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### Internal Assessment Test III – Sept 2023

Sub:	Mathematics – II for CSE Stream			Sub Code:	BMATS201		
Date:	04/09/2023	Duration:	90 mins	Max Marks:	50	Sem / Sec:	II / A-G
<b>Answer any FIVE questions.</b>							
1.	Find the directional derivative of $\varphi = x^2yz + 4xz^2$ at $(1, -2, -1)$ in the direction of the vector $2\hat{i} - \hat{j} - 2\hat{k}$ .			[10]	CO	RBT	
2.	If $\vec{F} = \nabla(xy^3z^2)$ , find $\operatorname{div} \vec{F}$ and $\operatorname{curl} \vec{F}$ at $(1, -1, 1)$ . Is $\vec{F}$ solenoidal or irrotational?			[10]	CO2	L3	
3.	Find the angle between the surfaces $x^2 + y^2 - z^2 = 4$ and $x^2 + y^2 - 13 = z$ at the point $(2, 1, 2)$ .			[10]	CO2	L3	
4.	Show that the spherical coordinate system is orthogonal.			[10]	CO2	L2	

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4.	Show that the spherical coordinate system is orthogonal.			[10]	CO2	L2	

5.	Prove that the subset $W = \{(x, y, z) / 2x + 3y + z = 0\}$ of the vector space $R^3$ is a subspace of $R^3$ .	[10]	CO3 L3
6.	Show that the function $f(x) = 3x - 2$ and $g(x) = x$ are orthogonal in $P_n$ with inner product $\langle f, g \rangle = \int_0^1 f(x) \cdot g(x) dx.$	[10]	CO3 L3
7.	Prove that the transformation $T: R^2 \rightarrow R^2$ defined by $T(x, y) = (3x, x + y)$ is linear. Find the images of the vectors $(1, 3)$ and $(-1, 2)$ under this transformation.	[10]	CO3 L3
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# Internal Assessment - III

## Test

QD of  $\phi = x^2yz + 4xz^2$  in direction of  $\vec{d} = 2\hat{i} - \hat{j} - 2\hat{k}$  at  $(1, -2, -1)$

$$\begin{aligned}\text{grad } (\phi) &= \hat{i} \left( \frac{\partial \phi}{\partial x} \right) + \hat{j} \left( \frac{\partial \phi}{\partial y} \right) + \hat{k} \left( \frac{\partial \phi}{\partial z} \right) \\ &= \hat{i} (2xyz + 4z^2) + \hat{j} (x^2z + 0) + \hat{k} (x^2y + 8xz) \\ \therefore \text{grad } (\phi) &= (2xyz + 4z^2)\hat{i} + (x^2z)\hat{j} + (x^2y + 8xz)\hat{k}\end{aligned}$$

WKT, QD of  $\phi$  along  $\vec{d}$  =  $\text{grad } (\phi) \cdot \frac{\vec{d}}{|\vec{d}|}$

$$\begin{aligned}\text{grad } (\phi) &= 2xyz\hat{i} + 2x^2z\hat{j} + (x^2y + 8xz)\hat{k} \\ (1, -2, -1) &= (2(-2) + 4)\hat{i} + (-1)\hat{j} + (-2 + (-8))\hat{k} \\ &= 8\hat{i} - \hat{j} - 10\hat{k}\end{aligned}$$

Now, QD of  $\phi$  along  $\vec{d}$  =  $\frac{(8\hat{i} - \hat{j} - 10\hat{k}) \cdot (2\hat{i} - \hat{j} - 2\hat{k})}{\sqrt{2^2 + (-1)^2 + (-2)^2}}$

$$\begin{aligned}&= \frac{16 + 1 + 20}{\sqrt{4 + 1 + 4}} \\ &= \frac{37}{3}\end{aligned}$$

Hence, QD of  $\phi$  along  $\vec{d}$  =  $\frac{37}{3}$

2.

