CMR INSTITUTE OF TECHNOLOGY





# **Internal Assessment Test 1 – September 2019**



A service-oriented architecture (SOA) is a style of software design where services are provided to the other components by application components, through a communication protocol over a network. The basic principles of service-oriented architecture are independent of vendors, products and technologies.[1] A service is a discrete unit of functionality that can be accessed remotely and acted upon and updated independently, such as retrieving a credit card statement online.

- A service has four properties according to one of many definitions of SOA
- 1. It logically represents a business activity with a specified outcome.
- 2. It is self-contained.
- 3. It is a black box for its consumers.
- 4. It may consist of other underlying services.

Different services can be used in conjunction to provide the functionality of a large software application, a principle it shares with modular programming. Service-oriented architecture integrates distributed, separately-maintained and deployed software components. It is enabled by technologies and standards that make it easier for components to communicate and cooperate over a network, especially an IP network.

In SOA, services use protocols that describe how they pass and parse messages using description metadata. This metadata describes both the functional characteristics of the service and quality-of-service characteristics. Service-oriented architecture aims to allow users to combine large chunks of functionality to form applications which are built purely from existing services and combining them in an ad hoc manner. A service presents a simple interface to the requester that abstracts away the underlying complexity acting as a black box. Further users can also access these independent services without any knowledge of their internal implementation. The related buzzword service-orientation promotes loose coupling between services. SOA separates functions into distinct units, or services, which developers make accessible over a network in order to allow users to combine and reuse them in the production of applications. These services and their corresponding consumers communicate with each other by passing data in a well-defined, shared format, or by coordinating an activity between two or more services.[7]

A manifesto was published for service-oriented architecture in October, 2009. This came up with six core values which are listed as follows

- 1. Business value is given more importance than technical strategy.
- 2. Strategic goals are given more importance than project-specific benefits.
- 3. Intrinsic inter-operability is given more importance than custom integration.
- 4. Shared services are given more importance than specific-purpose implementations.
- 5. Flexibility is given more importance than optimization.
- 6. Evolutionary refinement is given more importance than pursuit of initial perfection.

SOA can be seen as part of the continuum which ranges from the older concept of distributed computing and modular programming. through SOA, and on to current practices of mashups, SaaS, and cloud computing(which some see as the offspring of SOA).



### 2. Instruction Set Architecture Level

At the ISA level, virtualization is performed by emulating a given ISA by the ISA of the host machine. For example, MIPS binary code can run on an x86-based host machine with the help of ISA emulation. With this approach, it is possible to run a large amount of legacy binary code written for various processors on any given new hardware host machine. Instruction set emulation leads to virtual ISAs created on any hardware machine. The basic emulation method is through code interpretation. An interpreter program interprets the source instructions to target instructions one by one. One source instruction may require tens or hundreds of native target instructions to perform its function. Obviously, this process is relatively slow. For better performance, dynamic binary translation is desired. This approach translates basic blocks of dynamic source instructions to target instructions. The basic blocks

can also be extended to program traces or super blocks to increase translation efficiency. Instruction set emulatio n requires binary translation and optimization. A virtual instruction set architecture (V-ISA) thus

requires adding a processor-specific software translation layer to the compiler.

### **Hardware Abs traction Level**

Hardware-level virtualization is performed right on top of the bare hardware. On the one hand, this approach generates a virtual hardware environment for a VM. On the other hand, the process manages the underlying hardware through virtualization. The ide a is to virtualize a computer's resources, such as its processors, memory, and I/O devices. The intention is to upgrade the hardware utilization rate by multiple users concurrently. The idea was implemented in the IBM VM/370 in the 1960s. More recently, the Xen hypervisor has been applied to virtualize x86-based machines to run Linux or other

guest OS applications.

### **Operating System Level**

This refers to an abstraction layer between traditional OS and user applications. OS-level virtualization creates isolated containers on a single physical server and the OS instances to utilize the hardware and software in data centers. The containers behave like real servers. OS-level virtualization is commonly used in creating virtual hosting environments to allocate hardware resources among a large number of mutually distrusting users. It is also used, to a lesser extent, in consolidating server hardware by moving services on separate hosts into containers or VMs on one server.

