



## Fifth Semester B.E. Degree Examination, Jan./Feb. 2021 Signals and Systems

Max. Marks: 100

**Note: Answer any FIVE full questions, choosing ONE full question from each module.**

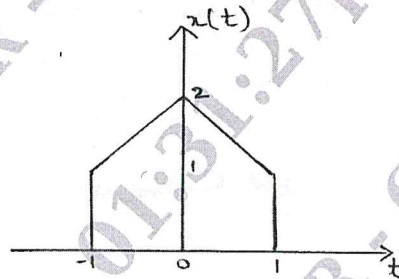
### Module-1

- 1 a. Determine whether the following signals are energy or power signals or neither. Justify your answer.
  - i)  $x(t) = e^{j(t+\pi/2)}$       ii)  $x(t) = 8 \cos(4t) \cdot \cos(6t)$ . (10 Marks)
- b. Sketch the following signals :
  - i)  $x_1(t) = -u(t+3) + 2u(t+1) - 2u(t-1) + u(t-3)$ .
  - ii)  $x_2(t) = r(t) - r(t-1) - r(t-3) + r(t-4)$ . (10 Marks)

### OR

- 2 a. Determine whether the system  $y(t) = e^{x(t)}$  is
  - i) Causal      ii) Time Invariant      iii) Linear
  - iv) Stability      v) Memoryless. Justify your answer. (10 Marks)
- b. For the signal shown in Fig. Q2(b), sketch and label each of the following signals :
  - i)  $y_1(t) = x(t-2)$       ii)  $y_2(t) = x(2t-2)$       iii)  $y_3(t) = x(\frac{1}{2}t+2)$
  - iv)  $y_4(t) = x(-2t-1)$       v)  $y_5(t) = 3x(2t)$ . (10 Marks)

Fig. Q2(b)



### Module-2

- 3 a. Evaluate the convolution integral for a system with input  $x(t)$  and impulse response  $h(t)$ .  
Given  $x(t) = u(t-1) - u(t-3)$  ;  $h(t) = u(t) - u(t-2)$ . Also sketch  $y(t)$ . (10 Marks)
- b. Represent the direct form I and form II realization for the system described by
  - i)  $y[n] + \frac{1}{4}y[n-1] + \frac{1}{8}y[n-2] = x[n] + x[n-1]$ .
  - ii)  $\frac{d^2}{dt^2}y(t) + 5\frac{d}{dt}y(t) + 4y(t) = x(t) + 3\frac{d}{dt}x(t)$ . (10 Marks)

### OR

- 4 a. Determine the complete response of the system describe by the differential equation.  
 $\frac{d^2}{dt^2}y(t) + 5\frac{d}{dt}y(t) + 4y(t) = \frac{d}{dt}x(t)$  with  $y(0) = 0$  ;  $\frac{d}{dt}y(t) \big|_{t=0} = 1$  ;  
For input  $x(t) = e^{-2t}u(t)$ . (10 Marks)
- b. Investigate the causality, stability and memory of the LTI system described by the impulse response
  - i)  $h(t) = e^{-2|t|}$       ii)  $h[n] = 2^n u[n-1]$ . (10 Marks)

**Module-3**

- 5 a. Prove the following properties related to continuous – time Fourier transform :  
 i) Convolution      ii) Parseval's theorem. (10 Marks)  
 b. Determine the Fourier Transform of the following signals :  
 i)  $x(t) = e^{at} u(-t)$       ii)  $x(t) = e^{-a|t|}$       iii)  $x(t) = e^{-a|t|} \text{sgn}(t)$ . (10 Marks)

**OR**

- 6 a. Determine the Inverse Fourier Transform of the following :  
 i)  $X(j\omega) = \frac{2j\omega + 1}{(j\omega + 2)^2}$       ii)  $X(j\omega) = \frac{1}{(a + j\omega)^2}$ . (10 Marks)  
 b. Determine the Fourier transform of the signal  $x(t) = e^{-3|t|} \sin(2t)$  using appropriate properties. (10 Marks)

