





#### **Magnetic Bounday Conditions:** Q.No. 1)

Magnetic field vectors can be split into tangential and normal components with respect to the boundary



Magnetic boundary conditions can be obtained by applying (i) Gauss's law for magnetic fields and (ii) Ampere's Circuital Law



$$
B_{N1} \cdot \pi \rho^{2} - B_{N2} \cdot \pi \rho^{2} + B_{L1} \frac{2\pi \rho}{J} \frac{\rho I}{\partial \alpha} + B_{L2} \cdot \frac{2\pi \rho}{J} \frac{\rho I}{\alpha} = 0
$$

To obtain conditions at the boundary,

$$
B_{N1} \cdot \eta_{j}^{2} - B_{N2} \cdot \eta_{j}^{2} = 0
$$
\n
$$
\frac{B_{N1} \cdot \eta_{j}^{2} - B_{N2} \cdot \eta_{j}^{2} = 0}{B_{N1} \cdot B_{N2}} \Rightarrow \frac{B_{N1} \cdot B_{N2}}{\sqrt{1 - \frac{B_{N1}}{N_{N1}}}
$$
\n
$$
\frac{B_{N1} \cdot \gamma_{m1} + \gamma_{m1} \cdot B_{N2}}{\sqrt{1 - \frac{B_{N1}}{N_{N1}} \cdot \frac{B_{N2}}{N_{N2}}}}
$$
\n
$$
\frac{B_{N1} \cdot \gamma_{m1} \cdot B_{N2}}{\gamma_{m1} \cdot B_{N2}} \Rightarrow \frac{B_{N1} \cdot B_{N2}}{\gamma_{m2} \cdot B_{N2}}
$$
\n
$$
\frac{B_{N1} \cdot B_{N2}}{\gamma_{m1} \cdot B_{N2}}
$$





Equations (1), (2), (3), (4), (5) and (6) are the magnetic boundary conditions

### Q. No. 2 a) **Faraday's Law and induced e.m.f.:**



**Faraday discovered that the induced** emf, Vemf (in volts) in any closed circuit is equal to the time rate of change of the magnetic flux linkage by the circuit



# Lerz's law

Lenz's law states the direction of current flow in the circuit is such that the induced magnetic field produced by the induced current opposes change in the original magnetic field.



An e.m.f. will be induced under the following two conditions:

(i) when the magnetic field is static and the coil is moving - such e.m.f is called Generator e.m.f. (or) Motional e.m.f.

(ii) when the coil is stationary and the magnetic field is time varying - such e.m.f is called Transformer e.m.f.

Faraday's Law of electromagnetic induction:



(a) For addition of  
\n
$$
\lim_{h \to 0} \frac{e^{-\frac{1}{h}}}{\ln e^{-\frac{1}{h}}}
$$
\n<

(ii) Generalov *e.m.* | Notional *e.m.*  
\n(i) Generality *e.m.* | Notional *e.m.*  
\n(c) Find is stable (not changing with required to divide)  
\n
$$
k
$$
  
\n(c) is moving ( $\vec{v}$  - velocity  $\vec{v}$  moving will  
\n
$$
\vec{F}_m = \mathcal{A}(\vec{v} \times \vec{B})
$$
\n
$$
\vec{F}_m = \mathcal
$$

Q. No. 2 b)

Electric Circuit Parameters:  $\vec{E} = -\vec{\nabla}V$  (cleatrostations)  $(V/m)$  $V_{ab} = -\int \vec{F} \cdot \vec{dl}$  (v)  $\overrightarrow{D} = E \overrightarrow{E} \left( C \right)_{n} \overrightarrow{A}$  $I = \iint \vec{f} \cdot d\vec{s}$  (A)  $\frac{1}{\frac{2}{\sqrt{2\sqrt{2\cdot\frac{1}{\sqrt{2}}}}}}$  $R = \frac{\rho}{c} = \frac{1}{\sigma s} (\rho)$ Conductance  $G = \frac{1}{R}(v)$  $\sigma = \frac{1}{\rho}$   $(s|_{m})$  $J = \sigma \vec{E}$  microscopic form of ohm's law Macroscopic form of V=IR

