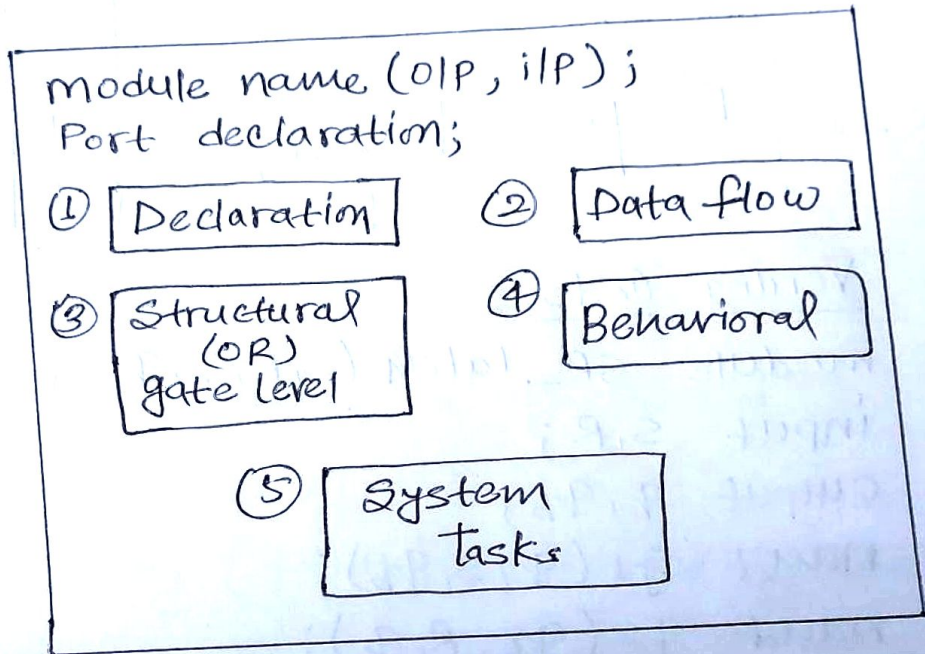


Q1.

What are the components of SR latch? Write Verilog HDL module of SR latch and write test bench to test the SR latch.

Soln:-

Components of SR latch.



→ Declaration:

```
module module_name (input, output);  
input a, b;  
output sum, cout; } - Port declaration.
```

→ Data flow: The model where the keyword 'assign' is used is the data flow.

Ex:- assign sum = i1 & i2;

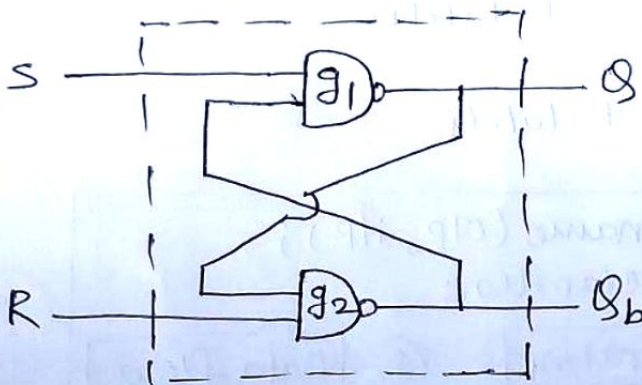
→ Structural/Gate level: Structural model where there is a calling in the main function (block)  
Gate level is gate name a1(a,b,out);

→ Behavioural: The keyword used is @always@(s.r);

→ System task: Where it performs some Routine operations. in simulation displaying, monitoring, stop and finish operation is performed.

SR-latch

Diagram



Truth table

S	R	q	qb
0	0	No change	
0	1	0	1
1	0	1	0
1	1	Toggle.	

Verilog Code :

```
module SR_latch (S,R,q,qb);  
input S,R;  
output q,qb;  
nand g1(q,S,qb);  
nand g2(qb,R,q);  
endmodule
```

Simulation Code / test bench Code

```
module SR_latchtb;  
reg S;  
reg R;
```



```

wire q;
wire qb;
SR-latch mc(q, qb, ~rset, ~rsset);
initial
begin
$monitor ($time " set= %.b, reset= %.b, q= %.b, qb= %.b");
set, re set, q, qb);
set=0; reset=0; #5;
#5; reset=1;
#5; reset=0;
#5; reset=1;
end
endmodule.

```

Q2 What are the uses of \$monitor, \$display & \$finish system tasks? Explain with examples.

Sol<sup>n</sup>: ① \$display:

The task used (or) performed is displaying the values which can be variable/string.