**Module-4**

- 7 a. Determine the Inverse DTFT of the following :  
 i)  $X(e^{j\Omega}) = 1 + 2 \cos \Omega + 3 \cos 2\Omega$       ii)  $Y(e^{j\Omega}) = j(3 + 4 \cos \Omega + 2 \cos 2\Omega) \sin \Omega$ . (10 Marks)  
 b. Using appropriate properties, determine the DTFT of  
 i)  $x[n] = \left(\frac{1}{2}\right)^n u[n - 2]$       ii)  $x[n] = \sin\left(\frac{\pi}{4}n\right) \left(\frac{1}{4}\right)^n u[n - 1]$ . (10 Marks)

**OR**

- 8 a. Prove the following properties related to DTFT :  
 i) Frequency differentiation      ii) Modulation. (10 Marks)  
 b. Compute the DTFT of the following signals :  
 i)  $x[n] = 2^n u[-n]$       ii)  $x[n] = a^{|n|}$  ;  $|a| < 1$ . (10 Marks)

**Module-5**

- 9 a. Determine the Inverse Z – transform if  

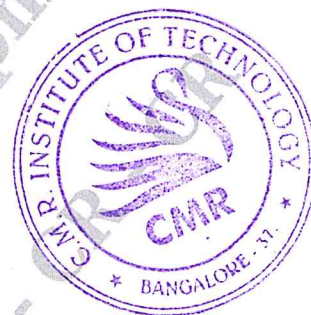
$$X(z) = \frac{(z^3 - 4z^2 + 5z)}{(z-1)(z-2)(z-3)}$$
 with ROCs i)  $2 < |z| < 3$       ii)  $|z| > 3$       iii)  $|z| < 1$ . (10 Marks)  
 b. Use Unilateral Z – transform to determine the forced response, natural response and complete response of system described by  $y[n] - \frac{1}{2}y[n - 1] = 2x[n]$   
 with input  $x[n] = 2\left(\frac{-1}{2}\right)^n u[n]$ . The initial conditions are  $y[-1] = 3$ . (10 Marks)

**OR**

- 10 a. Explain the properties of ROC. (08 Marks)  
 b. A LTI discrete – time system is given by system function  

$$H(z) = \frac{3 - 4z^{-1}}{1 - 3.5z^{-1} + 1.5z^{-2}}$$
 Specify ROC of  $H(z)$ .  
 Determine  $h[n]$  for the following conditions : i) Stable      ii) Causal. (12 Marks)

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1a.

i) a) 1)  $x(t) = e^{j(t+\pi/2)}$   
 $x(t)$  is of infinite duration periodic signal  
which is combination of sine & cosine signals.  
So this can be a power signal.

$$P = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt.$$

$$P = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |e^{j(t+\pi/2)}|^2 dt.$$

$$P = \frac{1 \text{ W}}{T}$$

$$E = \lim_{T \rightarrow \infty} \int_{-T}^T |x(t)|^2 dt.$$

$$E = \lim_{T \rightarrow \infty} \int_{-T}^T |e^{j(t+\pi/2)}|^2 dt.$$

$$E = \infty$$

$\therefore$  Energy is infinite & average power is finite.  
Hence  $x(t)$  is a power signal.