Ques.

$$\vec{F} = \nabla (xy^3z^2)$$

$$= \frac{\partial}{\partial x} (xy^3z^2) \hat{i} + \frac{\partial}{\partial y} (xy^3z^2) \hat{j} + \frac{\partial}{\partial z} (xy^3z^2) \hat{k}$$

$$\vec{F} = y^3z^2 \hat{i} + 3xy^2z^2 \hat{j} + 2xyz^3 \hat{k}$$

$$\operatorname{div}(\vec{F}) = \frac{\partial}{\partial x} (y^3z^2) + \frac{\partial}{\partial y} (3xy^2z^2) + \frac{\partial}{\partial z} (2xyz^3)$$

$$\operatorname{div}(\vec{F}) = 0 + 6xyz^2 + 2xy^3$$

$$\begin{aligned}\operatorname{div}(\vec{F})_{(1,-1,1)} &= 6(-1) + 2(-1) \\ &= -6 - 2 = -8\end{aligned}$$

$$\therefore \operatorname{div}(\vec{F})_{(1,-1,1)} = \underline{\underline{-8}}$$

$$\operatorname{curl}(\vec{F}) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y^3z^2 & 3xy^2z^2 & 2xyz^3 \end{vmatrix}$$

$$\begin{aligned}&= \hat{i} (6xyz^2 - 6xy^2z) - \hat{j} (2y^3z - 2y^3z) + \hat{k} (3y^2z^2 - 3y^2z^2) \\ &= 0\hat{i} + 0\hat{j} + 0\hat{k}\end{aligned}$$

$$\therefore \operatorname{curl}(\vec{F}) = \underline{\underline{0}}_{(1,-1,1)}$$

Since, the  $\operatorname{curl}(\vec{F})$  is '0',  $\vec{F}$  is irrotational

3) Given two faces,

$$\phi_1 = x^2 + y^2 - z^2 - 4 \quad , \quad \phi_2 = x^2 + y^2 - z - 13$$

$$\begin{aligned} \text{grad } (\phi_1) &= \frac{\partial (\phi_1)}{\partial x} \hat{i} + \frac{\partial (\phi_1)}{\partial y} \hat{j} + \frac{\partial (\phi_1)}{\partial z} \hat{k} \\ &= 2x \hat{i} + 2y \hat{j} - 2z \hat{k} \end{aligned}$$

$$\text{grad } (\phi_1)_{(2,1,2)} = 4 \hat{i} + 2 \hat{j} - 4 \hat{k}$$

$$\text{grad } (\phi_2) = 2x \hat{i} + 2y \hat{j} - \hat{k}$$

$$\text{grad } (\phi_2)_{(2,1,2)} = 4 \hat{i} + 2 \hat{j} - \hat{k}$$

If  $\theta$  is the angle b/w  $\phi_1$  and  $\phi_2$ , then

$$\cos \theta = \frac{\phi_1 \cdot \phi_2}{\|\phi_1\| \|\phi_2\|} = \frac{\text{grad } (\phi_1) \cdot \text{grad } (\phi_2)}{\|\text{grad } (\phi_1)\| \|\text{grad } (\phi_2)\|}$$

$$\cos \theta = \frac{16+4+4}{\sqrt{16+4+16} \sqrt{16+4+1}}$$

$$\cos \theta = \frac{24}{\sqrt{36} \sqrt{21}} = \frac{4}{\sqrt{21}}$$

$$\therefore \text{Angle b/w the surfaces at } (2,1,2) \Rightarrow \theta = \cos^{-1} \left( \frac{4}{\sqrt{21}} \right)$$

4.

## Spherical Coordinate System :-

If  $P$  is a point in spherical coordinate system, it can be denoted as  $P(r, \theta, \phi)$ .