Magnetic Circuit Parameters:  $\vec{H} = -\vec{\nabla} V_{m}$  (Am)  $V_m = -\int \vec{\mu} \cdot d\vec{l}$  (A)  $\vec{B} = \mu \vec{H} \quad (\mu b / m^2)$  $\phi = \iint\limits_{s} \overrightarrow{g} \cdot \overrightarrow{ds} \text{ (wb)}$  $S_{\kappa}$ R-Reluctance  $\left| R = \frac{R}{\mu s} \right| \left( \frac{At}{wb} \right)$  $12$  remeance  $P = \frac{1}{R}$  (Wb/At)  $f = m.m.f. = \oint_{M} R | (At)$ 

Electric Circuit Parameters:

# $\alpha$  $\lambda$

$$
\bigvee_{\alpha b}^{\mathsf{V}} = -\int_{b}^{\overrightarrow{\mathsf{E}}^{\mathsf{T}}} \overrightarrow{\mathsf{A}} \quad \left(\mathsf{V}\right)
$$

## Work done around a closed path is zero



$$
\frac{k\nu L}{L} = \oint \vec{E} \cdot d\vec{l} = 0
$$

$$
\begin{pmatrix}\nCapacitana \\
C &= \frac{a}{V} & (F)\n\end{pmatrix}
$$

Magnetic Circuit Parameters:

$$
\oint_{L} \vec{A} \cdot d\vec{l} = I_{enc}
$$
\n
$$
I_{enc}
$$
\n
$$
\oint_{L} \vec{A} \cdot d\vec{l} = N I
$$

$$
Induclance
$$
  

$$
L = \frac{N\phi}{I} \quad (4)
$$





<u>Series Electric Circuit</u>  $I = I_1 = I_2 = ... = I_N$  $V = V_1 + V_2 + \cdots + V_N$  $R = \frac{V}{T} = R_1 + R_2 + \cdots + R_N$  $\frac{1}{6}$  =  $\frac{1}{6}$  +  $\frac{1}{6}$  +  $\cdots$  +  $\frac{1}{6}$ <br>6 <u>Parallel Electre Circuit:</u>  $I = I_1 + I_2 + ... + I_N$  $V = V_1 = V_2 = \cdots = V_N$  $\frac{1}{R} = \frac{T}{V} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_1} + \frac{1}{R_2}$  $65661+62+...+66$ 

Series Magnelic Circuit:  $\phi'' = \phi'' = \phi''' = \phi'''$  $F = F_1 + F_2 + \cdots + F_N$  $F = \phi_m R$  $F_{\tau} = P_{\tau \tau} P_{\tau}$  $F_{\tau} = \phi_{m1} R_1 + \phi_{m2} R_2 + \cdots + \phi_{mn} R_n$  $R_1 = R_1 + R_2 + \cdots + R_n$ <u>Parallel</u> Magnetic Circuit:  $\phi = \phi_1 + \phi_2 + \cdots + \phi_N$  $F = F_1 = F_2 = \cdots = F_N$  $\frac{1}{R} = \frac{\phi}{F} = \frac{1}{R_1} + \frac{1}{R_2} + \cdots + \frac{1}{R_N}$  $P = P_1 + P_2 + \cdots + P_N$ 

Q. no. 3)

Explain the inconsistency of Ampere's law for time varying fields. Derive the consistent equation (Modified form) of Ampere's law for time varying fields.





**Modified form of Ampere's Circuital Law for** Time varying fields: (Differential or Point

Form)  
\n
$$
\vec{\nabla}\times\vec{H} = \vec{J} + \underbrace{\vec{\partial}\vec{J}}_{\text{othero}}
$$
\n
$$
\vec{J} = \underbrace{\vec{J} = \vec{J} \cdot \vec{J} \cdot
$$



$$
z = \frac{\xi_0 e_y S}{d}
$$
  
\n
$$
\overrightarrow{D} = \epsilon \overrightarrow{E}
$$
  
\n
$$
I = I_c + I_p
$$
  
\n
$$
I_c = \iint_C \overrightarrow{f_c} \cdot d\overrightarrow{s} = \iint_S \sigma \overrightarrow{E} \cdot d\overrightarrow{s}
$$
  
