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INTERNAL ASSESSMENT TEST – III

Sub:	SIGNALS AND SYSTEMS										Code:	18EC45
Date:	29 / 08 / 2022	Duration:	90 mins	Max Marks:	50	Sem:	IV	Branch:	ECE			

Answer any 5 full questions

		Marks	CO
1	Investigate the Causality, Stability and Memoryless properties of the following LTI Systems (i) $h(n) = 2\delta(n) - 3\delta(n-2) + 4\delta(n-3)$ (ii) $h(t) = e^{-t}u(t+100)$	[10]	CO2
2	Prove i) $x(n)*\{h_1(n)+h_2(n)\}=x(n)*h_1(n)+x(n)*h_2(n)$, ii) $x(t)*h(t)=h(t)*x(t)$.	[10]	CO3
3	Obtain the Fourier transform of the following signals. (i) $x(t) = 1$ for $-a \leq t \leq a$ (ii) $x(t) = e^{-2t}u(t-1)$	[10]	CO4
4	Obtain the DTFT of the following signal. (i) $x(n) = a^{ n }$ $ a < 1$ (ii) $x(n) = \cos(\pi n) \left(\frac{1}{4}\right)^n u(n)$	[10]	CO4

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5	<p>Find Inverse FT of the following</p> <p>(i) $X(j\omega) = \frac{j\omega}{6 + 7j\omega - \omega^2}$</p> <p>(ii) $X(j\omega) = \frac{5j\omega - 9 - 2\omega^2}{(j\omega + 4)(3 + 4j\omega - \omega^2)}$</p>	[10]	CO4	L1,L3
6	<p>Find Inverse DTFT of the following</p> <p>(i) $X(e^{j\Omega}) = \frac{3 - \frac{1}{4}e^{-j\Omega}}{1 - \frac{1}{16}e^{-2j\Omega}}$</p> <p>(ii) $X(e^{j\Omega}) = \frac{30 - 5e^{-j\Omega}}{-e^{-2j\Omega} - e^{-j\Omega} + 6}$</p>	[10]	CO4	L1,L3
7	<p>i) State and prove the time scaling property for FT.</p> <p>ii) State and prove the differentiation (Multiplication by ramp) property for DTFT.</p>	[10]	CO4	L1
8	<p>Determine the impulse response of the system described by</p> $\frac{d^2y(t)}{dt} + 5\frac{dy(t)}{dt} + 6y(t) = -\frac{dx(t)}{dt}$	[10]	CO2	L3

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1. a) $h(n) = 2\delta(n) - 3\delta(n - 2) + 4\delta(n - 3)$

$$\therefore h(n) = \left\{ \begin{matrix} 2, 0, -3, 4 \\ \uparrow \end{matrix} \right\}$$

- It's a R.H.S. sequence so causal. (2M)
- Exists for $n \neq 0$ so has memory(dynamic) (1M)
- $\sum_{n=0}^3 |h(n)| = 2 + 3 + 4 = 9 < \infty$, So stable. (2M)

b) . d) $h(t) = e^{-t}u(t + 100)$

$$h(t) = \begin{cases} e^{-t} & \text{for } t \geq -100 \\ 0 & \text{for } t < -100 \end{cases}$$

- It's double sided signal so not causal. (2M)
- Exists for $t \neq 0$ so has memory(dynamic) (1M)
- $\int_{-100}^{\infty} |e^{-t}| dt = e^{-t} \Big|_{-100}^{\infty} = e^{100} < \infty$, So stable. (2M)

2. We write $h(t) = h_1(t) * h_2(t)$ (2M)

$$h(t) = \int_{-\infty}^{\infty} h_1(\tau)h_2(t - \tau)d\tau$$

Perform the change of variable,

$$\begin{aligned} v &= t - \tau \\ dv &= -d\tau \\ &= - \int_{-\infty}^{\infty} h_1(t - v)h_2(v)dv \\ &= \int_{\infty}^{-\infty} h_1(t - v)h_2(v)dv \\ &= \int_{-\infty}^{\infty} h_2(v)h_1(t - v) dv \end{aligned}$$

$$= h_2(t) * h_1(t) \text{ (3M)}$$

ii) Statement (2M)