Syntax: \$display.

String by default are displayed in new line for example:

1. \$display ("Hello Verilog World");  
-- Hello verilog world.
2. \$display (\$time); // display the simul  
-- 2:30 // -tion time
3. \$display ("It is a new String \n which has  
%.%. sign");  
-- It is a new String.  
-- Which has %. sign.



## display specification :

- `%b` (or) `%B` → display binary
  - `%d` (or) `%D` → display decimal
  - `%s` (or) `%S` → display String
  - `%t` (or) `%T` → display time
  - `%o` (or) `%O` → display octal.
- `$display` is same as `printf` in C language.

## ② \$monitor :

- operation used to monitor the signal when its value changes is known as monitoring.
- It has two types "\$monitor on" & "\$monitor off"  
Where, `$monitor on` - Enable simulation  
`$monitor off` - disables simulation.
- Syntax is `$monitor`
- `$monitor` performs same as `$display`.

### Example :

```
$monitor ($time, "s = %b, r = %b, q = %b, qb = %b",  
s, r, q, qb);
```

## ③ \$finish :

- It is the operation where it terminates the simulation at a given time delay.
- Syntax: `$finish`

for example : initial  
begin

```
clock = 0;
```

```
reset = 1;
```

```
#100 $stop;
```

```
#900 $finish; // terminates after  
11900 time.
```

```
end.
```







```

fulladd4 fa0 (sum, c-out, a, b, c-in); // instantiation
initial
begin
<module instantiation >
:
end
endmodule.

```

## ② Connecting Port by name :-

- In large design there will be so ports remembering the order of the ports is not easy, which is impractical and Error.
- Verilog provides instead to connecting port in port order in portname.

for example :

```

fulladd4 fa0 (.a(a); .b(b);
               .cin (c-in);
               .c-out (c-out);
               .sum (sum);
               );

```

- make sure that all the external connected ports are connected with all port name.
- If there is any unconnected port in the module definition it can be disconnected. for example.

```

fulladd4 fab(
               .a(a);
               .b(b);
               .cin (cin);
               .sum (sum); // cout is unconnected.
               );

```

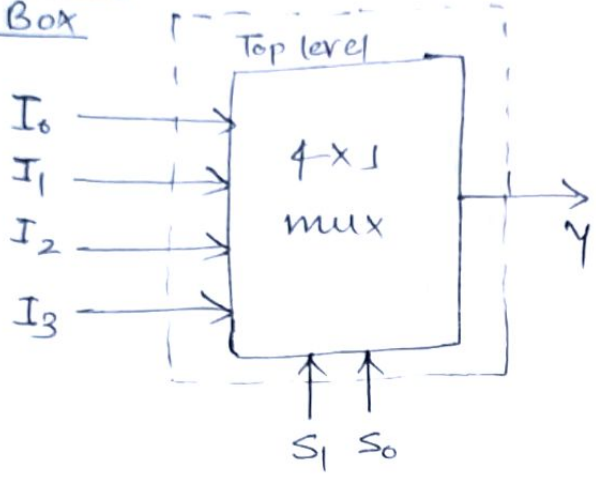


④

Use gate level description of Verilog HDL to design 4 to 1 multiplexer. Write truth table, top-level block, logic expression and logic diagram. Also write the Stimulus block for the same.

