

*Re-Modified*

# CBCS SCHEME

USN



18EE55

## Fifth Semester B.E. Degree Examination, Jan./Feb. 2021 Electrical Machine Design

Time: 3 hrs.

Max. Marks: 100

**Note:** 1. Answer any FIVE full questions, choosing ONE full question from each module.  
2. Assume any missing data.

### Module-1

- 1 a. Describe the modern trends in electrical machine manufacturing industries. (10 Marks)  
 b. What are the fundamental requirements of high conducting materials? (07 Marks)  
 c. What are the classification high resistivity materials according to their purpose? (03 Marks)

**OR**

- 2 a. Explain the classification of magnetic material related to the value of permeability and distinguish between soft and hard magnetic materials. (06 Marks)  
 b. Describe the classification of insulating materials based on their thermal consideration. (08 Marks)  
 c. List out the desirable properties of magnetic materials. (06 Marks)

### Module-2

- 3 a. Explain the specific loadings of D.C. machine and what are advantages and disadvantages of higher values of specific loadings (Base & q). (08 Marks)  
 b. Determine the external diameter and gross core length of armature for a 7.5kW, 220V, 1000rpm shunt motor. Select the number of poles considering the frequency of flux reversal  $\geq 50\text{Hz}$ . Assume average gap density as  $0.63\text{wb}/\text{m}^2$ , ampere conductors per metre as 30000, ratio of pole arc to pole pitch is 0.7 and the friction windage and iron loss to be 600watts. Check the design for following constraints peripheral speed  $< 15\text{m/s}$ , armature mmf per pole  $< 2500$ . Considering the maximum gap density,  $B_q = B_{avg}/0.75$  and mmf required for air gap is 60% of armature mmf and gap contraction factor is 1.15 calculate air gap length. (12 Marks)

**OR**

- 4 a. Explain the factors to be consider for selecting the number of poles of D.C. machines and write any three advantages of higher values of number of poles of D.C. machine. (08 Marks)  
 b. Design a 4 pole, 10kW, 220V, 1000rpm, d.c. shunt motor, giving following details:  
 i) The diameter and length of armature  
 ii) Number of armature conductors  
 iii) Number of slots  
 iv) Size of conductor

Assume following design data:

Specific magnetic loading =  $0.45\text{T}$ , specific electric loading =  $17500 \text{ amp cond/m}^2$ , ratio of pole arc to pole pitch = 0.68, slot pitch = 2.2cm, constant losses = 8% of output, armature voltage drop = 10% of terminal voltage armature is wave wound. (12 Marks)

**Module-3**

- 5 a. Derive the following design equations for a 3-phase transformer, relating the output to the specific loading and main dimensions, i) EMF per turn ii) Output equation. (08 Marks)  
 b. Design the magnetic frame of 3-phase 250kVA, 6600/400 volts, 50Hz, core type distribution transformer with respect to the following: i) Core section ii) Diameter of circumscribing circle iii) Window area iv) Dimensions of window v) Yoke section and flux density in yoke vi) Yoke dimensions.

Assume; cruciform core section with  $A = 0.56d^2$  and  $a = 0.85d$ , the constant  $K$ , in emf per turn is 0.45, maximum flux density in core is  $1.2 \text{ wb/m}^2$  and current density is  $2.2 \text{ A/mm}^2$ , the window space factor = 0.3, the ratio of window height to width = 3, yoke section is 10% higher than core section. (12 Marks)

**OR**

- 6 a. Explain the design of tank with cooling tubes for the transformer, giving the equation to calculate number of tubes to limit temperature rise. (10 Marks)  
 b. Calculate the active and reactive component of no-load current of a 15000kVA, 33.3/6.6kV, 3-phase, star-delta, core type transformer having following data:  
 net iron area of each limb =  $0.15 \text{ m}^2$  net iron area of yoke =  $0.18 \text{ m}^2$ , Mean length of each limb = 2.3m, mean length of each yoke = 1.6m, number of turns in h.v. winding = 450. Take maximum flux density same for both limb and yoke, as =  $1.2 \text{ wb/m}^2$ . At this flux density, ampere-turns per meter of the material is 420 AT and specific iron loss is =  $1.9 \text{ w/kg}$ , density =  $7.8 \times 10^3 \text{ kg/m}^3$  Neglect mmf for joints. (10 Marks)