ii)  $x(t) = 8 \cos(4t) \cdot \cos(6t)$

$$\therefore x(t) = 4 \cos(10t) + 4 \cos(2t)$$

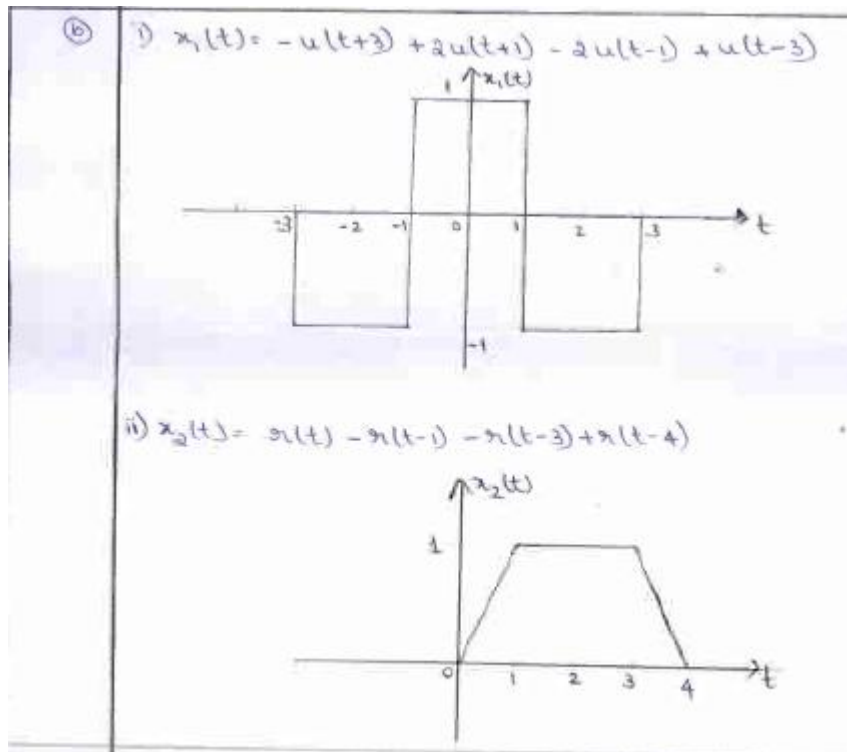
Since  $x(t)$  is periodic in nature; it can  
be a power signal.

$$P = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt = \underline{\underline{16 \text{ W}}}$$

-\*

$x(t)$  is power signal.

1b.



2 a)  $y(t) = z(t)$

(i) Since output of system at any instant depends only on present input; system is causal.

(ii) if input is delayed by  $t_0$  then  $y(t) = z(t-t_0)$   
 if output is delayed by  $t_0$  then  $y(t-t_0) = z(t-t_0)$   
 Since  $y(t) = y(t-t_0) \rightarrow$  time-invariant

(iii) if  $x_3(t) = a x_1(t) + b x_2(t)$   
 then  $y_3(t) = [a z_1(t) + b z_2(t)]$  — (1)

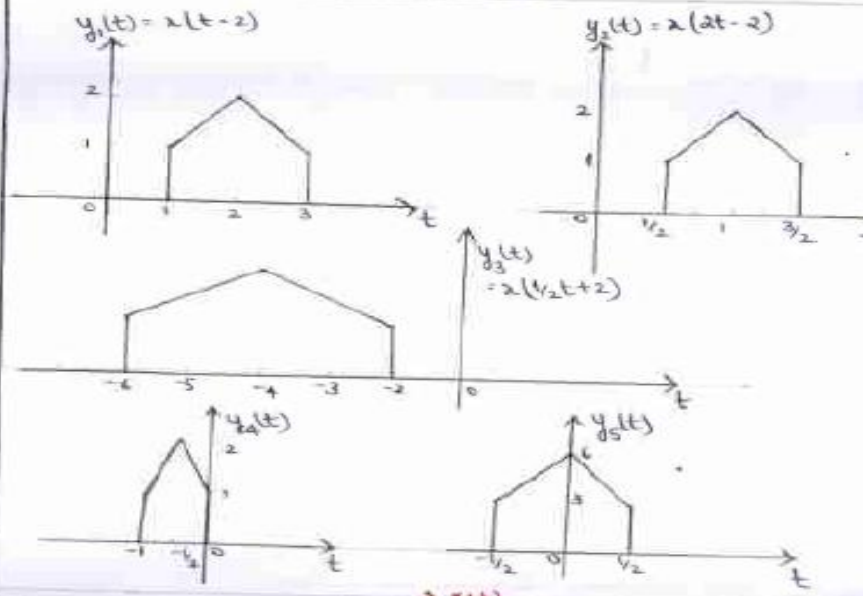
if  $y_3'(t) = a y_1(t) + b y_2(t)$   
 $y_3'(t) = a z_1'(t) + b z_2'(t)$  — (2)

