USN					



Internal Assessment Test 2 – August 2023

Sub:	Operating Systems	Sub Code:	21CS44	Branch:	ISE		
Date:							BE
Answer any FIVE FULL Questions						CO	RBT
1	Explain Semaphores. What do you mean by bina semaphore?	ry semapho	re and cour	nting	10	CO2	L2
	 Binary Semaphore (Mutex): Ensures that or access a shared resource at a time, preventing integrity. Counting Semaphore: Limits the number of access a resource simultaneously, controlling overuse of the resource. 	g conflicts a threads or p	and ensuring processes that	data t can			
	What are deadlocks and its characteristics with exconditions for its occurrence. Deadlock is a situation in concurrent programming with threads are unable to proceed because each is wait resource. This results in a standstill, where none execution, and the system becomes unresponsive. Characteristics of Deadlock: 1. Mutual Exclusion: At least one resource must meaning only one process can use it at a time 2. Hold and Wait: A process must hold at least acquire additional resources held by other process. 3. No Preemption: Resources cannot be forcible they can only be released voluntarily by the post they can only be released voluntarily by the post they can only be released voluntarily by the post they can only experience held by the meaning for a resource held by the meaning for a resource set of the processes require both resources to compand R2. The processes require both resources to compand R2. The processes require both resources to compand R2. The processes R1. P2 acquires R1. P2 acquires R2. P1 requests R2 but is blocked since P2 is holding the processes R1 but is blocked since P1 is holding Now, P1 and P2 are stuck in a deadlock. Both processes R1 but it is blocked since P1 is holding Now, P1 and P2 are stuck in a deadlock. Both processes R1 but it is blocked since P2 is holding Now, P1 and P2 are stuck in a deadlock. Necessary Conditions for Deadlock: 1. Mutual Exclusion: At least one resource must preventing multiple processes from using it since P2 is holding the processes from using it since P2 is holding the processes from using it since P2 is holding the processes from using it since P2 is holding the processes from using it since P2 is holding the processes from using it since P2 is holding the processes from using it since P2 is holding the processes from using it since P2 is holding the processes from using it since P2 is holding the processes from using it since P2 is holding the processes from using it since P2 is holding the processes from using it since P2 is holding the processes	where two or ting for the of the proces be held in a national resourcesses. y taken away rocesses holding re processes ext processes and P2, and polete their taken the processes are was a national resources.	more proces other to rele esses can con non-sharable in the while wait ay from a pro- ng them. exists, where in the chain. I two resources sks. iting for reso	sses or ease a ntinue mode, ing to occess; e each es, R1	10	CO2	L2
	 2. Hold and Wait: Processes must hold resour additional resources. This means they can ensure while holding some resources and waiting for 3. No Preemption: Resources cannot be forcible they must be released voluntarily. This concannot be interrupted while holding resources 	iter a state o others. y taken awa ndition ensu	f partial executy from proc	esses;			

4. Circular Wait: A circular chain of is waiting for a resource held by ar These four conditions together create a deadlocked, as all the conditions are satisfione or more of these conditions must not be resource allocation graphs, process prioritiavoid or resolve deadlocks.	scenario where processes can become ed simultaneously. To prevent deadlocks, e true. For example, using techniques like			
the process to the resource. 2. Request Edge: Represents a proces the process to the resource. A deadlock can be identified in a RAG request edges. This cycle indicates that e resource held by another process in the cythe processes can proceed, resulting in a d Example: Let's consider a scenario with resource types (R1, R2, R3). Each proce resource type. The following steps describ 1. P1 holds R1. 2. P2 holds R2. 3. P3 holds R3. 4. P1 requests R2 (request edge P1 -> 5. P2 requests R3 (request edge P2 -> 6. P3 requests R1 (request edge P3 -> At this point, the RAG will have a cycle in -> R3 -> P3 -> R1 -> P1. This cycle indiprocess is waiting for a resource held by "deadly embrace." The RAG is very useful in describing the contractions between processes an patterns that could lead to deadlock interactions between processes an patterns that could lead to deadlock 3. Identification of Resources: It help which resources, aiding in the anal	a graphical representation used to depict uest relationships among processes in a ng the interactions between processes and eks. nodes, and resources are represented as are two types of edges: less holding a resource. It is directed from the serequesting a resource. It is directed from the when it contains a cycle involving only ach process in the cycle is waiting for a cycle, leading to a situation where none of eadlock. In three processes (P1, P2, P3) and three is can hold at most one instance of each the scenario: R2). R3). R1). volving the request edges: P1 -> R2 -> P2 cates a potential deadlock situation. Each the next process in the cycle, forming a deadly embrace (deadlock) because: It is directed from the cycle is waiting for a cycle, leading to a situation where none of each each end the scenario: R2). R3). R1). volving the request edges: P1 -> R2 -> P2 cates a potential deadlock situation. Each the next process in the cycle, forming a deadly embrace (deadlock) because: It is a clear visual representation of the dorsources, making it easier to identify its. les involving only request edges, you can	10	CO2	L2
4a) Explain the process of recovery from dead	lock.	5	CO2	L2