**Module-4**

- 7 a. Discuss the factors that affect the  
 i) Choice of average flux density in air gap  
 ii) Choice of ampere conductors per meter in the design of 3-phase Induction Motor. (08 Marks)  
 b. Determine the main dimensions, turns per phase number of slots, conductor cross section and slot area of a 250h.p, 3-phase, 50Hz, 400V 1410rpm, slip-ring induction motor. Assume  $B_{av} = 0.5 \text{ wb/m}^2$ , ac =  $30000 \text{ A/m}$ , efficiency = 0.9 and p.f = 0.9, winding factor = 0.955, current density =  $3.5 \text{ A/mm}^2$ , slot space factor is 0.4 and ratio core length to pole pitch = 1.2 take 5 slots per pole per phase motor is delta connected. (12 Marks)

**OR**

- 8 a. Explain the step-by-step procedure of wound rotor design. (08 Marks)  
 b. During the stator design of a 3-phase, 50Hz, 30kW, 400V, 6 pole, squirrel cage induction motor, the following informations were obtained gross length = 0.17m, internal diameter = 0.33m, number of slots = 45, number of conductors per slot = 12, stator winding is star connected based on above, design a cage rotor giving i) diameter of rotor ii) number of rotor slots iii) rotor bar current iv) size of rotor bar v) end-ring current and section of end ring. Assume: p.f. = 0.86, efficiency = 0.88,  $k_w = 0.955$  current density in bar =  $6 \text{ A/mm}^2$ ; current density in end ring =  $6.5 \text{ A/mm}^2$ , take length of air gap = 0.67mm. (12 Marks)

**Module-5**

- 9 a. Derive the output equation of synchronous machine, that relates output to main dimensions. (08 Marks)
- b. Determine the main dimensions, number of stator slots, conductors per slot, and conductor area of a 75000kVA, 13.8kV, 50Hz, 187.5rpm, 3-phase, star connected synchronous alternator peripheral speed should be about 60m/sec. Assume average flux density =  $0.65\text{wb}/\text{m}^2$ , ampere conductors per meter = 40,000 and current density =  $6\text{A}/\text{mm}^2$ ,  $k_w = 0.955$ , number of slots per pole per phase = 2.5. (12 Marks)

**OR**

- 10 a. Define Short Circuit Ratio (SCR) and its effect on machine performance. (10 Marks)
- b. A 3000rpm, 50Hz, 3-phase, turbo alternator has a core length of 0.94m, the average gap density =  $0.45\text{wb}/\text{m}^2$ , and ampere conductors per meter = 25000. The peripheral speed of rotor is 100m/s, and length of air gap is 20mm. Find kVA output of the machine when
- Winding factor  $k_w = 0.955$
  - Winding factor  $k_w = 0.827$
- What is the relation between winding factor and kVA output. (10 Marks)

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## Fwd: Scheme 18EE55

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March 12, 2021 12:38 PM

----- Forwarded message -----  
From: **nagaraj ms** <msndvg@gmail.com>  
Date: Tue, 9 Mar 2021, 2:37 pm  
Subject: Scheme 18EE55  
To: <boe@vtu.ac.in>

Respected sir,

I have discussed with staff who have handled Electric Machine Design for more than 20 times. I would like to bring following points:

1. All questions are set from syllabus only.
2. Distribution of marks is balanced
3. No discrepancy in the scheme and solution
4. Necessary correction is done during the BOE meeting.

*Thanking You*

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## Scheme-18EE55 &53

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March 4, 2021 9:00 AM

Sir,

No issues in the Scheme and solution of 18EE55 , 18EE53 & 17EE73  
✓

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*Thanking You*

Dr. M. S. NAGARAJA

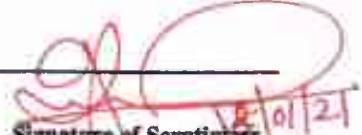
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 Signature of Scrutinizer

