

Internal Assessment Test-II										
Sub:	Electromagnetic Theory						Code:	BEC401		
Date:	08/07/2024	Duration:	90 mins	Max Marks:	50	Sem:	4th	Branch:	ECE(A,B,C,D)	
Answer any FIVE FULL Questions										

		Marks	OBE	
			CO	RBT
1.	Derive Maxwell's first equation of electrostatics. Also obtain the expression for Gauss's Divergence theorem.	[10]	CO2	L2
2.(a)	Derive an expression for the work done in moving a point charge Q in the presence of an electric field \mathbf{E} .	[04]	CO3	L2
2.(b)	Define electric potential. Prove that electric field intensity is negative potential gradient for electrostatics.	[06]	CO3	L2
3.(a)	Define current and current density. Derive the expression for equation of continuity of current.	[06]	CO3	L2
3.(b)	Calculate volume charge density at the point $P(3, -45^\circ, 5)$, given $\mathbf{D} = 5z^2 \mathbf{a}_\rho + 10\rho z \mathbf{a}_z \frac{C}{m^2}$.	[04]	CO2	L3
4.	A cube is defined by $1 < x, y, z < 1.2$. If $\mathbf{D} = 2x^2y\mathbf{a}_x + 3x^2y^2\mathbf{a}_y \frac{C}{m^2}$. Evaluate both sides of divergence theorem.	[10]	CO2	L3
5.	Using Laplace's equation, derive an expression for capacitance of a coaxial cylindrical capacitor.	[10]	CO3	L3
6.(a)	Starting from the Gauss's law deduce Poisson's and Laplace's equations. Write the equations in Cartesian, Cylindrical and Spherical coordinate systems.	[07]	CO3	L2
6.(b)	Given potential function $V = x^2yz + Ay^3z$. Find A so that Laplace's equation is satisfied.	[03]	CO3	L3
7.(a)	State and prove the Uniqueness theorem.	[07]	CO3	L2
7.(b)	Determine whether or not the given potential field satisfy the Laplace equation: $V = \rho^2 + z^2$.	[03]	CO3	L3

Gauss's Law: $\oint_S \vec{D} \cdot d\vec{S} = Q_{\text{enclosed}}$

Differential volume element, $\Delta V = \Delta x \Delta y \Delta z$

Volume charge density: $\rho_v = \lim_{\Delta V \rightarrow 0} \frac{Q}{\Delta V} \text{ C/m}^3$

$Q_{\text{enc}} = \rho_v \Delta V = \rho_v \Delta x \Delta y \Delta z$

$\vec{D} = \vec{D}_0(x_0, y_0, z_0)$ is known at the point P_0 at the center.

Differential volume element, $\Delta V = \Delta x \Delta y \Delta z$

Gauss's Law: $\oint_S \vec{D} \cdot d\vec{S} = Q_{\text{enclosed}}$

$$\oint_S \vec{D} \cdot d\vec{S} = \iint_{\text{Front Surface}} \vec{D} \cdot d\vec{S} + \iint_{\text{Back Surface}} \vec{D} \cdot d\vec{S} + \iint_{\text{Left Surface}} \vec{D} \cdot d\vec{S} + \iint_{\text{Right Surface}} \vec{D} \cdot d\vec{S} + \iint_{\text{Top Surface}} \vec{D} \cdot d\vec{S} + \iint_{\text{Bottom Surface}} \vec{D} \cdot d\vec{S}$$

D is constant on each of the surfaces

$$\oint_S \vec{D} \cdot d\vec{S} = D_{\text{front}} \iint_{\text{Front Surface}} d\vec{S} + D_{\text{back}} \iint_{\text{Back Surface}} d\vec{S} + D_{\text{left}} \iint_{\text{Left Surface}} d\vec{S} + D_{\text{right}} \iint_{\text{Right Surface}} d\vec{S} + D_{\text{top}} \iint_{\text{Top Surface}} d\vec{S} + D_{\text{bottom}} \iint_{\text{Bottom Surface}} d\vec{S}$$

If $f(x=0)$ is known, we can find $f(x)$ using Taylor Series Expansion, as given by the expression:

Taylor Series (One Dimensional): At $x=x_0$, $f(x=x_0)$ is known

$$f(x) = f(x_0) + \frac{(x-x_0)}{1!} f'(x_0) + \frac{(x-x_0)^2}{2!} f''(x_0) + \frac{(x-x_0)^3}{3!} f'''(x_0) + \text{higher order terms} \dots$$

If $f(x_0, y_0, z_0)$ is known, we can find $f(x, y, z)$ using Taylor Series Expansion, as given by the expression:

Taylor Series (Three Dimensional):

$$f(x, y, z) = f(x_0, y_0, z_0) + \frac{(x-x_0)}{1!} \frac{\partial f}{\partial x} + \frac{(y-y_0)}{1!} \frac{\partial f}{\partial y} + \frac{(z-z_0)}{1!} \frac{\partial f}{\partial z} + \text{higher order terms}$$

$\vec{D} = \vec{D}_0(x_0, y_0, z_0)$ is known at the point P_0 at the center.