\n
$$
I_p = \iint_S \overrightarrow{f_p} \cdot d\overrightarrow{s} = \iint_S \overrightarrow{d\overrightarrow{E}} \cdot d\overrightarrow{s}
$$

$$
\oint \vec{H} \cdot d\vec{l} = \hat{I}_c + \hat{I}_D
$$
\n
$$
\oint \vec{H} \cdot d\vec{l} = \iint_S \vec{r} \cdot d\vec{s} + \iint_S \frac{\partial \vec{r}}{\partial t} \cdot d\vec{s}
$$
\n
$$
\oint \vec{H} \cdot d\vec{l} = \iint_S \vec{r} \cdot d\vec{s} + \iint_S \frac{\partial \vec{r}}{\partial t} \cdot d\vec{s}
$$
\nModified form of A.C.L. for time varying fields in Integral form

Modified form of A.c.L. for time, varying fields in differential (point) from

\n
$$
\vec{\nabla} \times \vec{H} = \vec{\sigma} \vec{E} + \frac{\partial \vec{D}}{\partial \vec{E}}
$$

The displacement current is a result of time-varying electric field. A typical example of such current is the current through a capacitor when an alternating voltage source is applied to its plate.

$$
c = \frac{\varepsilon_{e} \varepsilon_{y} S}{d} \int_{s} \frac{\varepsilon_{f}}{\sqrt{1 - \frac{\varepsilon_{f}}{\varepsilon_{g}}}} \frac{\varepsilon_{f}}{\sqrt{1 - \frac{\vare
$$

Q. No. 4)

**State and Explain Poynting's theorem with derivation.** 

<u>(or)</u> **State and Prove Poynting's theorem.** <u>(or)</u> State Poynting's theorem. Prove that  $P = E \times H$ .

**Poynting's theorem and Wave Power:** 

Poynting's theorem states that the net power flowing out of a given volume is equal to the time rate of decrease in stored energy within the volume minus conduction losses (Ohmic losses)



# **Proof:**



$$
\vec{\nabla}\cdot(\vec{\epsilon}\times\vec{H}) = -\frac{\partial}{\partial t} \left( \frac{1}{2} \mu H^2 + \frac{1}{2} \epsilon \epsilon^2 \right) - \sigma \epsilon^2
$$

Differential form or Point form of Poynting's theorem





**Poynting's theorem and Wave Power:** 

Poynting's theorem states that the net power flowing out of a given volume is equal to the time rate of decrease in stored energy within the volume minus conduction losses (Ohmic losses)

Power of an EM  
wave,  
Power Density vector = Poynting's Vector  
(Power per unit Area)  

$$
S = P = \frac{Pv}{N} \left( \frac{W}{N} \right)
$$

Instantaneous Power Density Vector, 
$$
\overrightarrow{P}
$$
 =  $\overrightarrow{E}\times\overrightarrow{H}$  W/m<sup>2</sup>

**Active Power Density Vector** or Real Power Density Vector,

$$
P_{avg} = P_{real} = \frac{1}{2}Re\{\vec{e}\vec{r}^*\}W_{m}^{\dagger}
$$

Reactive Power Density Vector, 
$$
P_{\text{reactive}} = \frac{1}{2} \mathbf{Im} \{ \vec{E} \times \vec{H} \} \}
$$
  $W/m^2$ 

**Instantaneous Power Density = Real Power Density + Reactive Power Density** 

Q. no. 5)

Using Maxwell's equation derive an expression for uniform plane wave in free space.

 $(or)$ 

Derive the expression for Wave equation for a Uniform Plane Wave for free space from Maxwell's equation.

(or)

**Starting form Maxwell's equations, derive the general wave equations** for electric and magnetic fields.

$$
\boxed{\vec{B} = \mu \vec{H} \over \vec{D} = \epsilon \vec{E}}
$$

⋒

 $\bigcirc$ 

3.