Subject Title : Electrical Machine design

Subject Code : 18 EEE 55

## Scheme &amp; Solutions

Question Number	Solution Model -	Marks Allocated
1 a.	<p>(i) The type of construction depends upon the power of p and the speed.</p> <p>(ii) to build m/c which are smaller in size at the same time have same <math>\eta</math> and overload capacity</p> <p>(iii) use of magnetic materials which have a high permeability, low iron loss &amp; high mech.- -anical strength</p> <p>(iv) newer insulating materials being used.</p> <p>(v) use of higher- electro-magnetic loadings for active parts and increased mechanical loading for construction materials</p> <p>(vi) in order to have low manufacturing cost, different improved &amp; refined techniques are used for individual m/c parts</p> <p>(vii) The design must be such that m/c operates satisfactorily under the desired environmental conditions - → (explain some points)</p>	7+3 = 10
b	<p>(i) high possible conductivity (ii) least possible temp. co. eff. (iii) adequate mech. strength (iv) weldability &amp; drawability (v) good weldability &amp; solderability (vi) adequate resistance to corrosion.</p>	07
(c)	<p>(i) materials used in precision measuring instruments</p> <p>(ii) resistance elements for all kinds of thermal</p> <p>(iii) for high temp elements, furnace, heating source</p>	03

Subject Title : Electrical Machine Design      Subject Code : 18EE55

Question Number	Solution	Marks Allocated
2 a)	<p>1. Ferro, 2 Para 3 Dia-magnetic materials      → define each.</p> <p>Soft magnetic materials have narrow hysteresis loop whereas hard mag. materials with broad hysteresis loop.      → explain with hysteresis loop figures</p>	03 03 = (06)
b	<p>Classes:</p> <p>Y → 90°C      B → 130°C      C → &gt;180°C</p> <p>A → 105°      F → 155°C</p> <p>E → 120°      H → 180°C</p> <p>→ explain giving example to each.</p>	08
c	<p>(i) high mag. permeability (ii) high electric resistivity (iii) narrow hysteresis loop. (iv) high saturation limit. (v) low losses at higher flux density</p>	06
<u>Module-2</u>		
3 a	<p>i) traction (ii) Drives for process industry      (iii) battery driven vehicles (iv) machine tools (v) applications (vi) automatic control</p>	04
3 b	<p>i) Specific Magnetic loading is defined as ratio of total flux around the air gap to the air gap area, <math>B_{avg} = \frac{P\phi}{\pi D L}</math> Tesla.</p> <p>ii) Specific electric loading is defined as the total number of ampere conductors on the armature per unit circumference of armature <math>q_f = \frac{I_a Z_a}{\pi D}</math> <span style="color:red;">Advantages &amp; Disadvantages of pole pitch</span></p>	04
3 c	<p>Output co-efficient <math>\zeta_0 = 0.164 B_{av} q_f \times 10^{-3}</math></p>	08

Question Number	Solution	Marks Allocated
	$\text{of } C_0 = \pi^2 P_{\text{av}} \times g \times 10^{-3} = 186.5, n_s = 16.67 \text{ rpm}$ $P_a = 7.5 + 0.6 = 8.1 \text{ kW}$ → 03 $\therefore D^2 L = \frac{P_a}{C_0 n_s} = 2.6 \times 10^{-3} \text{ m}^3$ → 01 No. of poles, $P = 6$ [ $\because f = \frac{6 \times n_s}{2} = 50 \text{ Hz}$ ] $\gamma_{C_p} = 0.7 \therefore B = 0.7 \times \frac{\pi D}{6}$ → 02 Main dimensions $D = 0.19 \text{ m}$ $L = 0.07 \text{ m}$ } → 02 $c_p = 0.1 \text{ m}$ . <u>Check if peripheral speed = <math>\pi D n_s = 9.95 \text{ m/s}</math> &lt; 15 m/s</u> → 02	
(ii)	Armature mmf = $\frac{q \times c}{2} = 1500 < 2500$ within limit.	
	Length of air gap $\therefore B_g = \frac{0.63}{0.75} = 0.84 \text{ T}$	
	mmf required for air gap = $0.796 B_g k_f \times 10^6 \times l_g$ $A T_g = 768936 \times l_g$ Also air gap mmf / pole, atg = $0.6 \times 1500 = 900.00$ → 02	
	i. length of air gap $l_g = \frac{900}{768936} = 1.2 \times 10^{-3} \text{ m} = 1.2 \text{ mm}$ → 02 $= 12 \text{ M}$	
4a factors & Explanation	Advantages of specific magnetic & electric loading → <del>for less &amp; explanation</del> <del>→ reduction in volume, weight, cost</del> <del>Advantages of specific, less weight, low cost.</del>	6 2
Advantages $6+2=8$	Disadvantages of magnetic loading - <del>increased iron loss, higher field currents, increased no-load current, temp. rise, noise</del>	08