Sol<sup>n</sup>:→

Block Box

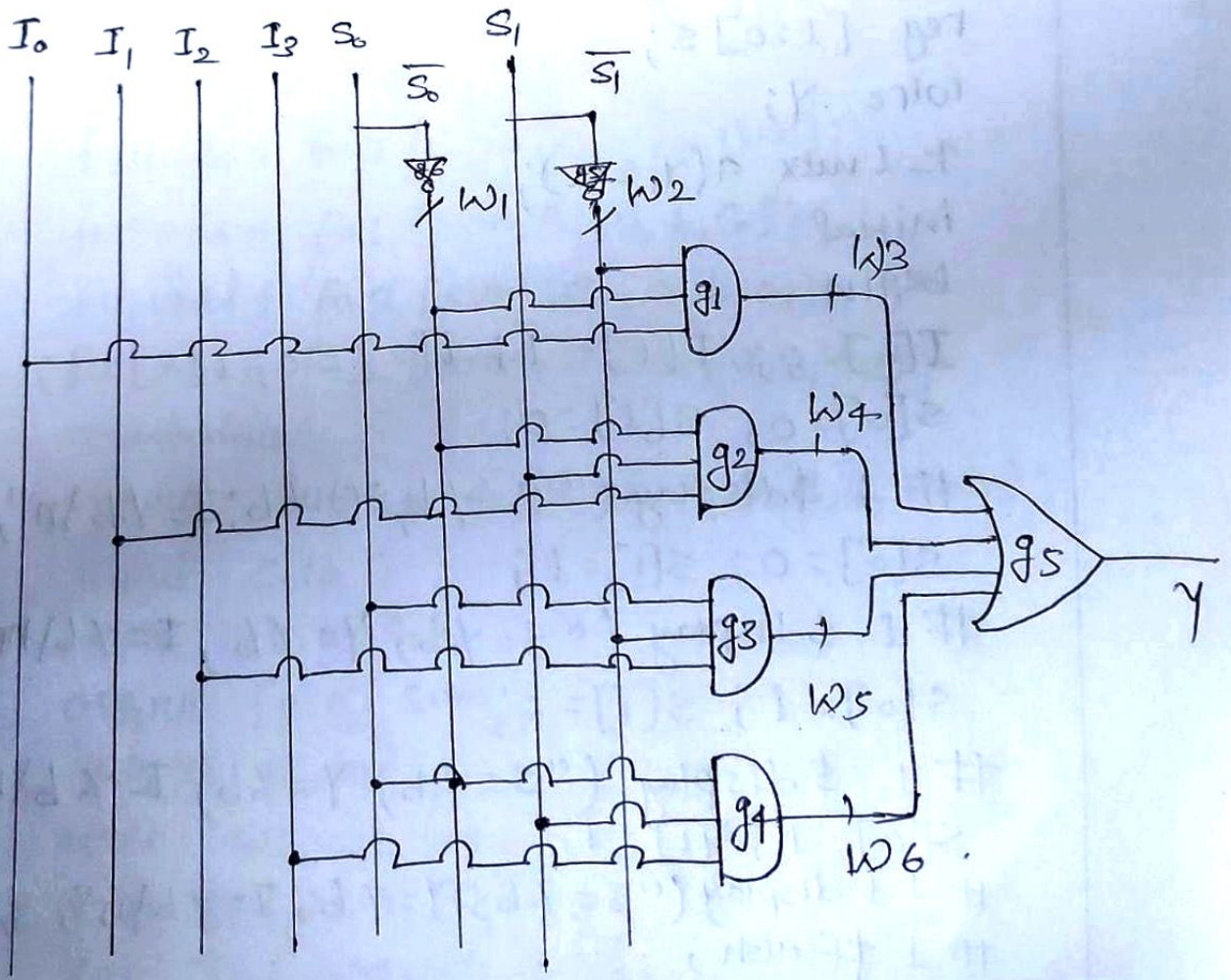


Truth Table

S <sub>0</sub>	S <sub>1</sub>	Y
0	0	I <sub>0</sub>
0	1	I <sub>1</sub>
1	0	I <sub>2</sub>
1	1	I <sub>3</sub>

Logic Expression:  $Y = \bar{S}_0 \bar{S}_1 I_0 + \bar{S}_0 S_1 I_1 + S_0 \bar{S}_1 I_2 + S_0 S_1 I_3$

Logic diagram:





Code:

```
module 4_1Mux (Y, I, S);  
output Y;  
input [3:0] I;  
input [1:0] S;  
wire w1, w2, w3, w4, w5, w6;  
and g1(w3, w2, w1, I[0]);  
and g2(w4, w1, S[1], I[1]);  
and g3(w5, S[0], w2, I[2]);  
and g4(w6, S[1], S[0], I[3]);  
OR g5(Y, w3, w4, w5, w6);  
not g6(w1, S[0]);  
not g7(w2, S[1]);  
endmodule.
```

Stimulus Code:

```
module 4_1muxt6;  
reg [3:0] I;  
reg [1:0] S;  
wire Y;  
4_1mux a(Y, S, I);  
initial  
begin  
I[0]=0; I[1]=1; I[2]=0; I[3]=1;  
S[0]=0; S[1]=0;  
# 1 $display ("S=%b, Y=%b; I=%b\n", S, I, Y);  
S[0]=0; S[1]=1;  
# 1 $display ("S=%b; Y=%b; I=%b\n", S, Y, I);  
S[0]=1; S[1]=0;  
# 1 $display ("S=%b; Y=%b; I=%b\n", S, Y, I);  
S[0]=1; S[1]=1;  
# 1 $display ("S=%b; Y=%b; I=%b\n", S, Y, I);  
# 1 $finish;  
end  
endmodule
```