Proof (3M)

3. i). $x(t) = 1$ for $-a \leq t \leq a$ (5M)

$$\therefore X(j\omega) = \int_{-a}^a 1 \cdot e^{-j\omega t} dt$$

Now by definition of FT

$$\begin{aligned} (j\omega) &= \frac{e^{-j\omega t}}{-j\omega} \Big|_{-a}^a \\ X(j\omega) &= \frac{e^{-ja\omega}}{-j\omega} - \frac{e^{ja\omega}}{-j\omega} \\ &= \frac{2}{\omega} \sin a\omega \end{aligned}$$

For $\omega=0$ use L'Hopital's rule

ii) $x(t) = e^{-2t}u(t - 1)$ (5M)

$$\therefore x(t) = \begin{cases} e^{-2t} & \text{for } t \geq 1 \\ 0 & \text{for } t < 1 \end{cases}$$

Now by definition of FT

$$\begin{aligned} X(j\omega) &= \int_1^{\infty} e^{-2t} e^{-j\omega t} dt = \int_1^{\infty} e^{-(2+j\omega)t} dt \\ &= \frac{e^{-t(2+j\omega)}}{-(2+j\omega)} \Big|_1^{\infty} \\ \therefore X(j\omega) &= \frac{e^{-(2+j\omega)}}{(2+j\omega)} \end{aligned}$$

4. i) $x[n] = a^{|n|}$, $|a| < 1$ (5M)

$$x[n] = \begin{cases} a^n, & n \geq 0 \\ a^{-n}, & n < 0 \end{cases}$$

We have the DTFT as

$$\begin{aligned} X(e^{j\Omega}) &= \sum_{n=-\infty}^{\infty} x[n] e^{-j\Omega n} \\ &= \sum_{n=-\infty}^{-1} x[n] e^{-j\Omega n} + \sum_{n=0}^{\infty} x[n] e^{-j\Omega n} \\ &= \sum_{n=-\infty}^{-1} a^{-n} e^{-j\Omega n} + \sum_{n=0}^{\infty} a^n e^{-j\Omega n} \\ &= \sum_{n=-\infty}^{-1} (ae^{j\Omega})^{-n} + \sum_{n=0}^{\infty} (ae^{-j\Omega})^n \\ &= \sum_{m=1}^{\infty} (ae^{j\Omega})^m + \sum_{n=0}^{\infty} (ae^{-j\Omega})^n \end{aligned}$$

In first summation,

$$\begin{aligned} m &= -n \\ n &= -\infty, m = \infty, \\ n &= -1, m = 1, \\ &= \sum_{m=1}^{\infty} (ae^{j\Omega})^m + \sum_{n=0}^{\infty} (ae^{-j\Omega})^n \\ &= \frac{ae^{j\Omega}}{1 - ae^{j\Omega}} + \frac{1}{1 - ae^{-j\Omega}} \\ &= \frac{ae^{j\Omega}(1 - ae^{-j\Omega}) + (1 - ae^{j\Omega})}{(1 - ae^{j\Omega})(1 - ae^{-j\Omega})} \\ &= \frac{ae^{j\Omega} - a^2 + 1 - ae^{j\Omega}}{1 - a(e^{j\Omega} + e^{-j\Omega}) + a^2} \\ &= \frac{1 - a^2}{1 - 2a \cos \Omega + a^2} \\ X(e^{j\Omega}) &= \frac{1 - a^2}{1 - 2a \cos \Omega + a^2} \end{aligned}$$

ii) Find FT of signal $x(n) = \cos(\pi n) \left(\frac{1}{4}\right)^n u(n)$ (5M)