Comparing to Cartesian system,

$$x = r \sin \theta \cos \phi, y = r \sin \theta \sin \phi, z = r \cos \theta$$

Let's denote  $\vec{r}$

$$\text{If } \vec{r} = x\hat{i} + y\hat{j} + z\hat{k},$$

In spherical system,  $\vec{r} = r \sin \theta \cos \phi \hat{i} + r \sin \theta \sin \phi \hat{j} + r \cos \theta \hat{k}$

$$\hat{e}_\theta = \frac{\partial \vec{r}}{\partial \theta} = \frac{r \cos \theta \cos \phi \hat{i} + r \cos \theta \sin \phi \hat{j} - r \sin \theta \hat{k}}{\sqrt{r^2 \cos^2 \phi + r^2 \sin^2 \phi + r^2 \sin^2 \theta}}$$

$$= \frac{r \cos \theta \cos \phi \hat{i} + r \cos \theta \sin \phi \hat{j} - r \sin \theta \hat{k}}{\sqrt{r^2 \cos^2 \theta (\cos^2 \phi + \sin^2 \phi) + r^2 \sin^2 \theta}}$$

$$= \frac{r \cos \theta \cos \phi \hat{i} + r \cos \theta \sin \phi \hat{j} - r \sin \theta \hat{k}}{\sqrt{r^2 (\sin^2 \theta + \cos^2 \theta)}}$$

$$= \frac{r \cos \theta \cos \phi}{r} \hat{i} + \frac{r \cos \theta \sin \phi}{r} \hat{j} - \frac{r \sin \theta}{r} \hat{k}$$

$$\therefore \hat{e}_\theta = \cos \theta \cos \phi \hat{i} + \cos \theta \sin \phi \hat{j} - \sin \theta \hat{k}$$

$$\begin{aligned}
 \hat{e}_\phi &= \frac{\partial \vec{r}}{\partial \phi} = \frac{-r \sin \theta \sin \phi \hat{i} + r \sin \theta \cos \phi \hat{j} + r \hat{k}}{\sqrt{r^2 \sin^2 \theta \sin^2 \phi + r^2 \sin^2 \theta \cos^2 \phi}} \\
 &= \frac{-r \sin \theta \sin \phi \hat{i} + r \sin \theta \cos \phi \hat{j} + 0 \hat{k}}{\sqrt{r^2 \sin^2 \theta (\sin^2 \phi + \cos^2 \phi)}} \\
 &= \frac{-r \sin \theta \sin \phi}{r \sin \theta} \hat{i} + \frac{r \sin \theta \cos \phi}{r \sin \theta} \hat{j} + 0 \hat{k} \\
 \therefore \hat{e}_\phi &= -\sin \phi \hat{i} + \cos \phi \hat{j} + 0 \hat{k}
 \end{aligned}$$

$$\begin{aligned}
 \hat{e}_x &= \frac{\partial \vec{r}}{\partial x} = \frac{\sin \theta \cos \phi \hat{i} + \sin \theta \sin \phi \hat{j} + \cos \theta \hat{k}}{\sqrt{\sin^2 \theta \cos^2 \phi + \sin^2 \theta \sin^2 \phi + \cos^2 \theta}} \\
 &= \frac{\sin \theta \cos \phi \hat{i} + \sin \theta \sin \phi \hat{j} + \cos \theta \hat{k}}{\sqrt{\sin^2 \theta (\cos^2 \phi + \sin^2 \phi) + \cos^2 \theta}} \\
 &= \frac{\sin \theta \cos \phi \hat{i} + \sin \theta \sin \phi \hat{j} + \cos \theta \hat{k}}{\sqrt{\sin^2 \theta + \cos^2 \theta}}
 \end{aligned}$$

$$\therefore \hat{e}_x = \sin \theta \cos \phi \hat{i} + \sin \theta \sin \phi \hat{j} + \cos \theta \hat{k}$$

Now,

$$\begin{aligned}
 \hat{e}_\phi \cdot \hat{e}_\phi &= -\cos \theta \cos \phi \sin \phi + \cos \theta \sin \phi \cos \phi + 0 \\
 &= 0
 \end{aligned}$$

$$\begin{aligned}
 \hat{e}_\phi \cdot \hat{e}_x &= -\sin \phi \sin \theta \cos \phi + \cos \phi \sin \theta \sin \phi + 0 \\
 &= 0
 \end{aligned}$$

$$\begin{aligned}
 \hat{e}_x \cdot \hat{e}_\theta &= \sin \theta \cos \phi \cos \theta \cos \phi + \cos \theta \sin \phi \sin \theta \sin \phi - \sin \theta \cos \phi \\
 &= \sin \theta \cos \theta (\cos^2 \phi + \sin^2 \phi) - \sin \theta \cos \theta \\
 &= \sin \theta \cos \theta - \sin \theta \cos \theta = 0
 \end{aligned}$$