Since  $y_3(t) \neq y_3'(t) \rightarrow$  non-linear

iv) if input  $x(t)$  is bounded and is a finite value; then system is stable

v) Since  $y(t)$  depends only on present value of input; system is memoryless

b)



3 a)

$$x(t) = u(t-1) - u(t-3)$$

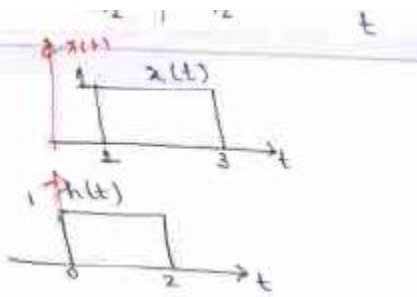
$$h(t) = u(t) - u(t-2)$$

$$y(t) = x(t) * h(t)$$

$$y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

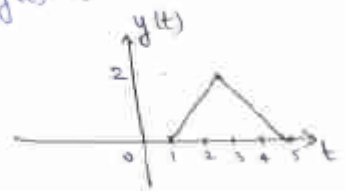
i)  $t < 0$ ;  $y(t) = 0$

ii)  $0 < t < 2$ ;  $y(t) = t$

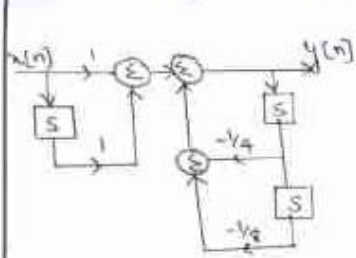


iii)  $2 < t < 5$ ;  $y(t) = -t+5$

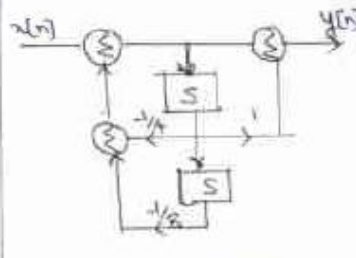
iv)  $t > 5$ ;  $y(t) = 0$



b) i)  $y[n] + \frac{1}{4}y[n-1] + \frac{1}{8}y[n-2] = x[n] + x[n-1]$



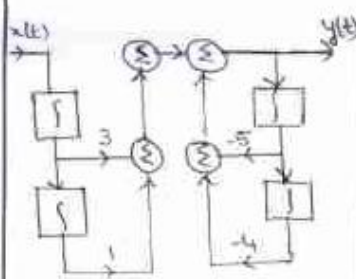
Direct form-I



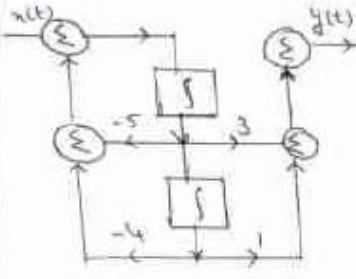
Direct form-II

ii)  $\frac{d^2}{dt^2}y(t) + 5\frac{d}{dt}y(t) + 4y(t) = x(t) + 3\frac{d}{dt}x(t)$