As we know that $\cos(\pi n) = (-1)^n$

$$\therefore x(n) = (-1)^n \left(\frac{1}{4}\right)^n u(n)$$

Rewrite as: $x(n) = \left(-\frac{1}{4}\right)^n u(n)$

We know that $\left(\frac{1}{4}\right)^n u(n) \xleftrightarrow{DTFT} \frac{1}{1 - \frac{1}{4}e^{-j\Omega}}$

$$\therefore \left(-\frac{1}{4}\right)^n u(n) \xleftrightarrow{DTFT} \frac{1}{1 + \frac{1}{4}e^{-j\Omega}}$$

$$5. \quad X(j\omega) = \frac{(j\omega)}{(6+7(j\omega)-\omega^2)} \quad (5M)$$

Replace variable $j\omega$ with v

$$X(v) = \frac{(v)}{(v^2+7v+6)}$$

$$A = \frac{(v)}{(v+1)} \Big|_{v=-6} = \frac{6}{5}$$

$$\therefore B = \frac{(v)}{(v+6)} \Big|_{v=-1} = \frac{-1}{5}$$

$$\therefore X(v) = \frac{6/5}{(v+6)} - \frac{1/5}{(v+1)}$$

$$= \frac{(v)}{(v+6)(v+1)}$$

$$= \frac{A}{(v+6)} + \frac{B}{(v+1)}$$

Replace back variable v with $j\omega$

$$\therefore X(j\omega) = \frac{6/5}{(j\omega+6)} - \frac{1/5}{(j\omega+1)}$$

$$\frac{1/5}{(j\omega+1)} \xleftrightarrow{FT} \frac{1}{5} e^{-t} u(t)$$

$$\frac{6/5}{(j\omega+6)} \xleftrightarrow{FT} \frac{6}{5} e^{-6t} u(t)$$

$$\therefore x(t) = \frac{6}{5} e^{-6t} u(t) - \frac{1}{5} e^{-t} u(t)$$

$$\text{ii) } X(j\omega) = \frac{5((j\omega)+1)}{(j\omega)^2+5(j\omega)+6} \quad (5M)$$

Replace variable $j\omega$ with v

$$X(v) = \frac{5(v+1)}{v^2+5v+6}$$

$$\therefore X(v) = \frac{5(v+1)}{(v+2)(v+3)}$$

$$\therefore X(v) = \frac{A}{(v+2)} + \frac{B}{(v+3)}$$

$$\therefore A = \frac{5(v+1)}{(v+3)} \Big|_{v=-2} = \frac{5(-2+1)}{(-2+3)} = -5$$

$$\therefore B = \frac{5(v+1)}{(v+2)} \Big|_{v=-3} = \frac{5(-3+1)}{(-3+2)} = 10$$

$$\therefore X(v) = \frac{-5}{(v+2)} + \frac{10}{(v+3)}$$

Replace back variable v with $j\omega$

$$\therefore X(j\omega) = \frac{-5}{(j\omega+2)} + \frac{10}{(j\omega+3)}$$

$$\frac{-5}{(j\omega+2)} \xleftrightarrow{IFT} -5e^{-2t}u(t)$$

$$\frac{10}{(j\omega+3)} \xleftrightarrow{IFT} 10e^{-3t}u(t)$$

AND

$$\therefore x(t) = -5e^{-2t}u(t) + 10e^{-3t}u(t)$$

$$6. \text{ i) b) } X(\Omega) = \frac{3 - \frac{1}{4}e^{-j\Omega}}{\left(1 - \frac{1}{16}e^{-j2\Omega}\right)} \quad (5M)$$