4.



$$
\vec{r}.\vec{p} = \hat{y}
$$
\n
$$
\epsilon \vec{v}.\vec{\epsilon} = \hat{y}
$$
\n
$$
\therefore \hat{y} = 0 \text{ for the median of the original line}
$$
\n
$$
\vec{v}.\vec{\epsilon} = 0
$$
\n
$$
\vec{v}.\vec{\mu} = 0
$$

**Uniform Plane Wave(UPW)/Transverse Electromagnetic Wave(TEM):** 

 $e^{j\omega t}$  = coswt +j sinwt

$$
\vec{E}(z,t) = E(z,t) \vec{a_x} = E(z) \vec{e}^{\text{wt}} \vec{a_x}
$$
  

$$
\vec{H}(z,t) = H(z,t) \vec{a_y} = H(z) \vec{e}^{\text{wt}} \vec{a_y}
$$

$$
\frac{\vec{\nabla} \times \vec{\epsilon}^2 = -\mu \frac{\partial \vec{\mu}}{\partial t} \longrightarrow \text{O} \quad \vec{\nabla} \times \vec{\mu}^2 = \sigma \vec{\epsilon} + \epsilon \frac{\partial \vec{\epsilon}^2}{\partial t} \longrightarrow \text{O} \quad \vec{\nabla} \cdot \vec{\epsilon}^2 = 0 \longrightarrow \text{O} \quad \vec{\sigma} \cdot \vec{\mu}^2 = 0 \longrightarrow \text{O} \quad \vec{\sigma} \cdot \vec{\mu}
$$

$$
\vec{V}x\vec{H} = \begin{vmatrix} a_{x1} & a_{y1} & a_{z2} \\ a_{y1} & a_{y2} & a_{z3} \\ a_{z1} & a_{z2} & a_{z3} \end{vmatrix} = a_{x1}^{-1}\begin{bmatrix} 0 & -\frac{a_{y1}}{a_{z1}} \\ 0 & \frac{a_{z1}}{a_{z2}} \end{bmatrix} \Rightarrow \vec{V}x\vec{H} = -\frac{a_{y1}}{a_{z1}}\vec{a}
$$

$$
\boxed{\nabla x \vec{\epsilon}^{\prime} = -\mu \frac{\partial \vec{H}}{\partial t} \rightarrow 0 \quad \boxed{\nabla x \vec{H} = \sigma \vec{\epsilon} + \epsilon \frac{\partial \vec{\epsilon}^{\prime}}{\partial t} \rightarrow 0 \quad \boxed{\nabla \cdot \vec{\epsilon}^{\prime} = 0} \rightarrow 0 \quad \boxed{\nabla \cdot \vec{H}^{\prime} = 0} \rightarrow \textcircled{0}
$$

$$
\vec{q}_{x}\vec{\epsilon} = \frac{\partial \epsilon}{\partial z} \vec{a}_{y} \qquad \qquad 0 \Rightarrow \qquad \frac{\partial \epsilon}{\partial z} \vec{a}_{y} = -\mu \frac{\partial H}{\partial t} \vec{a}_{y} \qquad \qquad 0
$$

$$
\begin{array}{rcl}\n\textcircled{1} & -\frac{\partial \text{H}}{\partial t} a_x^{\dagger} = & \textcircled{1} \in a_x^{\dagger} + \textcircled{2} \in a_x^{\dagger} \\
-\frac{\partial \text{H}}{\partial t} = & \textcircled{1} \in + \textcircled{3} \in \rightarrow \textcircled{6}\n\end{array}
$$

 $\vec{v}$   $\vec{v}$   $\vec{r}$  =  $\frac{\partial H}{\partial t}$   $\vec{a}$   $\vec{x}$ 

$$
\frac{\partial E}{\partial t} = -\mu \frac{\partial H}{\partial t} \rightarrow G
$$

$$
\frac{\partial^{2}H
$$

Differending

\n
$$
\frac{\partial w}{\partial t} + \epsilon \frac{\partial e}{\partial t} - \frac{\partial^2 u}{\partial t \partial t} = \frac{\partial^2 u}{\partial t^2} + \epsilon \frac{\partial^2 e}{\partial t^2}
$$

$$
\frac{\partial H}{\partial t} = \sigma E + \frac{\partial E}{\partial t} \rightarrow \textcircled{6}
$$

$$
\frac{dH \cdot (5) \cdot v \cdot t \cdot z'}{d^{2}E} = -\mu \frac{d^{2}H}{d^{2}U}
$$

$$
\frac{\partial \mathcal{H} \cdot \bigoplus \omega \cdot \mathbf{1} \cdot \mathbf{2}'}{-\frac{\partial^2 \mathcal{H}}{\partial z^2} = \sigma \frac{\partial \epsilon}{\partial z} + \epsilon \frac{\partial^2 \epsilon}{\partial z^2}}
$$