Recovery from a deadlock is a process of resolving the deadlock situation and allowing the affected processes to continue their execution. There are several strategies and techniques that can be employed to recover from a deadlock. Here are some common approaches: 1. **Process Termination**: One way to recover from a deadlock is to terminate one or more processes involved in the deadlock. This releases the resources held by the terminated processes, allowing other processes to continue. However, this approach should be used with caution as it might lead to loss of data or disruption of user activities. 2. **Resource Preemption**: In this approach, the operating system forcibly takes resources from one or more processes and gives them to other waiting processes to break the circular wait condition. The preempted processes are rolled back to a safe state, allowing them to restart later. This method requires careful consideration to choose which processes to preempt and a mechanism to roll back their state. 3. Wait-Die and Wound-Wait Schemes: These schemes are used in database management systems to handle deadlock situations. In the Wait-Die scheme, older processes wait for younger ones, while in the Wound-Wait scheme, older processes preempt resources from younger ones. These schemes are useful when dealing with transactions in a database environment. 4. **Timeouts**: Processes waiting for resources can be given a certain time limit (timeout). If a process doesn't acquire the required resources within the given time, it releases the resources it holds and goes back to its initial state, allowing other processes to use those resources. 5. **Dynamic Resource Allocation**: This involves allocating resources dynamically to processes as they request them. If a resource allocation leads to a potential deadlock, the system can backtrack and reallocate resources to avoid the deadlock situation. 6. Process Restart: In distributed systems, processes can be restarted on different nodes to resolve deadlocks. The idea is to break the circular wait by relocating processes to nodes with available resources. It's important to note that the recovery process should be well-designed and carefully implemented to avoid introducing further issues or complications. Additionally, it's often better to focus on preventing deadlocks from occurring in the first place through careful resource allocation, managing resource dependencies, and using appropriate synchronization mechanisms. L2 Explain three requirements that a solution to critical – section problem must satisfy. CO₂ The critical section problem is a fundamental synchronization problem in concurrent programming, where multiple processes or threads share a common resource and need to access it in a mutually exclusive manner. A solution to the critical section problem must satisfy the following three requirements to ensure correct and safe execution: 1. Mutual Exclusion: The solution must ensure that only one process or thread at a time can be in its critical section, accessing the shared resource. This requirement guarantees that no two processes are executing their critical sections simultaneously, preventing conflicts and ensuring data integrity. 2. **Progress**: The solution must ensure that if no process is in its critical section and some processes are waiting to enter their critical sections, then only those processes that are not in their remainder sections (non-critical sections) can participate in selecting the next process to enter the critical section. In other

words, the solution must ensure that processes waiting to enter the critical

section do eventually get a chance to do so.

4b)

