

Internal Assessment Test - III

Sub:	CONTROL SYSTEMS						Code:	17EE61 / 18EE61	
Date:	02/08/2021	Duration:	90 mins	Max Marks:	50	Sem:	6th	Branch:	EEE
Answer Any FIVE FULL Questions									
							Marks	OBE	
								CO	RBT
1	Sketch the root locus of the transfer function whose open loop transfer function is $G(s) = \frac{K}{s(s+2)(s+4)}$						10	CO4	L4
2	For the closed loop transfer function when the input is unit step $\frac{C(s)}{R(s)} = \frac{16}{s^2 + 4s + 16}$. Determine undamped natural frequency, damping ratio, Maximum overshoot, Peak time and settling time.						10	CO3	L3
3	A unity feedback system is characterized by open-loop transfer function $G(s) = \frac{10}{s^2(1+0.4s)(1+0.3s)}$. Determine steady state errors for unit step, unit ramp and unit parabola.						10	CO3	L3
4	Determine the range of K for stability of unity feedback system whose open loop transfer function is $G(s) = \frac{K}{s(s+1)(s+2)}$ using Routh Hurwitz criteria.						10	CO3	L4
5	Determine if the pole nearest to the imaginary axis is at least -0.75 away from imaginary axis, for the system given by characteristic equation $s^4 + 5s^3 + 10s^2 + 10s + 4 = 0$						10	CO3	L4
6	A unity feedback control system has an open loop transfer function $G(s) = \frac{K}{s(s^2 + 4s + 13)}$ Sketch the root locus.						10	CO4	L4
7	Determine the frequency domain specifications for the unity feedback system $G(s) = \frac{225}{s(s+6)}$						10	CO4	L3

Control Systems IAT 3 Solution

1.

Step:-1

Starting points are $s=0, s=-2, s=-4$

Ending points are $s=\infty, \infty, \infty$.

Step:-2

Number of branches = 3.

Step:-3 Symmetrical.

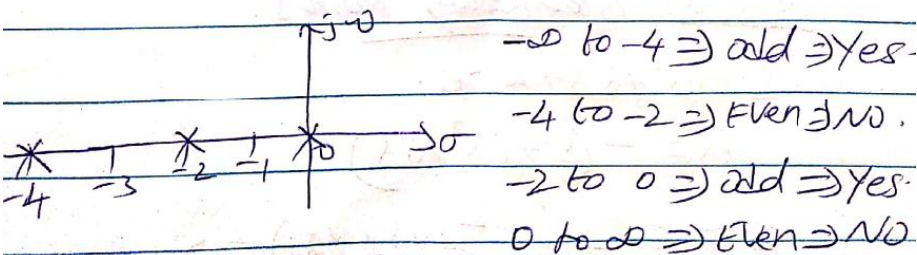
Step:-4

Angle of Asymptotes $\phi_a = \frac{(2q+1)180}{n-m}$

$n=3, m=0, n-m-1=3-0-1=2$.

If $q=0, \phi_a=60^\circ$.	Intersection of Asymptote $\sigma_a = \frac{(0-2-4)-0}{3-0}$ $= \frac{-6}{3} = -2$
$q=1, \phi_a=180^\circ$.	
$q=2, \phi_a=-60^\circ$.	

Step:-5 Root locus of real axis.



Step: 6. No complex pole of complex zero

∴ No Angle of Departure/Arrival

Step: 7

$$\frac{C(s)}{R(s)} = \frac{K}{s(s+2)(s+4)+K}$$

$$s(s+2)(s+4)+K=0$$

$$s^3+6s^2+8s+K=0$$

s^3	1	8	$s^0 \Rightarrow K > 0$
s^2	6	K	$s^1 \Rightarrow K < 48$
s^1	$48-K$		For stable,
s^0	6	K	$0 < K < 48$