$$
\frac{\partial E}{\partial t} = -\mu \frac{\partial H}{\partial t} \rightarrow \bigcirc
$$
\n
$$
\frac{\partial H}{\partial t} = \frac{\mu}{\partial t} \frac{\partial H}{\partial t} \rightarrow \bigcirc
$$
\n
$$
\frac{\partial H}{\partial t} = \frac{\mu}{\partial t} \frac{\partial H}{\partial t} \quad \text{where, the integral is given by } \frac{\partial H}{\partial t} \text{ is given by } \frac{\partial H}{
$$

$$
\frac{\partial E}{\partial t} = -\mu \frac{\partial H}{\partial t} \rightarrow \bigcirc
$$
\n
$$
\frac{\partial H}{\partial t} = -\mu \frac{\partial H}{\partial t} \qquad \frac{\partial W}{\partial t} = -\mu \frac{\partial H}{\partial t} \qquad \frac{\partial W}{\partial t} = -\mu \frac{\partial H}{\partial t} \qquad \frac{\partial W}{\partial t} = -\mu \frac{\partial H}{\partial t} \qquad \frac{\partial H}{\partial t} = -\mu \frac{\partial H}{\partial t} \qquad \frac{\partial H}{\partial t} = -\mu \frac{\partial H}{\partial t} \qquad \frac{\partial H}{\partial t} = -\mu \frac{\partial H}{\partial t} \qquad \frac{\partial H}{\partial t} = -\mu \frac{\partial H}{\partial t} \qquad \frac{\partial H}{\partial t} = -\frac{\partial H}{\partial t} = -\frac{\partial H}{\partial t} \qquad \frac{\partial H}{\partial t} = \frac{\partial H}{\partial t} = -\frac{\partial H}{\partial t} \frac{\partial H}{\partial t} = -\frac{\partial H}{
$$

# **Wave Equations for Free Space:**



**Wave Equations for Free Space:** 

$$
\frac{\frac{\partial^2 E}{\partial z^2}}{\frac{\partial^2 E}{\partial z^2}} = \frac{\partial \mu}{\partial t} \frac{\partial E}{\partial t} + \mu \epsilon \frac{\partial^2 E}{\partial t^2}
$$
\n
$$
\frac{\partial^2 H}{\partial z^2} = \frac{\partial \mu}{\partial t} \frac{\partial H}{\partial t} + \mu \epsilon \frac{\partial^2 H}{\partial t^2}
$$
\n
$$
\frac{\partial^2 H}{\partial z^2} = \frac{\partial \mu}{\partial t} \frac{\partial H}{\partial t} + \mu \epsilon \frac{\partial^2 H}{\partial t^2}
$$
\n
$$
\frac{\partial^2 E}{\partial z^2} = \mu_0 \epsilon_0 \frac{\partial^2 E}{\partial t^2}
$$
\n
$$
\frac{\partial^2 E}{\partial t^2} = \frac{1}{\mu_0 \epsilon_0} \frac{\partial^2 E}{\partial z^2}
$$
\n
$$
\frac{\partial^2 E}{\partial t^2} = \frac{1}{\mu_0 \epsilon_0} \frac{\partial^2 E}{\partial z^2}
$$
\n
$$
\frac{\partial^2 E}{\partial t^2} = c^2 \frac{\partial^2 E}{\partial z^2}
$$

# **Wave Equations for Free Space:**



**H-field** 

**Equation for E-field** 

Derive the relationship between E and H for a UPW for any medium. Q. No. 6 a)  $(or)$ Derive the expression for Intrinsic Impedance for any medium. (or) Derive the expression for Helmholtz Wave Equation and obtain the relationship between E and H for a UPW for any medium.  $($ or $)$ Derive the expression for Wave Equation and solution for a sinusoidal excitation and obtain the relationship between E and H for a UPW for any medium. For a UPW / TEM.  $=$  we we the join we **Consider the sinusoidal excitation.** The phasor form of Equations can be written as follows:  $\vec{E}(z,t) = E(z,t) \vec{a_x} = E(z)e^{j\omega t} \vec{a_y}$ <br>  $\vec{H}(z,t) = H(z,t) \vec{a_y} = H(z) e^{j\omega t} \vec{a_y}$  $\frac{\partial \vec{E}}{\partial t}$  =  $E(z) \vec{\ell}^{\text{wt}}$   $\vec{j}^{\text{w}} \frac{\partial \vec{\ell}}{\partial x}$  =  $\vec{j}^{\text{w}} \vec{E}$ 

$$
\frac{\partial \vec{H}}{\partial t} = \mu(z) e^{j\omega t} j\omega \vec{q} = j\omega \vec{H}
$$