Since,

$$\hat{e}_x \cdot \hat{e}_\theta = \hat{e}_\theta \cdot \hat{e}_\phi = \hat{e}_\phi \cdot \hat{e}_\theta = 0 \quad \{ \text{angle b/w them is } 90^\circ \}$$

We can conclude that spherical coordinate system  
is orthogonal

5.  $W = \{(x, y, z) \mid 2x + 3y + z = 0\}$

$W$  is  $T$        $2(0) + 3(0) + 0 = 0$

$(0, 0, 0) \in W$

$\therefore W$  is a non-empty set

Now,

$u, v \in W$  &  $a, b \in F$

$u = (x_1, y_1, z_1), \quad v = (x_2, y_2, z_2)$

$2x_1 + 3y_1 + z_1 = 0, \quad 2x_2 + 3y_2 + z_2 = 0$

$au + bv = 0,$

$a(x_1, y_1, z_1) + b(x_2, y_2, z_2)$

$(ax_1, ay_1, az_1) + (bx_2, by_2, bz_2)$

Now to check whether it belongs to  $\omega$ ,  
 $2(2ax_1 + 3bx_2) + 3(cay_1 + by_2) + (cax_1 + bx_2)$

$$\begin{aligned}
 &= (2ax_1 + 2bx_2) + (3ay_1 + 3by_2) + (cax_1 + bx_2) \\
 &= (2ax_1 + 3ay_1 + cx_1) + (2bx_2 + 3by_2 + bx_2) \\
 &= a(2x_1 + 3y_1 + x_1) + b(2x_2 + 3y_2 + x_2) \\
 &= a(0) + b(0) \\
 &= 0
 \end{aligned}$$

$\therefore$  the subset  $W$  belongs  $\checkmark$

6)

$$\text{Consider } \langle f, g \rangle = \int_0^1 f(x) \cdot g(x) dx$$

$$= \int_0^1 \begin{cases} & \text{given } f(x) = 3x - 2 \\ & g(x) = x \end{cases}$$

$$= \int_0^1 (3x - 2)x dx$$

$$= \int_0^1 3x^2 - 2x dx$$

$$= \left[ \frac{3x^3}{3} - \frac{2x^2}{2} \right]_0^1$$

$$= [1 - 1] = 0$$

$\therefore$  They are orthogonal.

i) Consider  $u = (x_1, y_1)$   
 $v = (x_2, y_2)$

$$\begin{aligned} T(u+v) &= (x_1+x_2, y_1+y_2) \\ &= (3(x_1+x_2), x_1+x_2+y_1+y_2) \\ &= (3x_1+3x_2, x_1+x_2+y_1+y_2) \\ &= (3x_1, x_1+y_1) + (3x_2, x_2+y_2) \\ &= T(u) + T(v) \end{aligned}$$

ii) Now,  
 $T(au) = (ax_1, ay_1)$

$$= (3ax_1, ax_1+ay_1) \quad \text{--- } ①$$

$$\begin{aligned} R.H.S &= aT(u) = a(x_1, y_1) \\ &= a(3x_1, x_1+y_1) \\ &= (3ax_1, ax_1+ay_1) \quad \text{--- } ② \end{aligned}$$

From ① & ②

$$R.H.S = L.H.S$$

$\therefore$  It is a linear transformation.

$$T(1,3) = (R(1), 1+3) = (3,4)$$

$$T(-1,2) = (-3,0), \quad 1+2 = (-3,1)$$

∴ The images of vectors  $(1,3)$  and  $(-1,2)$   
 $(3,4)$  and  $(-3,1)$  are