$$K=48, 6s^2+K=0$$

$$6s^2+48=0$$

$$s^2+8=0$$

$$s^2=-8$$

$$s = \pm 2.8j$$

Step: 8. Breakaway points -

$$s^3+6s^2+8s+K=0$$

$$K = -(s^3+6s^2+8s)$$

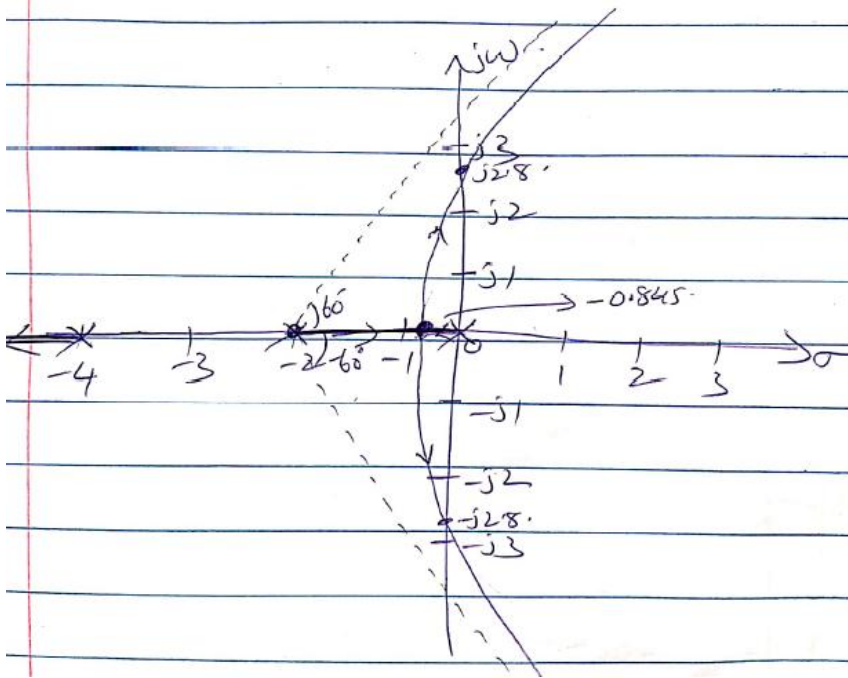
$$\frac{dK}{ds} = -(3s^2+12s+8) = 0$$

$$s = -0.845, -3.154$$

$s = -0.845$ is valid breakaway point

$s = -3.154$ is invalid breakaway point

Sketch root locus



2.

$$\frac{C(s)}{R(s)} = \frac{16}{s^2 + 4s + 16}$$

$$s^2 + 2\zeta\omega_n s + \omega_n^2 \Leftrightarrow s^2 + 4s + 16$$

$$\left. \begin{array}{l} \omega_n^2 = 16 \\ \omega_n = 4 \text{ rad/sec} \end{array} \right\} \begin{array}{l} 2\zeta\omega_n = 4 \\ \zeta = 0.5 \end{array}$$

∴ undamped natural

freq, $\omega_n = \underline{\underline{4 \text{ rad/sec}}}$

Damping ratio, $\zeta = \underline{\underline{0.5}}$

/ Maximum overshoot,

$$\% M_p = e^{-\zeta\pi/\sqrt{1-\zeta^2}} \times 100$$

$$= \underline{\underline{16.3\%}}$$

3.

$$G(s) = \frac{10}{s^2(1+0.4s)(1+0.3s)}$$

Unit step

$$K_p = \lim_{s \rightarrow 0} G(s) = \infty, \quad e_{ss} = \frac{1}{1+K_p} = 0.$$

Unit Ramp

$$K_v = \lim_{s \rightarrow 0} sG(s) = \infty, \quad e_{ss} = \frac{1}{K_v} = 0.$$

Unit Parabola

$$K_a = \lim_{s \rightarrow 0} s^2 G(s) = \lim_{s \rightarrow 0} \frac{10}{s(1+0.4s)(1+0.3s)}$$

$$= 10.$$

$$e_{ss} = \frac{1}{K_a} = \frac{1}{10} = \underline{\underline{0.1}}$$

4.