Maxwell's equation
1. $\vec{\nabla} \chi \vec{E} = -\mu \frac{\partial \vec{H}}{\partial t} \Rightarrow \vec{\nabla} \chi \vec{E} = -j\omega \mu \vec{H}$
2. $\vec{\nabla} \chi \vec{H} = \sigma \vec{E} + \vec{\varepsilon} \frac{\partial \vec{E}}{\partial t} \Rightarrow \vec{\nabla} \chi \vec{H} = \sigma \vec{E} + j\omega \vec{\varepsilon} = -j\omega \mu \vec{H}$
3. $\vec{\nabla} \cdot \vec{E} = \mathcal{R}/\vec{E} = 0 \Rightarrow \vec{\nabla} \cdot \vec{E} = 0 \Rightarrow \vec{\nabla} \cdot \vec{E} = 0 \Rightarrow \vec{\nabla} \cdot \vec{H} = 0$
4. $\vec{\nabla} \cdot \vec{H} = 0 \Rightarrow (\because \vec{\mathcal{R}} = 0) \Rightarrow \vec{\nabla} \cdot \vec{H} = 0 \Rightarrow \vec{\nabla} \cdot \vec{H} = 0$







**Similarly, Solution for Helmholtz Wave Equations for H-field can be given as:** 

$$
\vec{H}(z_1t) = H(z) e^{j\omega t} a_y
$$

$$
\frac{\partial^2 H}{\partial z^2} - k^2 H = 0
$$
  

$$
H_0 e^{-jkz} + H_0^2 e^{+jkz}
$$
  

$$
H_0 e^{+jkz}
$$
  

$$
H_0 e^{+jkz}
$$
  

$$
H_0 e^{+jkz}
$$
  

$$
Batawa
$$

$$
\vec{H}(z,t) = [H_0 e^{jkt} e^{j\omega t} + H_0 e^{jkt} e^{j\omega t}]_{y}^{2}
$$

$$
\vec{\nabla} \times \vec{E} = -j\omega \mu \vec{H}
$$

$$
\vec{\nabla}_{\mathsf{X}}\vec{\mu} = \sigma \vec{\epsilon} + j\omega \epsilon \vec{\epsilon}
$$

$$
\frac{\vec{v} \cdot \vec{E} = 0}{L_{1}(3)}
$$
  $\frac{\vec{v} \cdot \vec{H} = 0}{L_{1}(3)}$ 

**Relation between E and H:** 

Use ① to get relation 
$$
U_{w} \vec{\epsilon} = \vec{H}
$$
  
\n
$$
\vec{\nabla} \times \vec{\epsilon} = -j \frac{v}{h} \vec{H}
$$
\n
$$
LNS = \vec{\nabla} \times \vec{\epsilon} = \begin{vmatrix} \frac{a}{h} & \frac{a}{h} \\ \frac{a}{h} & \frac{a}{h} \\ \frac{a}{h} & 0 \end{vmatrix}
$$
\n
$$
\vec{\nabla} \times \vec{\epsilon} = \vec{A} \times (0 - \vec{A}) = \vec{A} \times (0 - \vec{A}) \times (\vec{A} \times \vec{B})
$$
\n
$$
\vec{\nabla} \times \vec{\epsilon} = \vec{A} \times (0 - \vec{A}) = \vec{A} \times (0 - \vec{A}) \times (\vec{A} \times \vec{B})
$$
\n
$$
\vec{\nabla} \times \vec{\epsilon} = \vec{A} \times (\vec{A} \times \vec{B})
$$
\n
$$
LNS = \vec{A} \times \vec{\epsilon} = \vec{A} \times (\vec{A} \times \vec{B})
$$
\n
$$
LNS = \vec{A} \times \vec{\epsilon} = (\vec{A} \times \vec{B}) \times (\vec{A} \times \vec{B})
$$
\n
$$
LNS = \vec{A} \times \vec{\epsilon} = (\vec{A} \times \vec{B}) \times (\vec{A} \times \vec{B})
$$

$$
RMS = -j\omega\mu\vec{H}
$$
\n
$$
RMS = \left(-j\omega\mu \text{ Ho}e^{j\omega t}e^{-j\vec{k}t} \sqrt{j\omega\mu Ho}e^{j\omega t}e^{j\vec{k}t} \right)\vec{a}_{ij}
$$

