

All the Best Hard Work Never Fails*** ANSWER

Solution to question paper 1

$Q1$ AND $Q2$

- 1. b. Explain the limitations in design of electrical machines.
- (08 Marks) Ans: Apart from the availability of suitable materials, facilities available for manufacture of required machine parts and facilities required for transportation, the following considerations impose limitation on design.
	- Saturation : Electromagnetic machines use ferro magnetic materials. The 1. maximum allowable flux density to be used is determined by the saturation level of the ferro - magnetic material used. A high value of flux density results in increased excitation resulting in higher cost for the field system.
	- Temperature rise : The operating life of a machine depends upon the type of $2.$ insulating materials used an the life of the insulating material in turn depends upon temperature rise of the machine. If an insulating material is operated beyond the maximum allowable temperature, its life is drastically reduced.
	- Insulation : The insulating used in the machine should be able to withstand in $3.$ electrical, mechanical, and thermal stresses which are produced in the machine Therefore, while designing the insulation, due consideration must be given a the capability of the insulation to withstand large mechanical stresses that are produced under short circuit conditions. The type of insulation is decided by the maximum operating temperature of the machine parts where it is put. The sized

- Efficiency: The efficiency should be as high as possible to reduce the operating 4. costs. In order to design a highly efficient machine, the magnetic loading used should be small and this requires the use of large amount of material. Therefore, the capital cost of a machine designed for high efficiency is high while its running cost is low.
- Mechanical parts: The size of the shaft should be such that it does not give rise 5. to excessive unbalanced magnetic pull when deflected. In large machines, the size of the shaft is decided by considering the critical speed which depends on the deflection of the shaft. Bearing of rotating machines are subjected to the action of rotor weight, external loads, inertia forces due to unbalanced rotors and forces on account of unbalanced magnetic pull. The type of bearings to be used is decided by considering the above mentioned forces and also the type of construction whether the machine is horizontally or vertically mounted.
- **Commutation :** The commutation conditions limit the maximum output that can 6. be taken from a machine.
- 7. Power factor : Poor Power factor results in larger values of current for the power and, therefore, larger conductor sizes have to be used. The size and cost of an induction motor can be reduced by using a high value of flux density in air gap but these results in saturation in iron the parts of machine and consequently a poor power factor. Thus the value of flux density depends upon the power factor and hence power factor becomes a limiting factor.
- Consumer's specifications: The specifications as laid down in the consumer's order have to be met and the design evolved should be such that it satisfies all the specifications and also the economic constraints imposed on the manufacture.

Standard specifications : These specification are the biggest strain on the design because both the manufactures as well as the consumer cannot get away from them without satisfying them. 0.435

insulation is decided by the maximum voltage stress and the mechanical stresses produces.

Derive the output equation of a 3 phase core type transformer and also deflue an expression for EMF per turn.

OUTPUT EQUATION:
In the case of 3- ϕ transformer, there are two windows Each window comains the
19 and 38 window of two phases (window 1 – R & V; window 2 – Y & B) = Each **M: OUTPUT EQUATION:** In the case of 3- ϕ transformer, there are two windows Each window 2 – Y & B) is Each
Iⁿ and 2° windings of two phases (window 1 – R & V, window 2 – Y & B) is Each
Window ¹⁶ and 2⁶ windings of two phases (window) windings windings Total cu area in each window, $A_c = 2a_pT_a + 2a_sT_s$ **From Scon**

Q3

$$
\therefore Q = 4.44f \phi_{m} AT \times 10
$$

3.

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Electri

 \mathbb{Q}_1

$$
= 2 \times \frac{I_y T_y}{\delta} + 2 \times \frac{I_x}{\delta} T_x
$$

$$
= \frac{2}{\delta} \Big[I_y T_y + I_x T_x \Big]
$$

$$
A_z = \frac{4 \Delta T}{\delta}
$$

As $I_pT_p = I_iT_i = AT$ if we neglect magnetizing mmf

Also, we have
$$
k_w = \frac{A_c}{A_w}
$$

 $Ac = A_{\nu}K_{\nu}$ Comparing eqns (1) & (2),

$$
\frac{4AT}{\delta} = A_w K_w
$$

$$
AT = \frac{\delta A_w K_w}{}
$$

 \overline{A}

34

KVA rating of a $3-\phi$ transformer,

$$
Q = 3V_p I_p \times 10^{-3} = 3 E_p I_p \times 10^{-3}
$$

= 3E_iT_pI_p × 10⁻³ = 3E_t × AT × 10⁻³
= 3 × 4.44 + $\phi_m \times \frac{\delta A_w K_w}{4} \times 10^{-3}$
= 3.33 f B_m A_i $\delta A_w k_w \times 10^{-3}$
 $Q = 3.33 f B_m S K_w A_w A_i \times 10^{-3}$ KVA