characteristic equation is,

$$1 + G(s)H(s) = 1 + \frac{K}{s(s+1)(s+2)} = 0$$

$$s(s+1)(s+2) + K = 0.$$

$$s^3 + 3s^2 + 2s + K = 0.$$

Routh table,

s^3	1	2
s^2	3	K
s^1	$\frac{6-K}{3}$	
s^0	K	

For stable system,

$$s^0 \text{ row} \Rightarrow K > 0.$$

$$s^1 \text{ row} \Rightarrow \frac{6-K}{3} > 0 \Rightarrow K < 6$$

\therefore Range of K for stable system is

$$\underline{\underline{0 < K < 6.}}$$

5.

$$\text{Put } s = (z - 0.75)$$

$$(z - 0.75)^4 + 5(z - 0.75)^3 + 10(z - 0.75)^2 + 10(z - 0.75) + 4 = 0$$

$$z^4 - 2z^3 + 11.24z^2 - 5z - 7.043 = 0$$

z^4	1	11.24	-7.043
z^3	-2	-5	
z^2	8.74	-7.043	
z^1	-6.6		
z^0	-7.043		

Unstable system.

\therefore 3 roots are less negative than -0.75.

6.

Step 1 Starting and Ending points.

Starting points are poles.

$$s = 0, s^2 + 4s + 13 = 0$$

$$s = -2 \pm j\sqrt{9}$$

Ending points are zeros \Rightarrow No zeros.

$$\Rightarrow s = \infty, \infty, \infty$$

Step 2 Number of branch = Number of Poles.

$$= 3.$$

Step 3 Symmetrical with respect to ~~real~~ ^{real} axis.

Step 4

$$\text{Angle of Asymptote } \phi_a = \frac{(2q+1)180}{n-m}$$

where $q = 0, 1, \dots, n-m-1$.

$$n = 3, m = 0, n-m-1 = 3-0-1 = 2.$$

$$\text{If } q = 0, \phi_a = \frac{180}{3-0} = 60^\circ.$$

$$\text{If } q = 1, \phi_a = \frac{3 \times 180}{3} = 180^\circ.$$

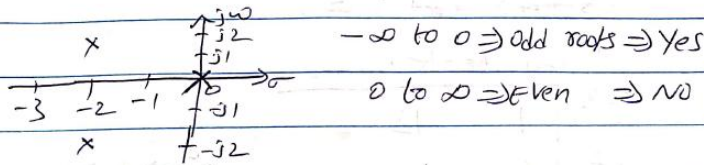
$$\text{If } q = 2, \phi_a = \frac{5 \times 180}{3} = 300 = -60^\circ.$$

Intersection point of Asymptote,

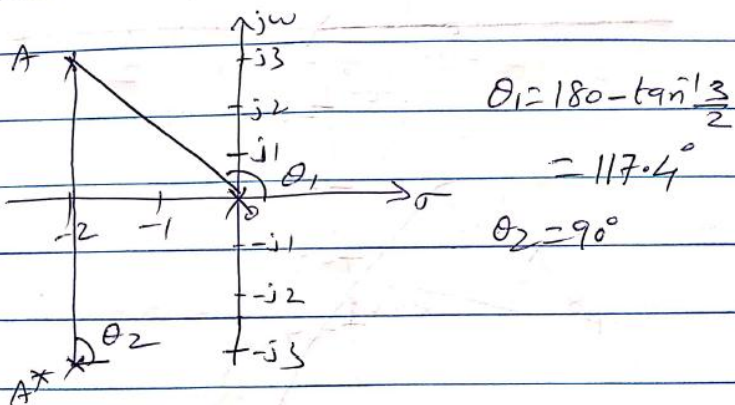
$$\sigma = \frac{\sum \text{finite poles} - \sum \text{finite zeros}}{n-m}$$

$$= \frac{(0-2-2) - 0}{3-0} = \frac{-4}{3} = -1.33$$

Step 5 Root locus on real axis



Step 6 Angle of Departure.