Subject Title : Electrical Machine design      Subject Code : 18EE55

Question Number	Solution	Marks Allocated
	<p><del>D1 = advantages of electric loading :- increased arm. cur. loss, increased reluctance drop, inferior commutation, reduced over load capacity.</del></p>	<del>4+4</del>
b.	<p><math>C_0 = 77.72</math>, , <math>n_s = 16.67 \text{ rpm}</math>. <math>\rightarrow 01</math></p> <p><math>P_a = 1.08 \times 10 = 10.8 \text{ kW} \rightarrow 01</math></p> <p>i. <math>D^2 L = \frac{10.8}{77.72 \times 16.67} = 8.33 \times 10^{-3} \text{ m}^3</math></p> <p>and <math>L = 0.68 \times \frac{\pi D}{P} = 0.534D</math></p> <p>ii. <math>D = 0.25 \text{ M}</math> and <math>L = 0.13 \text{ M}</math>.</p> <p><math>P\phi = B_{avg} \times \pi D L = 0.45 \times \pi \times 0.25 \times 0.13 \rightarrow 03</math></p> $= 0.046 \text{ Wb}$ <p>Emf <math>E = 220 - 22 \text{ (motor)} \rightarrow 02</math></p> $= 198 \text{ Volts.}$ <p>iii. No. of conductors <math>Z = \frac{E \times 60 \times f}{\phi \times P \times N}</math></p> $= 516 \rightarrow 01$ <p>Slot pitch <math>c_s = \frac{\pi D}{m \times q \text{ slots}}</math></p> <p>iv. No. of slots <math>= \frac{2 \pi \times 25}{2 \times 2} = 36 \rightarrow 02</math></p> <p>Cond/slot <math>= \frac{516}{36} \approx 14</math>.</p> <p>v. Revised no. of conductors <math>Z = 14 \times 36</math></p> $= 504$ <p>Mean length of armature current <math>\rightarrow 01</math></p> <p><math>I_a = \frac{10 \times 10^3}{220} = 45.45 \text{ Amp} \rightarrow 01</math></p> <p>and <math>I_a/A = 11.36</math>. ii. <math>a_c = \frac{11.36}{4.5} = 2.52 \text{ mm}^2</math></p>	12

Subject Title : Electrical Machine Design      Subject Code : 18 EEE 55

Question Number	Solution	Marks Allocated
5 a	<p>(i) <math>E_t = K \sqrt{KVA / \text{phase}} ; K = \sqrt{4.44 f Y} \times 10^3</math></p> <p>(ii) <math>\theta = 3.33 f B_m S_{kw} A_w A_i \times 10^{-3} \text{ --- kVA}</math>  <math>\rightarrow (4+4)M</math>.</p> <p>b. <math>E_t = K \sqrt{KVA / 3} = 0.45 \sqrt{250 / 3} = 4.1 \text{ Volts}</math></p> $A_i = \frac{E_t}{4.44 f B_m} = 0.0154 \text{ m}^2$ $d = \sqrt{A_i / 0.56} = 0.166 \text{ m}, a = 0.85d = 0.14 \text{ m}$ $A_w = \frac{250}{3.33 \times 1.2 \times 2.2 \times 10^6 \times 0.3 \times 0.0154 \times 10^3} = 0.123 \text{ m}^2$ $H_w / w_w = 3 \therefore H_w = 0.6 \text{ m}; w_w = 0.2 \text{ m}$ $D = w_w + d = 0.366 \text{ m}; A_y = 1.1 A_i = 0.0169 \text{ m}^2$ $a_y = a = 0.14 \text{ m} \therefore h_y = 0.12 \text{ m}.$ $\text{flux in core } \phi_c = B_m \times A_i = 0.0185 \text{ wb}$ $\therefore \text{flux density in yoke } = B_y = \frac{\phi}{A_y} = 1.09 \text{ wb/m}^2$	08
6 a	<p>width of tank <math>t_w = 2D + D_e + 2b \quad (3-q)</math>  <math>= D + D_e + 2b \quad (1-q)</math></p> <p>Length of tank <math>L = D_e + 2L</math>; height of tank  <math>H = H_t + h_s; \theta_B = \frac{P_i + P_c}{S_t(12.6 + 8.8x)}</math></p> <p>No. of tubes <math>= \frac{1}{8.8 \pi d L_t} \left[ \frac{P_i + P_c}{\theta} - 12.5 S_t \right]</math>  <math>\rightarrow \text{with explanation.}</math></p>	12 M
b	<p>Total flux path in 3 limbs <math>= 3 \times 2.3 = 6.9 \text{ m}</math></p> <p>" " " " 2 yoke <math>= 2 \times 1.6 = 3.2 \text{ m}</math></p> <p><math>\therefore \text{Total length} = 10.1 \text{ m.}; \therefore \text{total mmf for iron}</math></p> <p>path <math>A E_t = 10.1 \times 420 = 4242 \text{ A}; AT/\text{phase}</math>  <math>= 4242 / 3 = 1414 \therefore \text{relative component, } I_\mu</math></p> <p><math>I_\mu = 1414 / (450 \times \sqrt{2}) = 2.22 \text{ Amp}</math></p>	10

