



CBGS SCHEME

--	--	--	--	--	--	--	--	--	--

15ME73

Seventh Semester B.E. Degree Examination, Jan./Feb. 2023 Control Engineering

Time: 3 hrs.

Max. Marks: 80

Note: Answer any FIVE full questions, choosing ONE full question from each module.

Module-1

- 1 a. Compare open loop and closed loop control system with example. (08 Marks)
b. Explain basic structure of a feedback control system with a suitable example and block diagram. (08 Marks)

OR

- 2 a. Explain the ideal requirements of control system with example. (06 Marks)
b. What is controller? Compare PI, PD and PID controllers, with block diagram and relevant characteristics equation. (10 Marks)

Module-2

- 3 a. Determine system equation of the system shown in Fig.Q.3(a) and draw force-voltage analogy. (08 Marks)

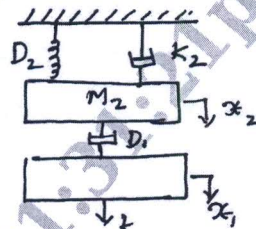


Fig.Q.3(a)

- b. A thermometer is dipped in a vessel containing liquid at a constant temperature of θ_1 . thermometer has a thermal capacitance for storing heat as C and thermal resistance to limit heat flow as R . If the temperature indicated by thermometer is θ_r , obtain the transfer function of the system. (08 Marks)

OR

- 4 a. Determine the transfer function of the system by block diagram reduction technique. (08 Marks)

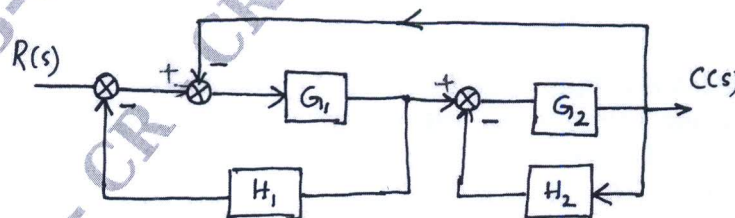


Fig.Q.4(a)

Important Note : 1. On completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages.
2. Any revealing of identification, appeal to evaluator and /or equations written eg. 42+8 = 50, will be treated as malpractice.

- b. Determine the transfer function of the system by Mason's gain formula. (08 Marks)

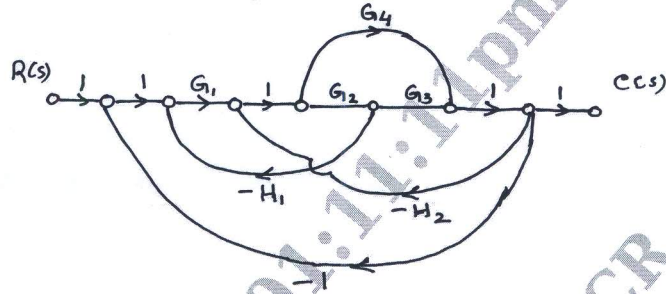


Fig. Q.4(b)

Module-3

- 5 a. Examine the stability of the system represented by the characteristic equation $2s^4 + 10s^3 + 2s^2 + 5s + k = 0$. Using RH criterion. Suggest the range of K for the system to be stable. (08 Marks)
- b. Derive the governing expression for the first order system subjected to unit step response. (06 Marks)
- c. Explain the transient response characteristics of a control system to a unit step input. (02 Marks)

OR

- 6 A negative feedback control system is characterized by $G(s)H(s) = \frac{K}{s(s+1)(s+2)(s+3)}$. Generate the root locus plot for values of K ranging from 0 to ∞ . (16 Marks)

Module-4

- 7 Sketch the Bode plot for a unit feedback system with $G(S) = \frac{242(S+5)}{S(S+1)(S^2+5S+121)}$ and comment on stability. (16 Marks)

OR

- 8 Draw the Nyquist plot for a system with $G(S)H(S) = \frac{K}{S(S+1)(S+2)}$ and find the range of values of K for stability. (16 Marks)

Module-5

- 9 a. Explain series and feedback compensation of a system with a diagram. (08 Marks)
- b. Explain lag compensator and lead compensator with a diagram. (08 Marks)

OR

- 10 a. Explain in brief controllability and observability. (10 Marks)
- b. Using Kalman's test determine whether the system represented by following state matrix is controllable or not.

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u \quad \text{and} \quad C = [1 \quad 1] x. \quad (06 \text{ Marks})$$
