

# CBCS SCHEME

18ME732

USN

--	--	--	--	--	--	--	--	--	--

Seventh Semester B.E. Degree Examination, July/August 2022

## Automation and Robotics

Time: 3 hrs.

Max. Marks: 100

*Note: Answer any FIVE full questions, choosing ONE full question from each module.*

### Module-1

- 1 a. What is Automation? Explain the basic elements of an automated system. (06 Marks)
- b. What is the difference between a closed loop control system and an open loop control system? (06 Marks)
- c. Briefly explain the advanced automation functions. (03 Marks)
- d. Briefly explain five levels of automation. (05 Marks)

OR

- 2 a. What is the difference between a continuous control system and a discrete control system? (06 Marks)
- b. What is Sensors? Explain analog and discrete measuring device. (06 Marks)
- c. Explain with block diagram analog to digital converters. (08 Marks)

### Module-2

- 3 a. With sketch explain the types of flow line configurations. (12 Marks)
- b. Write a short note on buffer storage. (05 Marks)
- c. Explain the three control functions of the automate production line. (03 Marks)

OR

- 4 a. A ten station transfer machine has an ideal cycle time of 30 sec. The frequency of line stops is  $F = 0.075$  stops/cycle. When a line stop occurs, the average down time is 4.0min. The cost of raw work part is Rs.0.55/pc, line operating cost is Rs.42.00/hr and cost of disposable tooling is Rs.0.27/pc. Determine:
  - i) Average production rate in pc/hr.
  - ii) Line efficiency
  - iii) Proportion down time
  - iv) The average cost of work piece produced. (09 Marks)
- b. Write a short note on automatic identification methods. (06 Marks)
- c. Explain in briefly magnetic stripes, optical character recognition and machine vision. (05 Marks)

### Module-3

- 5 a. What is Industrial Robotics? Explain with neat sketch Robotic configuration. (10 Marks)
- b. Explain with sketch six degrees of freedom in Robotics. (10 Marks)

OR

- 6 a. What are the Industrial Robot applications? (08 Marks)
- b. What is End effectors? Briefly explain the type of End-Effectors. (06 Marks)
- c. Explain with sketch Robot Accuracy and Repeatability. (06 Marks)

**Module-4**

- 7 a. Explain with sketch hydraulic system for Robot. (08 Marks)  
b. What are the characteristics of pneumatic actuators used in Robotics? (06 Marks)  
c. Write a short note on servo motor and stepper motor. (06 Marks)

OR

- 8 a. What is Homogeneous Transformation? Explain. (08 Marks)  
b. Explain for the Denavit Hartenberg (D-H) representation of robot. (12 Marks)

**Module-5**

- 9 a. Explain in levels of Robot programming. (09 Marks)  
b. What are the requirements of a robot programming language? (05 Marks)  
c. What are problems pertaining to robot programming languages? (06 Marks)

OR

- 10 a. Explain off-line programming systems. (08 Marks)  
b. Explain in central issues in OLP systems. (12 Marks)

CMRIT LIBRARY  
BANGALORE - 560 037

\*\*\*\*\*