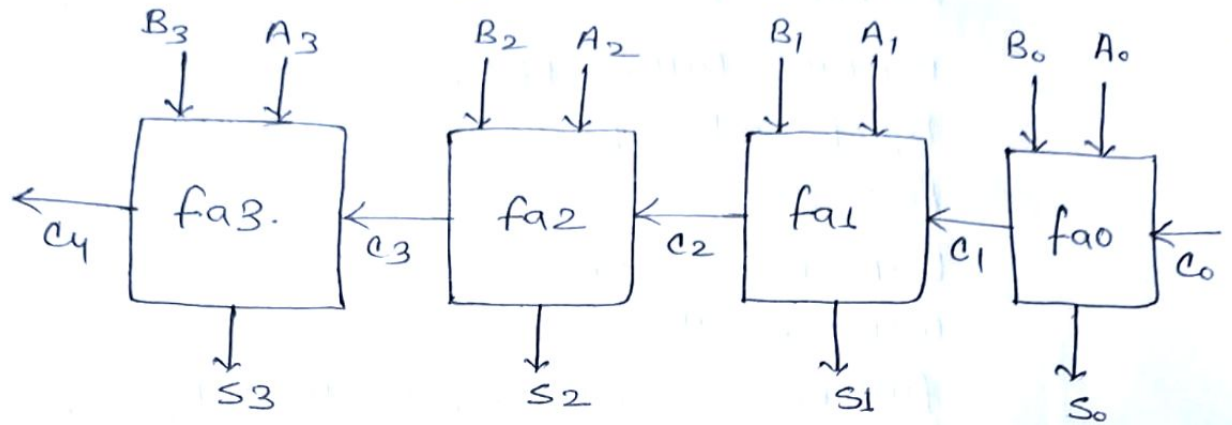


5

Use gate level description of Verilog HDL to describe the 4-bit ripple carry adder. Also write a stimulus block for 4-bit ripple carry adder

Soln:→

4-bit ripple carry adder:



Verilog Code : (gate level);

```
module 4-bit-ripple-carry-adder(sum, c-out, a, b, c-in)
input [3:0] a, b;
input c-in;
output [3:0] sum;
output c-out;
fulladd4 fa0 (sum, c0, a, b, c-in);
fulladd4 fa1 (sum, c1, a, b, c0);
fulladd4 fa2 (sum, c2, a, b, c1);
fulladd4 fa3 (sum, c-out, a, b, c2);
endmodule.

module fulladd4 (sum, c-out, a, b, c-in);
input c-in;
input [3:0] a, b;
output [3:0] sum;
output c-out;
wire w1, w2, w3;
xor g1 (w1, a, b);
xor g2 (sum, w1, c-in);
```



```

and g3 (w2, a, b);
and g4 (w2, w1, cin);
or g5 (c-out, w2, w3);
endmodule

```

Stimulus Code:

```

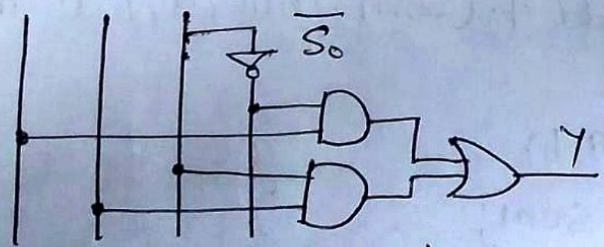
module fulladd4bt;
reg [3:0] a, b;
reg cin;
wire [3:0] sum;
wire c-out;
fulladd4 fab (sum, c-out, a, b, cin);
initial
begin
$monitor ($time, "a = %b b = %b, c-in = %b, sum = %b,
c-out = %b\n", a, b, cin, sum, c-out);
#5; a = 4'b0000; b = 4'b0; c = 1'b0;
#5; a = 4'b0001; b = 4'b0000; c = 1'b1;
...
#5; $finish
end
endmodule

```

Q6

Given: 2x1 mux using bufifo & bufifl.