### **Library Support Level**

Most applications use APIs exported by user-level libraries rather than using lengthy system calls by the OS. Since most systems provide well-documented APIs, such an interface becomes another candidate for virtualization. Virtualization with library interfaces is possible by controlling the communication link between applications and the rest of a system through API hooks. The software tool WINE has implemented this approach to support Windows applications on top of UNIX hosts.

Another example is the vCUDA which allows applications executing within VMs to leverage GPU

#### hardware acceleration. **User-Application Level**

Virtualization at the application level virtualizes an application as a VM. On a traditional OS, an application often runs as a process. Therefore, application-level virtualization is also known a sprocess-level virtualization. The most popular approach is to deploy high level language (HLL) VMs. In this scenario, the virtualization layer sits as an application program on top of the operating system, and the layer exports an abstraction of a VM that can run programs written and compiled to a particular abstract machine definition. Any program written in the HLL and compiled for this VM will be able to run on it. The Microsoft .NET CLR and Java Virtual Machine (JVM) are two good examples of this class of VM. Other forms of application -level virtualization are known as application isolation, application s andboxing, or application streaming. The process involves wrapping the application in a layer that is isolated from the host OS and other applications. The result is an application that is much easier to distrib ute and remove from user workstations. An example is the LANDesk application virtualization platform which deploys software applications as self-contained, executable files in an isolated

environment without requiring installation, system modifications, or elevated security privileges. process -level virtualization. The most popular approach is to deploy high level language (HLL) VMs. In this scenario, the virtualization layer sits as an application program on top of the operating system, and the layer exports an abstraction of a VM that can run programs written and compiled to a particular abstract machine definition. Any program written in the HLL and compiled for this

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#### FIGURE 3.2

Virtualization ranging from hardware to applications in five abstraction levels.

3.a.



#### 3b.

The term "storage virtualization" was widely used before the renaissance of system virtualization. Yet the term has a different meaning in a system virtualization environment. Previously, storage virtualization was largely used to describe the aggregation and repartitioning of disks at very coarse time scales for use by physical machines. In system virtualization, virtual storage includes the storage managed by VMMs and guest OSes. Generally, the data stored in this environment can be classified into two categories: VM images and application data. The VM images are special to the virtual environment, while application data includes all other data which is the same as the data in traditional OS environments.

The most important aspects of system virtualization are encapsulation and isolation. Traditional operating systems and applications running on them can be encapsulated in VMs. Only one operating system runs in a virtualization while many applications run in the operating system. System virtualization allows multiple VMs to run on a physical machine and the VMs are completely isolated. To achieve encapsulation and isolation, both the system software and the hardware platform, such as CPUs and chipsets, are rapidly updated. However, storage is lagging. The storage systems become the main bottleneck of VM deployment.

In virtualization environments, a virtualization layer is inserted between the hardware and traditional operating systems or a traditional operating system is modified to support virtualization. This procedure complicates storage operations. On the one hand, storage management of the guest OS performs as though it is operating in a real hard disk while the guest OSes cannot access the hard disk directly. On the other hand, many guest OSes contest the hard disk when many VMs are running on a single physical machine. Therefore, storage management of the underlying VMM is much more complex than that of guest OSes (traditional OSes).

In addition, the storage primitives used by VMs are not nimble. Hence, operations such as remapping volumes across hosts and checkpointing disks are frequently clumsy and esoteric, and sometimes simply unavailable. In data centers, there are often thousands of VMs, which cause the VM images to become flooded. Many researchers tried to solve these problems in virtual storage management. The main purposes of their research are to make management easy while enhancing performance and reducing the amount of storage occupied by the VM images. Parallax is a distributed storage system customized for virtualization environments. Content Addressable Storage (CAS) is a solution to reduce the total size of VM images, and therefore supports a large set of VM-based systems in data centers.