Angle of Departure from A } $= 180 - (\theta_1 + \theta_2) + (0)$
 $= 180 - 117.4 - 90 = -27.4^\circ$

Angle of Departure from A* } $= 27.4^\circ$

Step: 7 Intersection of root locus with Imaginary axis.

$$\frac{C(s)}{R(s)} = \frac{K}{s(s^2+4s+13)+K}$$

$$s(s^2+4s+13)+K=0$$

$$s^3+4s^2+13s+K=0$$

Routh table.

s^3	1	13	
s^2	4	K	$s^0 \Rightarrow K > 0$
s^1	$\frac{52-K}{4}$		$s^1 \Rightarrow K < 52$
s^0	K		For stable $0 < K < 52$

Critical value of $K = 52$.

$$4s^2+K=0$$

$$4s^2+52=0 \Rightarrow s^2+13=0$$

$$s^2 = -13$$

$$s = \pm j3.6$$

Step: 8 Breakaway point.

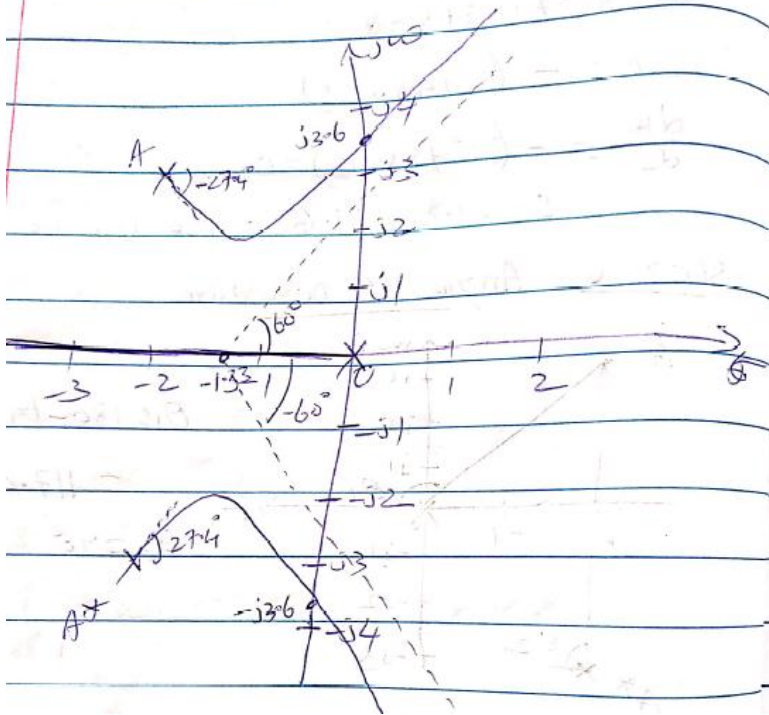
$$s^3+4s^2+13s+K=0$$

$$K = -(s^3+4s^2+13s)$$

$$\frac{dK}{ds} = -(3s^2+8s+13)=0$$

$$s = -1.33 \pm j1.6 \Rightarrow \text{No Breakaway points}$$

Sketch root locus -



7.

$$\therefore \frac{C(s)}{R(s)} = \frac{225}{s^2 + 6s + 225} \rightarrow \textcircled{1}$$

* By Comparing Equation ① with $\frac{W_n^2}{s^2 + 2\zeta W_n s + W_n^2}$, we have

$$W_n^2 = 225$$

$$W_n = \sqrt{225}$$

$$W_n = 15 \text{ rad/sec}$$

$$2\zeta W_n = 6$$

$$\zeta = \frac{6}{2W_n} = \frac{6}{2 \times 15}$$

$$\zeta = 0.2$$

Resonant Peaks.

$$M_r = \frac{1}{2\xi\sqrt{1-\xi^2}}$$
$$= \frac{1}{2 * 0.2 * \sqrt{1-(0.2)^2}}$$

$$M_r = 2.60$$

Resonant frequency

$$\omega_r = \omega_n \sqrt{1-2\xi^2}$$
$$= 15 * \sqrt{1-2*(0.2)^2}$$

$$\omega_r = 14.39 \text{ rad/sec}$$

Bandwidth

$$\omega_b = \omega_n \sqrt{(1-2\xi^2) + \sqrt{2-4\xi^2+4\xi^4}}$$
$$= 15 \sqrt{(1-2(0.2)^2) + \sqrt{2-4(0.2)^2+4(0.2)^4}}$$
$$= 15 \sqrt{(1-2(0.2)^2) + 1.3588}$$

$$\omega_b = 22.656 \text{ rad/sec.}$$