>Obtain the transfer function of the given network in the Fig 5</p>  <p style="text-align: center;"><b>Fig 5</b></p> <ul style="list-style-type: none"> <li>• KVL equations in time and frequency domain</li> <li>• Derivations and final result</li> </ul>	<p style="text-align: center;">6M 4 M</p>	<p style="text-align: center;">10M</p>	<p style="text-align: center;">10 M</p>
<p style="text-align: center;">6</p>	<p>a)</p>	<p>Using relevant equations obtain the mathematical model armature controlled dc motor.</p> <ul style="list-style-type: none"> <li>• Back emf equation</li> <li>• Torque equation</li> </ul>	<p style="text-align: center;">2M 2M</p>		

		<ul style="list-style-type: none"><li>• Load equation</li><li>• Transfer equation</li><li>• Block diagram</li></ul>	2M		
			2M		
			2M	10M	10 M