Since traditional storage management techniques do not consider the features of storage in virtualization environments, Parallax designs a novel architecture in which storage features that have traditionally been implemented directly on high-end storage arrays and switchers are relocated into a federation of storage VMs. These storage VMs share the same physical hosts as the VMs that they serve. Figure 3.30 provides an overview of the Parallax system architecture. It supports all popular system virtualization techniques, such as paravirtualization and full virtualization. For each physical machine, Parallax customizes a special storage appliance VM. The storage appliance VM acts as a block virtualization layer between individual VMs and the physical storage device. It provides a virtual disk for each VM on the same physical machine.

#### 4. Host-Based Virtualization

An alternative VM architecture is to install a virtualization layer on top of the host OS. This host OS is still responsible for managing the hardware. The guest OSes are installed and run on top of the virtualization layer. Dedicated applications may run on the VMs. Certainly, some other applications can also run with the host OS directly. This hostbased architecture has some distinct adva ntages, as enumerated next. First, the user can install this VM architecture without modifying the host OS. The virtuali zing software can rely on the host OS to provide device drivers and other low-level services. This will simplify the VM design and ease

its deployment. Second, the host-based approach appeals to many host machine configurations. Compared to the hypervisor/VMM architecture, the performance of the host-based architecture may also be low. When an application requests hardware access, it involves four layers of mapping which downgrades performance significantly. When the ISA of a guest OS is different from the ISA of the underlying hardware, binary translation must be adopted. Although the host-based architecture has flexibility, the performance is too low to be useful in practice.



#### **FIGURE 3.6**

Indirect execution of complex instructions via binary translation of guest OS requests using the VMM plus direct execution of simple instructions on the same host.

#### Para-Virtualization Architecture

When the x86 processor is virtualized, a virtualization layer is inserted between the hardware and the OS. According to the x86 ring definition, the virtualization layer should also be installed at Ring 0. Different instructions at Ring 0 may cause some problems. In the figure below, we show that para-virtualization replaces nonvirtualizable instructions with hypercalls that communicate directly with the hypervisor or VMM. However, when the guest OS kernel is modified for virtualization, it can no longer run on the hardware directly. Although para-virtualization reduces the overhead, it has incurred other problems. First, its compatibility and portability may be in doubt, because it must support the unmodified OS as well. Second, the cost of maintaining para-virtualized OSes is high, because they may require deep OS kernel modifications. Finally, the performance advantage of para-virtualization varies greatly due to workload variations. Compared with full virtualization, para-virtualization is relatively easy and more practical. The main problem in full virtualization is its low performance in binary translation. To speed up binary translation is difficult. Therefore, many virtualization products employ the para-virtualization architecture. The popular Xen, KVM, and VMware ESX are good examples.



#### **FIGURE 3.7**

5.

Para-virtualized VM architecture, which involves modifying the guest OS kernel to replace nonvirtualizable instructions with hypercalls for the hypervisor or the VMM to carry out the virtualization process (See Figure 3.8 for more details.)



#### **FIGURE 3.8**

The use of a para-virtualized guest OS assisted by an intelligent compiler to replace nonvirtualizable OS instructions by hypercalls.

(Courtesy of VMWare [71])



#### **FIGURE 3.20**

Live migration process of a VM from one host to another.



### **What is a public cloud?**

A public cloud is built over the Internet and can be accessed by any user who has paid for the service. Public clouds are own ed by service providers and are accessible through a subscription. The callout box in top of Figure shows the architecture of a typical public cloud. Many public clouds are available, including Google App Engine (GAE), Amazon Web Services (AWS), Microsoft Azure, IBM Blue Cloud, and Salesforce.com's Force.com. The providers of the aforementioned clouds are commercial providers that offer a publicly accessible remote interface for creating and managing VM instances within their proprietary infrastructure. A public cloud delivers a selected set of business processes. The application and infrastructure services are offered on a flexible price-per-use basis.

### **Advantages of public clouds:**

 Lower costs—no need to purchase hardware or software and you pay only for the service you use. No maintenance—your service provider provides the maintenance. Near-unlimited scalability—on-demand resources are available to meet your business needs. High reliability—a vast network of servers ensures against failure.

#### **What is a private cloud?**

A private cloud is built within the domain of an intranet owned by a single organization. Therefore, it is client owned and managed, and its access is limited to the owning clients and their partners. Its deployment was not meant to sell capacity over the Intern et through publicly accessible interfaces. Private clouds give local users a flexible and agile private infrastru cture to run service workloads within their administrative domains. A private cloud is supposed to deliver more efficient and convenient cloud services. It may imp act the cloud standardization, while retaining greater customization and organizational control.