**Equating LHS and RHS, gives the following relations:** 



$$
\eta = \frac{E_o}{\mu_0} = \frac{\dot{f} \omega \mu}{\dot{f} \omega \mu (64 \dot{f} \omega \epsilon)}
$$

$$
2 = \frac{E_0}{H_0} = \sqrt{\frac{\dot{d}^{\mu}M}{\sigma f\dot{d}^{\mu}\epsilon}}
$$

Intrinsic Impedance of the medium



Q. No. 6 b)

Four Equations<br>List the Maxwell's Equations in Integral form and differential (point) form:



Q. No. 7)

**Magnetic Field Intensity due to a conductor carrying** current of 'l' amperes **Finitely Long Conductor Infinitely Long Conductor** 



$$
\overrightarrow{1}d\overrightarrow{k} = \overrightarrow{1}d\overrightarrow{a}
$$
\n
$$
1d\overrightarrow{k} \times \overrightarrow{k} = \begin{vmatrix} a\overrightarrow{p} & a\overrightarrow{q} & a\overrightarrow{r} \\ 0 & 0 & 1d\overrightarrow{r} \\ 0 & 0 & -\overrightarrow{r} \end{vmatrix} = \overrightarrow{a} \begin{pmatrix} 0 & -9 \end{pmatrix} - a \overrightarrow{q} \begin{pmatrix} 0 & -9 \end{pmatrix}d\overrightarrow{r}
$$
\n
$$
+ a \overrightarrow{q} \begin{pmatrix} 0 & -9 \end{pmatrix}
$$
\n
$$
\overrightarrow{1}d\overrightarrow{x} \times \overrightarrow{R} = \overrightarrow{1} \begin{pmatrix} 0 & -\overrightarrow{r} & \overrightarrow{r} \\ 0 & 0 & -\overrightarrow{r} \end{pmatrix}
$$

$$
d\vec{h} = \frac{I \rho d\vec{z} d\vec{\phi}}{4\pi (\rho^2 + z^2)^{3/2}}
$$
  

$$
\vec{h} = \int d\vec{h} = \int d\vec{h} = \int_{z=2}^{2} \frac{I \rho d\vec{z} d\phi}{4\pi (\rho^2 + z^2)^{3/2}}
$$

Substitution:  $z = f$  tan d

 $dz = \int sec^2 d\alpha$ 

社  $\mathbf{z}_1$ そと  $\alpha$  :  $\alpha$  $\alpha_2$ 

$$
\vec{H} = \int \frac{2 \vec{r}^2 \sec^2{\alpha} d\alpha \vec{a} \phi}{4\pi (\vec{r}^2 + \vec{r}^2 \tan^2{\alpha})^3/2}
$$
  
 
$$
\alpha = \alpha_1
$$

$$
\vec{H} = \frac{1}{4\pi\rho} \int_{\alpha_1}^{\alpha_2} \frac{d\alpha}{\sec\alpha} \vec{a} \vec{p} = \frac{1}{4\pi\rho} \int_{\alpha_1}^{\alpha_2} \omega s \alpha \, d\alpha \, \vec{a} \vec{p}
$$

$$
\vec{H} = \frac{1}{4\pi\rho} \left[ sin \alpha_2 - sin \alpha_1 \right] a_0^2 \vec{H} due to4\pi\rho
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z_{1} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix}
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z_{2} = \int tan \alpha
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z_{1} = \frac{1}{2} \int tan \alpha
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z_{2} = \frac{1}{2} \int tan \alpha
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z_{3} = \frac{1}{2} \int tan \alpha
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z_{4} = \frac{1}{2} \int tan \alpha
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z_{13} = \frac{1}{2} \int tan \alpha
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z_{14} = \frac{1}{2} \int tan \alpha
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