**Subject Title : Electrical Machine Design Subject Code : 18EE55**

Question Number	Solution	Marks Allocated
	<p>loss component <math>I_w</math> :- Volume of core = <math>6.9 \times 0.15</math>  <math>= 1.035 \text{ m}^3</math>; Volume of yoke = <math>0.576 \text{ m}^3</math>  i Total volume = <math>1.611 \text{ m}^3</math>; ii Weight of trans <math>= \text{Volume} \times \text{density} = 1.611 \times 7.8 \times 10^3 = 12565.8 \text{ kg}</math>  iii Total iron loss = <math>P_i = 12565.8 \times 1.9 = 23875.02 \text{ watt}</math>  Iron loss / phase = <math>P_i/3 = 7958.4 \text{ watt}</math>.  iv loss component of current <math>I = \frac{7958.4}{(23.3 \times 10^3)/\beta} = 0.414 \text{ Amp}</math>  v No-load current <math>I_0 = \sqrt{I_\mu^2 + I_\omega^2} = \sqrt{(2.22)^2 + (0.614)^2} = 2.258 \text{ Amp}</math></p>	
7 (a)	<p><u>Module - 4</u></p> <p>choice of <math>B_{av}</math> :- (i) P.f (ii) Iron loss (iii) over load capacity  <u>choice of ac</u> :- (i) Cu-loss &amp; Tempr. rise (ii) Voltages = 0.8  (iv) Overload capacity :- (explain each)</p> <p>(b)</p> <p>Nearest synchronous speed to 1410 is 1500 rpm.</p> <p>i <math>N_s = 1500/60 = 25 \text{ ops. } P = 2 \times 50/25 = 4</math></p> <p>ii <math>c_o = 11 k_w B_{av} \text{ ac} \times 10^{-3} = 157.57 \therefore \theta = \frac{250 \times 0.746}{0.9 \times 0.9}</math></p> <p>iii <math>D^2 L = \frac{\theta}{c_o N_s} = 0.0584 \text{ m}^3</math></p> <p>But <math>L/c_p = 1.2 ; L = 0.942 D, \therefore D = 0.395 \text{ m}</math></p> <p><math>L = 0.373 \text{ m} ; \phi = 0.5 \times \frac{\pi D L}{P} = 0.0578 \text{ wb}</math></p> <p>iv <u>Stator turns/phase</u>, <math>T_{pn} = \frac{400}{4.44 \times 50 \times \phi \times k_w} = 32.6 \approx 32</math></p> <p>v Total conductor <math>Z_s = 6 \times 32 = 192</math></p> <p>No. of slots <math>S_s = 5 \times 3 \times 4 = 60</math>; cond/slot = 3.2</p> <p>Taking 3 cond/slot; Revised no. of conductors <math>Z = 3 \times 60 = 180</math>; <math>T_{pn} = 30</math>.</p> <p><math>I_{pn} = 192 \text{ Amp. } \therefore \text{Conductor section} = 55 \text{ mm}^2</math></p> <p>Slot dimension = <math>\frac{55 \times 3}{0.4} = 412.5 \text{ mm}^2</math></p>	4+4 = 0.8 12