Differential volume element, $\Delta V = \Delta x \Delta y \Delta z$

$\vec{D}_0 = D_{x_0} \hat{a}_x + D_{y_0} \hat{a}_y + D_{z_0} \hat{a}_z$

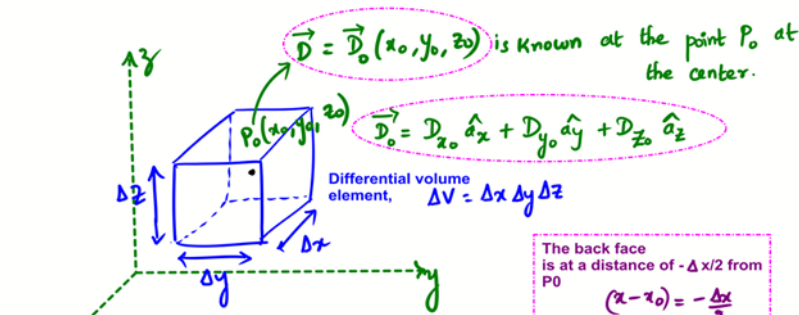
The front face is at a distance of $\Delta x/2$ from P_0
 $\therefore (x-x_0) = \frac{\Delta x}{2}$

Because the surface element is very small, D is essentially constant (over this portion of the entire closed surface) and we have only to approximate the value of Dx at this front face

$D_{\text{front}} = D_{x_0} + \frac{\Delta x}{2} \frac{\partial D_x}{\partial x} + \text{higher order terms}$ (negligible)

Taylor Series (Three Dimensional):

$$f(x, y, z) = f(x_0, y_0, z_0) + \frac{(x-x_0)}{1!} \frac{\partial f}{\partial x} + \frac{(y-y_0)}{1!} \frac{\partial f}{\partial y} + \frac{(z-z_0)}{1!} \frac{\partial f}{\partial z} + \text{higher order terms}$$



Because the surface element is very small, D is essentially constant (over this portion of the entire closed surface) and we have only to approximate the value of D_x at this back face

$$D_{\text{back}} = D_{x_0} - \frac{\Delta x}{2} \frac{\partial D_x}{\partial x}$$

Taylor Series (Three Dimensional):

$$f(x, y, z) = f(x_0, y_0, z_0) + \frac{(x-x_0)}{1!} \frac{\partial f}{\partial x} + \frac{(y-y_0)}{1!} \frac{\partial f}{\partial y} + \frac{(z-z_0)}{1!} \frac{\partial f}{\partial z} + \text{higher order terms}$$

negligible

If we combine these two integrals, we have

$$D_{\text{front}} \iint_{\text{Front Surface}} d\vec{s} + D_{\text{back}} \iint_{\text{Back Surface}} d\vec{s} = \left[D_{x_0} + \frac{\Delta x}{2} \frac{\partial D_x}{\partial x} \right] (\Delta y \Delta z) + \left[D_{x_0} - \frac{\Delta x}{2} \frac{\partial D_x}{\partial x} \right] (-\Delta y \Delta z)$$

$$D_{\text{front}} \iint_{\text{Front Surface}} d\vec{s} + D_{\text{back}} \iint_{\text{Back Surface}} d\vec{s} = \frac{\partial D_x}{\partial x} \Delta x \Delta y \Delta z$$

By exactly the same process we find that,

$$D_{\text{left}} \iint_{\text{Left Surface}} d\vec{s} + D_{\text{right}} \iint_{\text{Right Surface}} d\vec{s} = \left[D_{y_0} + \frac{\Delta y}{2} \frac{\partial D_y}{\partial y} \right] (\Delta x \Delta z) + \left[D_{y_0} - \frac{\Delta y}{2} \frac{\partial D_y}{\partial y} \right] (-\Delta x \Delta z)$$

$$D_{\text{left}} \iint_{\text{Left Surface}} d\vec{s} + D_{\text{right}} \iint_{\text{Right Surface}} d\vec{s} = \frac{\partial D_y}{\partial y} \Delta x \Delta y \Delta z$$