$y(t) + 5\int y(t) dt + 4\int\int y(t) dt = \int x(t) dt + 3\int x(t) dt$



Direct form-I



Direct form-II

4 a) Homogenous soln:

$$s^2 y(t) + 5s y(t) + 4y(t) = 0$$

$$\therefore \underline{y^h(t) = c_1 e^{-t} + c_2 e^{-4t}}$$

Particular soln:

$$y^p(t) = k \cdot e^{-2t} u(t)$$

$$\frac{d}{dt} y^p(t) = -2k e^{-2t} u(t)$$

$$\frac{d^2}{dt^2} y^p(t) = 4k \cdot e^{-2t} u(t)$$

To find value of  $k$ :

$$4k e^{-2t} u(t) + 5[-2k e^{-2t} u(t)] + 4[k e^{-2t} u(t)] = -2 e^{-2t} u(t)$$

$$\therefore k = 1$$

$$\underline{y^p(t) = 1 \cdot e^{-2t} u(t)}$$

Total response:  $y(t) = y^h(t) + y^p(t)$

$$y(t) = c_1 e^{-t} + c_2 e^{-4t} + e^{-2t} u(t)$$

$$\therefore y(0) = c_1 + c_2 + 1 = 0 \Rightarrow c_1 + c_2 = -1$$

$$\frac{d}{dt} y(0) = -c_1 - 4c_2 - 2 = 1 \Rightarrow c_1 + 4c_2 = -3$$

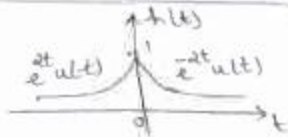
$$c_1 = -1/3, \quad c_2 = -2/3$$

$$\underline{y(t) = (-1/3 e^{-t} - 2/3 e^{-4t} + e^{-2t}) u(t)}; \quad t \geq 0$$

b) i)  $f(t) = e^{-2|t|}$

$f(t)$  is non-causal:

since  $f(t) \neq 0$  for  $t < 0$



not memoryless since  $f(t) \neq c \cdot \delta(t)$

$$S = \int_{-\infty}^{\infty} |f(t)| dt \Rightarrow \underline{S = 1} \text{ finite}$$

$\therefore f(t)$  is stable

$$(vi) h[n] = 2^n u[n-1]$$

$h[n]$  is causal since  $h[n] = 0$  for  $n < 0$

$h[n]$  is not memoryless since  $h[n] \neq c \delta[n]$

$$S = \sum_{k=-\infty}^{\infty} |h[k]|$$

$$= \sum_{k=1}^{\infty} 2^k \cdot 1 = \infty \quad \text{unstable.}$$

5 a)

i) convolution

$$x(t) \xleftrightarrow{FT} X(\omega)$$

$$y(t) \xleftrightarrow{FT} Y(\omega)$$

$$\text{then } z(t) = x(t) * y(t) \xleftrightarrow{FT} Z(\omega) = X(\omega) \cdot Y(\omega)$$

convolution operation is transformed to multiplication in frequency domain.

Proof -

(ii) Parseval's Theorem

$$\text{if } x(t) \xleftrightarrow{FT} X(\omega)$$

$$\text{then } E = \int_{-\infty}^{\infty} |x(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |X(\omega)|^2 d\omega = \int_{-\infty}^{\infty} |x(f)|^2 df$$

Energy of the signal can be obtained by interchanging its energy spectrum

Proof -

b) i)  $x(t) = e^{at} u(-t)$

$$X(\omega) = \int_{-\infty}^{\infty} x(t) \cdot e^{-j\omega t} dt$$

$$X(\omega) = \int_{-\infty}^{\infty} e^{at} u(-t) \cdot e^{-j\omega t} dt$$

$$X(\omega) = \int_0^{\infty} e^{at} e^{-j\omega t} dt$$

$$X(\omega) = \frac{1}{a - j\omega}$$



$$b) x(t) = \frac{-a|t|}{e}$$

$$X(\omega) = \int_{-\infty}^{\infty} x(t) \cdot e^{-j\omega t} dt$$

$$X(\omega) = \int_{-\infty}^0 \frac{at}{e} \cdot e^{-j\omega t} dt + \int_0^{\infty} \frac{-at}{e} \cdot e^{-j\omega t} dt$$

