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**Fourth Semester B.E. Degree Examination, June/July 2017**  
**Control System**

Time: 3 hrs.

Max. Marks:100

**Note: 1. Answer any FIVE full questions, selecting at least TWO questions from each part.**  
**2. Graph and semi log required.**

**PART - A**

- 1 a. Write down the differential equations governing the system below and write the force voltage analogy circuit. (10 Marks)

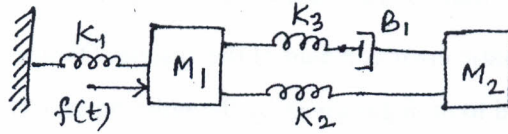


Fig.Q1(a)

- b. For the Fig.Q1(b). Derive the expression for the TF :  $\frac{Q_1(s)}{T_1(s)} = \frac{1}{s(s^2 J_{eq} + B_{eq})}$ . (10 Marks)

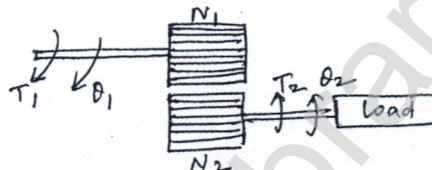


Fig.Q1(b)

- 2 a. Find the TF of the system by using block diagram reduction method. (10 Marks)

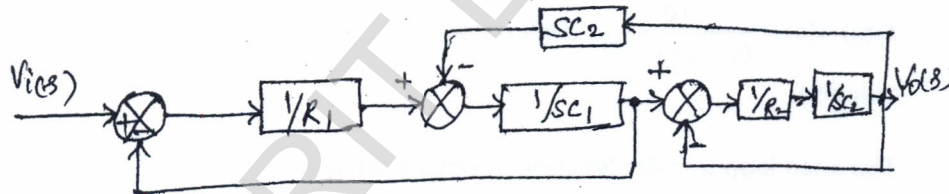


Fig.Q2(a)

- b. Find the C/R for the following system using Mason's gain formula. (10 Marks)

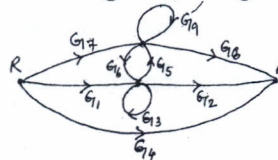


Fig.Q2(b)

- 3 a. Give the definition for the following transient response of a control systems to a unit step input in terms of time domain specifications.  
i) Delay time,  $t_d$  ii) Rise time,  $t_r$  iii) Peak time,  $t_p$  iv) Maximum overshoot  $M_p$  v) Settling time,  $t_s$  with equations. (10 Marks)

- b. A closed loop servo is represented by the differential equation :  $\frac{d^2c}{dt^2} + \frac{8dc}{dt} = 64e$  where 'c' is the displacement of the output Shaft 'r' is the displacement of the input shaft and  $e = r - c$ , determine undamped natural frequency, damping ratio. (10 Marks)

Important Note : 1. On completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages.  
2. Any revealing of identification, appeal to evaluator and /or equations written eg, 42+8 = 50, will be treated as malpractice.

- 4 a. A system with oscillating frequency  $\omega$ , if it has poles at  $s = \pm j\omega$ , no poles to the right half of the S plane. Determine the value of 'K' and so that the system is shown below oscillates at a frequency of 2 rad/sec. (10 Marks)

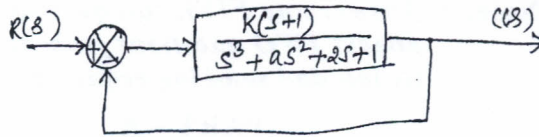


Fig.Q4(a)

- b. The open loop transfer function of servo system with unity feedback is  $G(s) = \frac{10}{s(0.1s + 1)}$ . Evaluate the static error constant of the system. Obtain the steady – state error of the system, when subjected to an input given by the polynomial  $r(t) = a_0 + a_1t + \frac{a_2}{2}t^2$ . (10 Marks)

**PART – B**

- 5 For a unity feedback system the open–loop transfer function is given by :

$$G(s) = \frac{k}{s(s + 2)(s^2 + 6s + 25)}$$

- i) Sketch the root locus for  $0 \leq k \leq \infty$
- ii) At what value of K the system becomes unstable?
- iii) At this point of instability, determine the frequency of oscillation of the system.

(20 Marks)

- 6 Sketch the Nyquist plot for the open loop transfer function :

$$G(s)H(s) = \frac{10}{(s + 2)(s + 4)}$$

Determine the stability of the closed loop system by Nyquist criterion.

(20 Marks)

- 7 The open loop transfer function of unity feedback system is :  $G(s) = \frac{K}{s(s + 1)(s + 10)}$ .

Draw the Bode plot and determine :

- i) Limiting value of K for the system to be stable
- ii) The value of 'K' for gain margin of 7dB

iii) The value of K for phase margin of  $40^\circ$   $G(s) = \frac{k}{s(s + 1)(s + 10)}$ .

(20 Marks)

- 8 a. Write the state equation for the network shown :

(10 Marks)

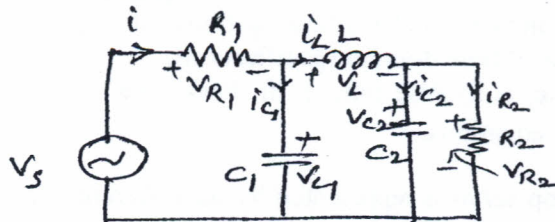


Fig.Q8()

- b. Obtain the characteristic equation of the matrix :

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 3 & 0 & 2 \\ -12 & -7 & -6 \end{bmatrix}$$

(10 Marks)

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