3. Bounded Waiting : The solution must ensure that there is a limit on the number of times a process can enter its critical section after another process has requested access to it. This limit prevents any particular process from being indefinitely starved and guarantees that processes waiting to enter the critical section are not continually bypassed by new requests. These three requirements, mutual exclusion, progress, and bounded waiting, are collectively known as the "three conditions for synchronization" and are essential to ensure that a solution to the critical section problem is correct and prevents potential issues such as race conditions, deadlocks, and starvation.	s n e e		
Consider the following snapshot of a system: Allocation Max Available ABC ABC ABC	10	CO3	L3
iii. Is the system in a safe state? i. Calculate the Need matrix (N): Need (N) = Max (M) - Allocation (A) 0 0 2 1 0 1 0 0 2 2 1 0			
 0 1 4 ii. Finding the Safe Sequence: To determine the safe sequence, we'll use the Banker's Algorithm: 1. Find a process whose Need can be satisfied with the Available resources. Once a process is completed, its resources are returned to Available. 2. Repeat the process until all processes are completed or it's not possible to find a process that can be completed. 			
Starting with the given Available resources [1 0 2], we can follow these steps: 1. At t=0, we can allocate resources to Process 1 (P1), leaving Available = [1 0 2] - [0 0 2] = [1 0 0]. 2. At t=1, Process 4 (P4) can be allocated, leaving Available = [1 0 0] + [6 3 2] = [7 3 2]. 3. At t=2, Process 0 (P0) can be allocated, leaving Available = [7 3 2] + [0 0 2] = [7 3 4]. 4. At t=3, Process 2 (P2) can be allocated, leaving Available = [7 3 4] + [1 3 2].			
 5] = [8 6 9]. 5. At t=4, Process 3 (P3) can be allocated, leaving Available = [8 6 9] + [1 4 3] = [9 10 12]. 6. Finally, at t=5, Process 5 (P5) can be allocated. The safe sequence: P1 -> P4 -> P0 -> P2 -> P3 -> P5 iii. System Safety: Since we were able to find a safe sequence, the system is in a safe state. In conclusion, based on the provided matrices and calculations, we've determined the content of the matrix "Need" found the safe sequence, and determined that the 			
the content of the matrix "Need," found the safe sequence, and determined that the system is in a safe state according to the Banker's Algorithm. 6 Process Arrival Time Burst Time	10	CO2	L3

For the following set of process find the **P**1 0 4 P2 2 avg. waiting time and avg. turn around 2 P3 5 using Gantt chart for a) FCFS P4 3 4

ab	5	Janet Chart 10	(u) 1 C1 5	
b)	SJF	(preemptive	and non-	preemptive)

c) RR (quantum= 4)

SOLUTION.....

To calculate the average waiting time and average turnaround time for different scheduling algorithms (FCFS, SJF preemptive and non-preemptive, and RR), we can simulate the execution of the processes using a Gantt chart and then calculate the times accordingly. Below, I'll provide the calculations and Gantt charts for each case.

Process details: Process P1 P2 P3 P4 Arrival Time 0 1 2 3 Burst Time 4 2 5 4 Let's start with FCFS (First-Come-First-Serve) scheduling:

1. FCFS Scheduling:

- Gantt Chart: P1 -> P2 -> P3 -> P4
- Waiting Times: P1 = 0, P2 = 4, P3 = 6, P4 = 11
- Turnaround Times: P1 = 4, P2 = 6, P3 = 11, P4 = 15

Average Waiting Time = (0 + 4 + 6 + 11) / 4 = 5.25 Average Turnaround Time = (4+6+11+15)/4=9

Now, let's move to SJF (Shortest Job First) scheduling:

2. SJF Preemptive Scheduling:

- Gantt Chart: P1 -> P2 -> P1 -> P4 -> P2 -> P3 -> P3 -> P3 ->
- Waiting Times: P1 = 6, P2 = 3, P3 = 0, P4 = 6
- Turnaround Times: P1 = 10, P2 = 5, P3 = 11, P4 = 10

Average Waiting Time = (6 + 3 + 0 + 6) / 4 = 3.75 Average Turnaround Time = (10 + 5 + 11 + 10) / 4 = 9

3. SJF Non-Preemptive Scheduling:

- Gantt Chart: P1 -> P2 -> P4 -> P3
- Waiting Times: P1 = 6, P2 = 0, P3 = 6, P4 = 3
- Turnaround Times: P1 = 10, P2 = 3, P3 = 11, P4 = 7

Average Waiting Time = (6 + 0 + 6 + 3) / 4 = 3.75 Average Turnaround Time = (10 + 3 + 11 + 7) / 4 = 7.75

4. **RR** (Round Robin) Scheduling (Quantum = 4):

- Gantt Chart: P1 -> P2 -> P3 -> P4 -> P1 -> P3 -> P4 -> P3 -> P3
- Waiting Times: P1 = 5, P2 = 2, P3 = 5, P4 = 8
- Turnaround Times: P1 = 9, P2 = 7, P3 = 14, P4 = 12

Average Waiting Time = (5 + 2 + 5 + 8) / 4 = 5 Average Turnaround Time = (9+7+14+12)/4=10.5

These are the calculations and Gantt charts for each scheduling algorithm

Faculty Signature CCI Signature **HOD Signature**