$$X(\omega) = \frac{2a}{a^2 + \omega^2}$$

$$(iii) x(t) = \frac{-a|t|}{e} \operatorname{sgn}(t) ; \operatorname{sgn}(t) = \begin{cases} 1 & ; t > 0 \\ -1 & ; t < 0 \end{cases}$$

$$X(\omega) = \int_{-\infty}^{\infty} x(t) \cdot e^{-j\omega t} dt$$

$$X(\omega) = \int_{-\infty}^0 -\frac{at}{e} \cdot e^{-j\omega t} dt + \int_0^{\infty} \frac{-at}{e} \cdot e^{-j\omega t} dt$$

$$X(\omega) = \frac{-2j\omega}{a^2 + \omega^2}$$

$$6 a) i) X(j\omega) = \frac{2j\omega + 1}{(j\omega + 2)^2}$$

$$X(j\omega) = \frac{A}{j\omega + 2} + \frac{B}{(j\omega + 2)^2} \quad \text{using partial fraction}$$

$$X(j\omega) = \frac{2}{j\omega + 2} - \frac{3}{(j\omega + 2)^2}$$

using standard fourier transform

$$x(t) = \underline{2 \cdot e^{-2t} u(t)} - 3t \cdot e^{-2t} u(t)$$

$$(ii) X(j\omega) = \frac{1}{(a + j\omega)^2} = \frac{1}{(a + j\omega)} \frac{1}{(a + j\omega)}$$

$$X(j\omega) = X_1(j\omega) \cdot X_2(j\omega)$$

$$x_1(t) = e^{-at} u(t); \quad x_2(t) = e^{-at} u(t)$$

using convolution property

$$x(t) = x_1(t) * x_2(t)$$

$$x(t) = \int_{-\infty}^{\infty} e^{-at} u(\tau) \cdot e^{-a(t-\tau)} u(t-\tau) \cdot d\tau$$

$$x(t) = \underline{\underline{1 \cdot e^{-at} u(t)}}$$

b)  $x(t) = e^{-3|t|} \sin 2t$

$$x(t) = \frac{e^{j2t} - e^{-j2t}}{2j} e^{-3|t|}$$

$$x(t) = \frac{1}{2j} \left[ e^{j2t} e^{-3|t|} - e^{-j2t} e^{-3|t|} \right]$$

$$e^{-a|t|} \xleftrightarrow{FT} \frac{2a}{a^2 + \omega^2}$$

$$\therefore e^{-3|t|} \xleftrightarrow{FT} \frac{6}{9 + \omega^2}$$

Using shifting property of frequency

$$\therefore e^{j2t} e^{-3|t|} \xleftrightarrow{FT} \frac{6}{9 + (\omega - 2)^2}$$

$$\therefore e^{-j2t} e^{-3|t|} \xleftrightarrow{FT} \frac{6}{9 + (\omega + 2)^2}$$

$$\therefore x(t) \xleftrightarrow{FT} \frac{1}{2j} \left[ \frac{6}{9 + (\omega - 2)^2} - \frac{6}{9 + (\omega + 2)^2} \right]$$

$$= \underline{\underline{\frac{3}{j} \left[ \frac{1}{9 + (\omega - 2)^2} - \frac{1}{9 + (\omega + 2)^2} \right]}}$$

7 a) i)  $x(e^{j\Omega}) = 1 + 2 \cos \Omega + 3 \cos 2\Omega$

$$x(e^{j\Omega}) = 1 + 2 \left[ \frac{e^{j\Omega} + e^{-j\Omega}}{2} \right] + 3 \left[ \frac{e^{j2\Omega} + e^{-j2\Omega}}{2} \right]$$