Replace variable $e^{-j\Omega}$ with v

$$X(v) = \frac{3 - \frac{1}{4}v}{\left(1 - \frac{1}{16}v^2\right)}$$

$$= \frac{3 - \frac{1}{4}v}{\left(1 - \frac{1}{4}v\right)\left(1 + \frac{1}{4}v\right)}$$

$$= \frac{A}{1 - \frac{1}{4}v} + \frac{B}{1 + \frac{1}{4}v}$$

$$\therefore A = \frac{\left(3 - \frac{1}{4}v\right)}{\left(1 + \frac{1}{4}v\right)} \Big|_{v=4} = \frac{3-1}{1+1} = 1$$

$$\therefore B = \frac{\left(3 - \frac{1}{4}v\right)}{\left(1 - \frac{1}{4}v\right)} \Big|_{v=-4} = \frac{3+1}{1+1} = 2$$

$$\therefore X(v) = \frac{1}{1 - \frac{1}{4}v} + \frac{2}{1 + \frac{1}{4}v}$$

$$\therefore X(e^{-j\Omega}) = \frac{1}{1 - \frac{1}{4}e^{-j\Omega}} + \frac{2}{1 + \frac{1}{4}e^{-j\Omega}}$$

Replace back variable v with $e^{-j\Omega}$

$$\frac{1}{1 - \frac{1}{4}e^{-j\Omega}} \xleftrightarrow{IFT} \left(\frac{1}{4}\right)^n u(n)$$

$$\frac{2}{1 + \frac{1}{4}e^{-j\Omega}} \xrightarrow{IFT} 2 \left(-\frac{1}{4}\right)^n u(n)$$

$$\therefore x(n) = \left(\frac{1}{4}\right)^n u(n) + 2 \left(-\frac{1}{4}\right)^n u(n)$$

7. i) Consider the effect of scaling the time variable on the frequency domain representation of a signal. (2M)

Let $z(t) = x(at)$, where a is a constant

$$\begin{aligned} Z(j\omega) &= \int_{-\infty}^{\infty} z(t)e^{-j\omega t} dt \\ &= \int_{-\infty}^{\infty} x(at)e^{-j\omega t} dt \end{aligned}$$

Change the variable $\tau = at$

$$\begin{aligned} Z(j\omega) &= \frac{1}{a} \int_{-\infty}^{\infty} x(\tau)e^{-j\left(\frac{\omega}{a}\right)\tau} d\tau, \quad a > 0 \\ &= \frac{1}{a} \int_{-\infty}^{\infty} x(\tau)e^{-j\left(\frac{\omega}{a}\right)\tau} d\tau, \quad a < 0 \end{aligned}$$

These two integrals may be combined into single integral (3M)

$$Z(j\omega) = \frac{1}{|a|} \int_{-\infty}^{\infty} x(\tau)e^{-j\left(\frac{\omega}{a}\right)\tau} d\tau, \quad a < 0$$

$$z(t) = x(at) \leftrightarrow \frac{1}{|a|} X\left(j\left(\frac{\omega}{a}\right)\right)$$

ii) Statement-2M

Proof-3M

8. $\frac{d^2y(t)}{dt^2} + 5\frac{dy(t)}{dt} + 6y(t) = -\frac{dx(t)}{dt}$

Take FT on both sides

$$(j\omega)^2 Y(j\omega) + 5j\omega Y(j\omega) + 6Y(j\omega) = -j\omega X(j\omega) \quad (2M)$$

$$H(j\omega) = \frac{-j\omega}{(j\omega)^2 + 5j\omega + 6}$$

Substitute $j\omega = v$

$$\begin{aligned} H(v) &= \frac{-v}{(v)^2 + 5v + 6} \\ &= \frac{-v}{(v+2)(v+3)} \end{aligned}$$

$$= \frac{K_1}{(v+2)} + \frac{K_2}{(v+3)}$$

On solving $K_1 = 2$ and $K_2 = -3$

$$H(j\omega) = \frac{2}{(j\omega+2)} - \frac{3}{(j\omega+3)} \quad (4M)$$

$$\text{Hence } x(t) = 2e^{-2t}u(t) - 3e^{-3t}u(t) \quad (4M)$$