EMF per turn:

Consider the output of one phase i, KVA/phase = Q The KVA rating per phase of a $3-\phi$ transformer is, $Q = V_p I_p \times 10^{-3} = E_p I_p \times 10^{-3} = E_t T_p I_p \times 10^{-3}$
= 4.44f $\phi_m T_p I_p \times 10^{-3}$ The ratio ϕ m/AT is a constant for a transformer of a given type.

Let $\frac{\phi_m}{AT} = r$ where r is a constant \therefore Q = 4.44f ϕ_m AT × 10⁻³

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 $Q6,$

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Using the same stepped cross section for the yoke as that of core, pepth of yoke, $D_y = a = 0.727$ m Height of yoke, $H_y = a = 0.272$ m Overall height of frame, $H = H_w + 2H_v$ $= 0.26 + (2 \times 0.272)$ $H = 0.804$ m Overall length of frame, $W = D + a$ $= 0.435 + 0.272$ $W = 0.707$ m

La. Compute the active and reactive components of no load current of 50 Hz, 1φ core type transformer with the following particulars: Mean length of magnetic path = 300 cm Gross cross sectional area $= 150$ cm² Maximum flux density = 1.5 Tesla Specific core loss $= 2.5$ watts/kg Ampere turns/cm at 1.15 Tesla = 7.0 Specific gravity of core material = 7.5 gm/cm³ The effect of joints is equivalent to an air gap of 1 mm in the ma that of each of the side limbs

3. b. Define iron space factor.
Ams: Iron space factor (k) is defined as the ratio of net core area and $\frac{8r_{O_{80}}}{6r_{O_{80}}}\cos\left(\frac{9r_{O_{80}}}{6r_{O_{80}}}\right)$

$$
K_{1} = \frac{Net\,core\,area}{Gross\,core\,area}
$$

 A_{μ}
3. c. Determine the dimensions of core and yoke for a 200 kVA, 50 Hz, 1 phase one of the dimensions of core is used with distance between adjacent links one. Determine the dimensions of core and with distance between adjacent links one transformer. A cruciform core is used with distance between adjacent links one transformer. A cruciform core laminations. Assume voltage per tu Determined A cruciform core is used one. Assume voltage per turn ≈ 14 V_n by and 1.6 times the width of core laminations. Assume voltage per turn ≈ 14 V_n by and 1.6 times the width of core laminations space facto transformer.

1.6 times the width of core lamination space factor = 0.32, current density based

flux density = 1.1 Wb/m², window space factor = 0.32, current density based

The net iron area is 0.56 d², where d is the diameter of circumscribing $\frac{\Delta t}{\Delta t}$
The net iron area is 0.56 d², where d is the diameter of circumscribing $\frac{\Delta t}{\Delta t}$ the width of the largest stamping is 0.85 d. Assume CRGO steel, $(12 M_{\odot})$ Ans: Voltage per turn, $Et = 4.44fB_mA$

ntral limb

A.

$$
A_{i} = \frac{Et}{4.44tBm}
$$

= $\frac{14}{4.44 \times 50 \times 1.1}$

$$
A_{i} = 0.057 m^{2}
$$

Given net iron area, $A_i = 0.56d^2$ i, $0.057 = 0.56 d^2$

 $d = 0.32m$ For cruciform core, $a = 0.85d = 0.85 \times 0.32$ $a = 0.272m$

Given, $D = 1.6$ a = 1.6×0.272 $D = 0.435m$

Width of the window, $W_w = D - d$

$$
= 0.435 - 0.32
$$

$$
= 0.115 \text{m}
$$

We know, $Q = 2.22f B_m K_w A_w A i \delta \times 10^{-3}$ $200 = 2.22 \times 50 \times 1.1 \times 0.32 \times A_w \times 0.057 \times 3 \times 10^6 \times 10^{3}$ \Rightarrow A_{ω} = 0.0298 m² Also, $A_w = H_w K_w \Rightarrow H_w = \frac{A_w}{W_w} = \frac{0.0298}{0.115}$ $H_w = 0.26m$

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