Inverse DTFT

$$\therefore x[n] = \delta[n] + \delta[n+1] + \delta[n-1] + \frac{3}{2} \delta[n+2] + \frac{3}{2} \delta[n-2]$$

$$\therefore x[n] = \underline{\underline{\left\{ \frac{3}{2}, 1, 1, \frac{3}{2} \right\}}}$$

$$(ii) Y(e^{j\Omega}) = j(3 + 4\cos\Omega + 2\cos 2\Omega) \sin\Omega$$

$$Y(e^{j\Omega}) = \frac{1}{2} e^{j3\Omega} + e^{j2\Omega} + e^{j\Omega} - e^{-j\Omega} - e^{-j2\Omega} - \frac{1}{2} e^{-j3\Omega}$$

Inverse DTFT

$$y[n] = \left\{ \frac{1}{2}, 1, 1, 0, -1, -1, -\frac{1}{2} \right\}$$

b) (i)  $x[n] = \left(\frac{1}{2}\right)^n u[n-2]$

$$x[n] = \left(\frac{1}{2}\right)^2 \cdot \left(\frac{1}{2}\right)^{n-2} u[n-2]$$

$$\left(\frac{1}{2}\right)^n u[n] \xleftrightarrow{\text{DTFT}} \frac{1}{1 - \frac{1}{2} e^{j\Omega}}$$

time-shift

$$\left(\frac{1}{2}\right)^{n-2} u[n-2] \xleftrightarrow{\text{DTFT}} e^{-j2\Omega} \frac{1}{1 - \frac{1}{2} e^{j\Omega}}$$

linearity property

$$\left(\frac{1}{2}\right)^2 \cdot \left(\frac{1}{2}\right)^{n-2} u[n-2] \xleftrightarrow{\text{DTFT}} \left(\frac{1}{2}\right)^2 e^{-j2\Omega} \frac{1}{1 - \frac{1}{2} e^{j\Omega}}$$

$$x(e^{j\Omega}) = \frac{1}{4} e^{-j2\Omega} \frac{1}{1 - \frac{1}{2} e^{j\Omega}}$$

(ii)  $x[n] = \sin\left(\frac{\pi}{4}n\right) \left(\frac{1}{4}\right)^n u[n-1]$

$$x[n] = \left[ \frac{e^{j\pi/4n} - e^{-j\pi/4n}}{2j} \right] \left(\frac{1}{4}\right) \left(\frac{1}{4}\right)^{n-1} u[n-1]$$

Time-shift property

$$\left(\frac{1}{4}\right)^{n-1} u[n-1] \xleftrightarrow{\text{DTFT}} e^{-j\Omega} \frac{1}{1 - \frac{1}{4} e^{j\Omega}}$$

Frequency-shift

$$e^{j\pi/4n} \cdot \left(\frac{1}{4}\right)^{n-1} u[n-1] \xleftrightarrow{\text{DTFT}} \frac{1}{e^{j(\Omega - \pi/4)} - \frac{1}{4}}$$

$$x(e^{j\Omega}) = \frac{1}{8j} \left[ \frac{1}{e^{j(\Omega - \pi/4)} - \frac{1}{4}} - \frac{1}{e^{j(\Omega + \pi/4)} - \frac{1}{4}} \right]$$

8 a) i) Frequency differentiation

$$\text{If } x[n] \xleftrightarrow{\text{DTFT}} X(e^{j\Omega})$$

$$\text{Then } -jn x[n] \xleftrightarrow{\text{DTFT}} \frac{d}{d\Omega} X(e^{j\Omega})$$

Proof:

(ii) Modulation

$$\text{If } x[n] \xleftrightarrow{\text{DTFT}} X(e^{j\Omega})$$

$$\text{and } y[n] \xleftrightarrow{\text{DTFT}} Y(e^{j\Omega})$$

$$\text{Then } z[n] = x[n] \cdot y[n] \xleftrightarrow{\text{DTFT}} Z(e^{j\Omega})$$

$$= \frac{1}{2\pi} [X(e^{j\Omega}) * Y(e^{j\Omega})]$$

⊛ periodic convolution

Proof:

9 b) (i)  $x[n] = 2^n u[-n]$

$$X(e^{j\Omega}) = \sum_{n=-\infty}^{\infty} x[n] \cdot e^{-j\Omega n}$$

$$\therefore X(e^{j\Omega}) = \sum_{n=-\infty}^0 2^n \cdot e^{-j\Omega n}$$

$$\therefore X(e^{j\Omega}) = \underline{\underline{\frac{2}{2 - e^{j\Omega}}}}$$

(ii)  $x[n] = a^{|n|}$ ;  $|a| < 1$

$$X(e^{j\Omega}) = \sum_{n=-\infty}^{\infty} x[n] \cdot e^{-j\Omega n}$$

$$= \sum_{n=-\infty}^{-1} a^{-n} \cdot e^{-j\Omega n} + \sum_{n=0}^{\infty} a^n \cdot e^{-j\Omega n}$$

$$X(e^{j\Omega}) = \underline{\underline{\frac{1 - a^2}{1 - 2a \cos \Omega + a^2}}}$$

9 a)

$$X(z) = \frac{z(z^2 - 4z + 5)}{(z-1)(z-2)(z-3)}$$

ROCs: (i)  $2 < |z| < 3$

$$\frac{X(z)}{z} = \frac{z^2 - 4z + 5}{(z-1)(z-2)(z-3)}$$

$$\frac{X(z)}{z} = \frac{A}{z-1} + \frac{B}{z-2} + \frac{C}{z-3}$$

$$\frac{X(z)}{z} = \frac{1}{z-1} + \frac{1}{z-2} + \frac{1}{z-3}$$

$$\therefore \underline{x[n] = -(3)^n u[-n-1] + (1)^n u[n] - (2)^n u[n]}$$

(ii)  $|z| > 3$

$$\underline{x[n] = 3^n u[n] + (1)^n u[n] - (2)^n u[n]}$$

(iii)  $|z| < 1$

$$\underline{x[n] = -(3)^n u[-n-1] + (1)^n u[-n-1] + 2^n u[-n-1]}$$

b)  $y[n] - \frac{1}{2}y[n-1] = 2x[n]$

natural response:  $y[n] - \frac{1}{2}y[n-1] = 0$

$$Y(z) = \frac{3/2 \cdot z}{(z-1/2)}$$

$$\therefore \underline{y^n[n] = 3/2 \cdot (1/2)^n u[n]}$$

forced response:  $x[n] = 2 \cdot (-1/2)^n u[n]$

$$Y(z) = 2 \frac{z}{(z+1/2)} + 2 \frac{z}{(z-1/2)}$$

$$\therefore \underline{y^f[n] = 2 \cdot (-1/2)^n u[n] + 2 \cdot (1/2)^n u[n]}$$

complete response:  $y[n] = y^n[n] + y^f[n]$

$$\underline{y[n] = \frac{7}{2} (1/2)^n u[n] + 2 \cdot (-1/2)^n u[n]}$$

10 a) Properties of ROC

$$b) H(z) = \frac{3 - 4z^{-1}}{1 - 3.5z^{-1} + 1.5z^{-2}}$$

By partial fraction expansion.

$$H(z) = \frac{1}{(1 - \frac{1}{2}z^{-1})} + \frac{2}{(1 - 3z^{-1})}$$

location of poles  $z = \frac{1}{2}$  and  $z = 3$

(i) stable system

$$\frac{1}{2} < |z| < 3$$

$$\therefore h[n] = \left(\frac{1}{2}\right)^n u[n] - 2(3)^n u[-n-1]$$

(ii) causal system

$$|z| > 3$$

$$\therefore h[n] = \left(\frac{1}{2}\right)^n u[n] + 2(3)^n u[n]$$