Question Number	Solution	Marks Allocated
8 a	Explanations + equations	08
b)	<p>Length of air gap = 0.67 mm, rotor dia <math>D_r = D - 2l_g</math>  <math>D_r = \underline{0.328 \text{ m}}</math>; No. of rotor slots = <u>42</u></p> <p><u>Rotor bar-current</u> / stator current <math>I_s = \frac{\Theta}{3 \times 400}</math></p> $I_s = \frac{30 \times 10^3}{0.88 \times 0.86 \times 3 \times 400} = \underline{33 \text{ A}}$ $\therefore$ <del>rotor bar</del> current $I_b' = 0.85 \times 33 = 28.1 \text{ Amp}$ $\therefore I_b = 28.1 \times \frac{0.955}{1} \times \frac{45}{42} \times \frac{12}{1} = \underline{345 \text{ Amp}}$ bar section = $\frac{345}{6} = \underline{57.5 \text{ mm}^2}$ End ring current $I_e = 345 \times \frac{48}{6} = \underline{768.7 \text{ Amp}}$ End ring section = $\frac{768.7}{6.5} = \underline{118.26 \text{ mm}^2}$	12
9 a	$D^2 L = \frac{\Theta}{C_0 n_s}$ ; <u>Module - 5</u> $C_0 = 11 B_{av} K_w \cdot ac \times 10^3$	08
b)	<p>Synchronous speed <math>n_s = \frac{187.5}{60} = 3.125 \text{ rps.}</math>  <math>C_0 = 11 \times 0.65 \times 40000 \times 0.955 \times 10^{-3} = 273.</math>  <math>\therefore D^2 L = \frac{75000}{273 \times 3.125} = 87.9 \text{ m}^3</math>; <math>P = \frac{2 \times 50}{3.125} = 32</math></p> <p>Diameter with peripheral speed of 40 m/s  <math>D = \frac{60}{\pi n_s} = 6.07 \approx \underline{6 \text{ m}}</math> <math>\therefore L = \underline{4.4 \text{ m}}</math></p> $E_{pn} = 13.8 / \sqrt{3} = 7.967 \text{ kV} = 7967.4 \text{ volts}$ $\Phi = 0.65 \times \pi \times 6 \times \frac{2.44}{32} = 0.93 \text{ wb}$ $\therefore T_{pn} = 40 \times 60 \approx 40 \text{ turns} \therefore Z = 240$ No. of slots = $2.5 \times 3 \times 32 = 240 \text{ slots}$ Conductors / slot = 1.	12

Subject Title : Technical Machine design Subject Code : 18EE55

Question Number	Solution	Marks Allocated
	$I_{ph} = \frac{75000 \times 1000}{3 \times 7967.4} = 3137.8 \text{ Amp}$ Section of conductor = $\frac{3137.8}{6} = 522.96 \text{ mm}^2$	
10 a	$S.C.R = \frac{1}{X_d}$ : define $\Rightarrow (04) M$ (with graph) <u>It effects</u> : (i) Vg-regulation (ii) stability (iii) parallel operation (iv) short-circuit current (v) Self excitation : Explain each $\Rightarrow (06) M$	10
(b)	synchronous speed $n_s = \frac{3000}{60} = 50 \text{ rps.} (01M)$ peripheral speed = $\pi D_p n_s = 100 \text{ m/s.} \therefore D_p = 0.637 \text{ m} \Rightarrow (02M)$ Then stator diameter $D = D_p + 2l_g = 0.677 \text{ m}$ . Then $Q = D^2 \times n_s \times C_0 \Rightarrow (01M)$ if $C_0 = 11 k_w B_o \alpha \times 10^{-5}$ : (i) when $k_w = 0.95$ $C_0 = 118.18$ (ii) $Q = 0.677^2 \times 0.94 \times 50 \times 118.18 = 2545 \text{ kVA} \Rightarrow (0.2M)$ when $k_w = 0.827$ $C_0 = 102.34 \therefore Q = 2206.5 \text{ kVA} \Rightarrow (02M)$ As specific loading and speed remaining same, the output of the machine is directly proportional to the winding factor. $\Rightarrow (02M)$	10M

Off

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