$I_0, I_1, S_0$



T.T

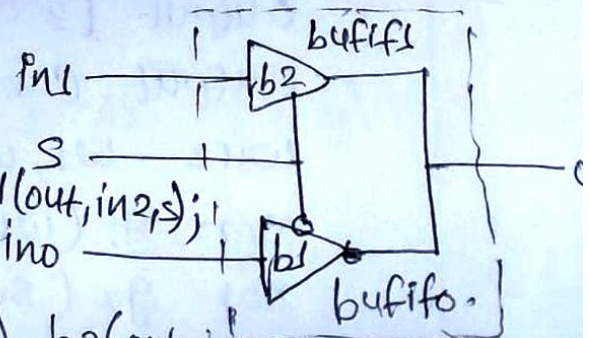
$S_0$	$Y$
0	$I_0$
1	$I_1$

Exp:  $Y = \bar{S}_0 I_0 + S_0 I_1$

```

module 2-1mux (I, Y, S);
input [1:0] I; inp = S; outp = Y;
bufifo # (1:2:3, 3:4:5, 5:6:7); b1(out, in2, s);

```



```

bufifo # (1:2:3, 3:4:8, 5:6:7) b2(out, in1, s); endmodule

```



⑦

With Syntax describe the continuous assignment statement. Show how different delays associated with logic circuit are modelled using dataflow description.

Soln:-

Continuous assignment statement

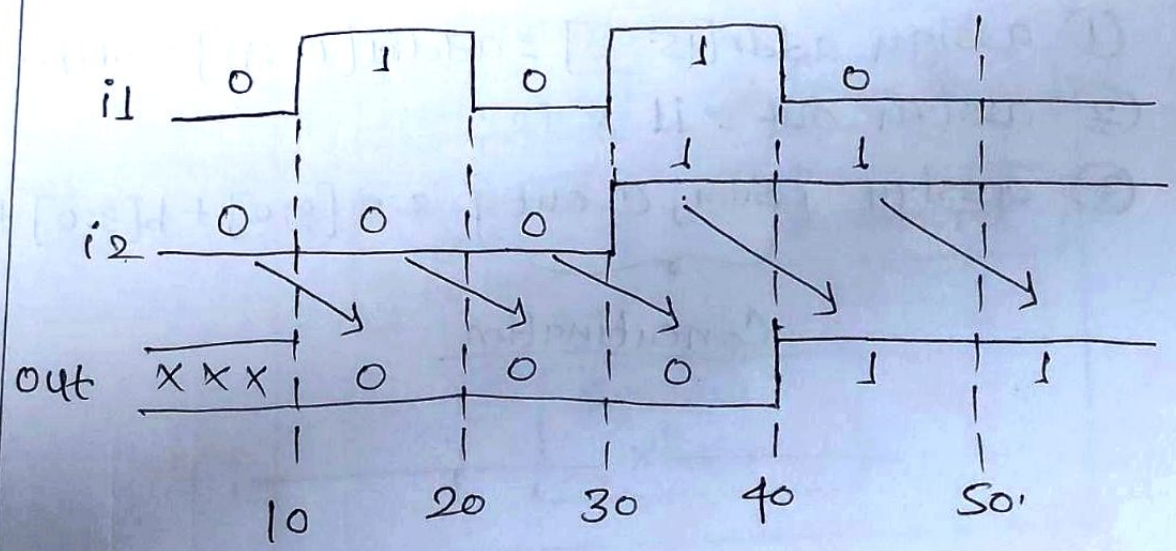
Continuous\_assignment ::= assign #to.  
Continuous\_net\_of\_assignment  
net\_of\_assign.

Delay associated with continuous assignment are:

- ① Regular Continuous assignment
- ② Implicit Continuous assignment
- ③ Net declaration.

① Regular Continuous assignment:

- The first method used to specify particular delay in Continuous assignment.
- The delay is specified after the assign statement.
- When the value of i1 & i2 varies there is lot of time delay for every before commutation of i1 & i2.
- Initial delay is formed.



- for example :
- 1. assign #10 out = i1 & i2;
  - 2. assign #20 sum = i1 ^ i2;



## ② Implicit Continuous assignment

- It is same as continuous assignment.

Ex: wire out;  
assign out = i1 & i2;

## ③ Net Declaration

- which can be used in gate level modeling.

- When there is declaration or "net",

### Characteristic of Continuous assignment

- The LHS of continuous assignment scalar (or) vector 'NET' / concatenation of both are scalar/vector "NETS" it can't be scalar/vector register.
- RHS of the continuous assignment operators is can be found only when the values of RHS operand changes.
- RHS operands can be NETs / Register / etc.

Ex:

- ① assign  $addr[15:0] = addr_1[15:0] + addr_2[15:0];$
- ② assign  $out = i1 \& i2;$
- ③ assign  $\{sum, c\_out\} = a[3:0] + b[3:0] + c\_in;$

Concatenation

x