#### **Advantages of private clouds:**

 More flexibility—your organisation can customise its cloud environment to meet specific business needs. Improved security—resources are not shared with others, so higher levels of control and security are possible. High scalability—private clouds still afford the scalability and efficiency of a public cloud.

#### **What is a hybrid cloud?**

A hybrid cloud is built with both public and private clouds, as shown at the lower-left corner of Figure. Private clouds can also support a hybrid cloud model by supplementing local infrastructure with computing capacity from an external public cloud. For example , the Research Compute Cloud (RC2) is a private cloud, built by IBM, that interconnects the computing and IT resources at eight IBM Research Centers scattered throughout the United States, Europe, and Asia. A hybrid cloud provides access to clients, the partner network, and third parties.

#### **Advantages of hybrid clouds:**

Control—your organisation can maintain a private infrastructure for sensitive assets.

Flexibility—you can take advantage of additional resources in the public cloud when you need them.

 Cost-effectiveness—with the ability to scale to the public cloud, you pay for extra computing power only when needed. Ease—transitioning to the cloud does not have to be overwhelming because you can migrate gradually—phasing in workloads over time.

6a.

### 6b**.** IaaS: Infrastructure as a Service

Cloud infrastructure services, known as Infrastructure as a Service (IaaS), are made of highly scalable and automated compute resources. IaaS is fully self-service for accessing and monitoring things like compute, networking, storage, and other services, and it allows businesses to purchase resources on-demand and as-needed instead of having to buy hardware outright. Some characteristics to look for when considering IaaS are:

- Resources are available as a service
- The cost varies depending on consumption
- Services are highly scalable
- Typically includes multiple users on a single piece of hardware
- Provides complete control of the infrastructure to organizations
- Dynamic and flexible

### PaaS: Platform as a Service

Cloud platform services, or Platform as a Service (PaaS), provide cloud components to certain software while being used mainl y for applications. PaaS provides a framework for developers that they can build upon and use to create customized applications. Al l servers, storage, and networking can be managed by the enterprise or a third-party provider while the developers can maintain management of the applications.

PaaS has many characteristics that define it as a cloud service, including:

- It is built on virtualization technology, meaning resources can easily be scaled up or down as your business changes
- Provides a variety of services to assist with the development, testing, and deployment of apps
- Numerous users can access the same development application
- Web services and databases are integrated

### SaaS: Software as a Service

Software as a Service, also known as cloud application services, represent the most commonly utilized option for businesses in the cloud market. SaaS utilizes the internet to deliver applications to its users, which are managed by a third -party vendor. A majority of SaaS applications are run directly through the web browser, and do not require any downloads or installations on the client side.

There are a few ways to help you determine when SaaS is being utilized:

- Managed from a central location
- Hosted on a remote server
- Accessible over the internet
- Users not responsible for hardware or software updates



#### FIGURE 4.5

The laaS, PaaS, and SaaS cloud service models at different service levels.

# 7. vCUDA Architecture



Basic concept of the vCUDA architecture.

CUDA is a programming model and library for general-purpose GPUs. It leverages the high performance of GPUs to run computeintensive applications on host operating systems. However, it is difficult to run CUDA applications on hardware-level VMs directly. vCUDA virtualizes the CUDA library and can be installed on guest OSes. When CUDA applications run on a guest OS and issue a call to the CUDA API, vCUDA intercepts the call and redirects it to the CUDA API running on the host OS. The vCUDA employs a clientserver model to implement CUDA virtualization. It consists of three user space components: the vCUDA library, a virtual GPU in the guest OS (which acts as a client), and the vCUDA stub in the host OS (which acts as a server). The vCUDA library resides in the guest OS as a substitute for the standard CUDA library. It is responsible for intercepting and redirecting API calls from the clien t to the stub. Besides these tasks, vCUDA also creates vGPUs and manages them. The functionality of a vGPU is threefold: It abstracts the GPU structure and gives applications a uniform view of the underlying hardware; when a CUDA application in the guest OS allocates a device's memory the vGPU can return a local virtual address to the application and notify the remote stub to allocate the real device memory, and the vGPU is responsible for storing the CUDA API flow. The vCUDA stub receives and interprets remote requests and creates a corresponding execution context for the API calls from the guest OS, then returns the results to the guest OS. The vCUDA stub also manages actual physical resource allocation.

8. Message Passing: Message passing is a form of communication between objects, processes or other resources used in object-oriented programming, inter-process communication and parallel computing. Message passing can be **synchronous** or **asynchronous**. Synchronous message passing systems require the sender and receiver to wait for each other while transferring the message. In asynchronous communication the sender and receiver do not wait for each other and can carry on their own computations while transfer of messages is being done. The concept of message passing makes it easier to build systems that model or simulate real- world problems.

Map Reduce: MapReduce is a programming model suitable for processing of huge data. Hadoop is capable of running MapReduce programs written in various languages: Java, Ruby, Python, and C++. MapReduce programs are parallel in nature, thus are very useful for performing large-scale data analysis using multiple machines in the cluster. MapReduce programs work in two phases: Map phase & Reduce phase. An input to each phase is **keyvalue** pairs. In addition, every programmer needs to specify two functions: **map function** and **reduce function**.



# Network Threats:

Data Integrity:

9.



## **FIGURE 3.5**

The Xen architecture's special domain 0 for control and I/O, and several guest domains for user applications. (Courtesy of P. Barham, et al. [7])

10. Virtual clusters are built with VMs installed at distributed servers from one or more physical clusters. The VMs in a virtual cluster are interconnected logically by a virtual network across several physical networks. Each virtual cluster is formed with physical machines or a VM hosted by multiple physical clusters. The virtual cluster boundaries are shown as distinct bou ndaries. The provisioning of VMs to a virtual cluster is done dynamically to have the following interesting properties:

• The virtual cluster nodes can be either physical or virtual machines. Multiple VMs running with different OSes can be deplo yed on the same physical node.

• A VM runs with a guest OS, which is often different from the host OS, that manages the resources in the physical machine, where the VM is implemented.

• The purpose of using VMs is to consolidate multiple functionalities on the same s erver. This will greatly enhance server utilization and application flexibility.

• VMs can be colonized (replicated) in multiple servers for the purpose of promoting distributed parallelism, fault tolerance , and disaster recovery.

• The size (number of nodes) of a virtual cluster can grow or shrink dynamically, similar to the way an overlay network varies in size in a peer-to-peer (P2P) network.

• The failure of any physical nodes may disable some VMs installed on the failing nodes. But the failure of VMs will not pull down the host system.

Since system virtualization has been widely used, it is necessary to effectively manage VMs running on a mass of physical computing nodes (also called virtual clusters) and consequently build a high-performance virtualized computing environment. This involves virtual cluster deployment, monitoring and management over large-scale clusters, as well as resource scheduling, load balancing, server consolidation, fault tolerance, and other techniques. The different node colors in the Figure refer to different virtual clusters. In a virtual cluster system, it is quite important to store the large number of VM images efficiently. The different colors in the figure represent the nodes in different virtual clusters. As a large number of VM images might be present, the most important thing is to determine how to store those images in the system efficiently. There are common installations for most users or applications, such as operatin g systems or user-level programming libraries. These software packages can be preinstalled as templates (called template VMs). With these templates, users can build their own software stacks. New OS instances can be copied from the template VM. User-specific components such as programming libraries and applications can be installed to those instances. Three physical clusters are shown on the left side of the Figure. Four virtual clusters are created on the right, over the physical clusters. The physical machines are also called host systems. In contrast, the VMs are guest systems. The host and guest systems may run with different operating systems. Each VM can be installed on a remote server or replicated on multiple servers belonging to the same or different physical clusters. The boundary of a virtual cluster can change as VM nodes are added, removed, or migrated dynamically over time.



# **FIGURE 3.18**

A cloud platform with four virtual clusters over three physical clusters shaded differently.



**FIGURE 3.19** 

The concept of a virtual cluster based on application partitioning.