By exactly the same process we find that,

$$D_{\text{top}} \iint_{\text{Top Surface}} d\vec{s} + D_{\text{bottom}} \iint_{\text{Bottom Surface}} d\vec{s} = \left[D_{z_0} + \frac{\Delta z}{2} \frac{\partial D_z}{\partial z} \right] (\Delta x \Delta y) + \left[D_{z_0} - \frac{\Delta z}{2} \frac{\partial D_z}{\partial z} \right] (-\Delta x \Delta y)$$

$$D_{\text{top}} \iint_{\text{Top Surface}} d\vec{s} + D_{\text{bottom}} \iint_{\text{Bottom Surface}} d\vec{s} = \frac{\partial D_z}{\partial z} \Delta x \Delta y \Delta z$$

$$\iint_{\text{Front Surface}} \vec{D} \cdot d\vec{s} + \iint_{\text{Back Surface}} \vec{D} \cdot d\vec{s} = D_{\text{front}} \iint_{\text{Front Surface}} d\vec{s} + D_{\text{back}} \iint_{\text{Back Surface}} d\vec{s} = \frac{\partial D_x}{\partial x} \Delta x \Delta y \Delta z$$

$$\iint_{\text{Left Surface}} \vec{D} \cdot d\vec{s} + \iint_{\text{Right Surface}} \vec{D} \cdot d\vec{s} = D_{\text{left}} \iint_{\text{Left Surface}} d\vec{s} + D_{\text{right}} \iint_{\text{Right Surface}} d\vec{s} = \frac{\partial D_y}{\partial y} \Delta x \Delta y \Delta z$$

$$\iint_{\text{Top Surface}} \vec{D} \cdot d\vec{s} + \iint_{\text{Bottom Surface}} \vec{D} \cdot d\vec{s} = D_{\text{top}} \iint_{\text{Top Surface}} d\vec{s} + D_{\text{bottom}} \iint_{\text{Bottom Surface}} d\vec{s} = \frac{\partial D_z}{\partial z} \Delta x \Delta y \Delta z$$

$$\oint_S \vec{D} \cdot d\vec{s} = \iint_{\text{Front Surface}} \vec{D} \cdot d\vec{s} + \iint_{\text{Back Surface}} \vec{D} \cdot d\vec{s} + \iint_{\text{Left Surface}} \vec{D} \cdot d\vec{s} + \iint_{\text{Right Surface}} \vec{D} \cdot d\vec{s} + \iint_{\text{Top Surface}} \vec{D} \cdot d\vec{s} + \iint_{\text{Bottom Surface}} \vec{D} \cdot d\vec{s}$$

$$\oint_S \vec{D} \cdot d\vec{s} = \left[\frac{\partial D_x}{\partial x} + \frac{\partial D_y}{\partial y} + \frac{\partial D_z}{\partial z} \right] \Delta x \Delta y \Delta z$$

Gauss's Law: $\oiint_S \vec{D} \cdot d\vec{S} = Q_{\text{enclosed}}$

$$\oiint_S \vec{D} \cdot d\vec{S} = \left[\frac{\partial D_x}{\partial x} + \frac{\partial D_y}{\partial y} + \frac{\partial D_z}{\partial z} \right] \Delta x \Delta y \Delta z$$

$$Q_{\text{enc}} = \rho_v \Delta V = \rho_v \Delta x \Delta y \Delta z$$

Equating the two sides of Gauss's Law:

$$\frac{\partial D_x}{\partial x} + \frac{\partial D_y}{\partial y} + \frac{\partial D_z}{\partial z} = \rho_v$$

$$\text{div } \vec{D} = \vec{\nabla} \cdot \vec{D} = \frac{\partial D_x}{\partial x} + \frac{\partial D_y}{\partial y} + \frac{\partial D_z}{\partial z} = \rho_v$$

$\text{div } \vec{D} = \vec{\nabla} \cdot \vec{D} = \rho_v$ Maxwell's First Equation of Electrostatics

This equation is also called Point (Differential) form of Gauss's law

The divergence of the vector flux density \mathbf{A} is the outflow of flux from a small closed surface per unit volume as the volume shrinks to zero.

$$\text{Divergence of } \mathbf{A} = \text{div } \mathbf{A} = \lim_{\Delta v \rightarrow 0} \frac{\oint_S \mathbf{A} \cdot d\mathbf{S}}{\Delta v}$$

$$\text{div } \mathbf{D} = \left(\frac{\partial D_x}{\partial x} + \frac{\partial D_y}{\partial y} + \frac{\partial D_z}{\partial z} \right) \quad (\text{rectangular})$$

$$\text{div } \mathbf{D} = \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho D_\rho) + \frac{1}{\rho} \frac{\partial D_\phi}{\partial \phi} + \frac{\partial D_z}{\partial z} \quad (\text{cylindrical})$$

$$\text{div } \mathbf{D} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 D_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta D_\theta) + \frac{1}{r \sin \theta} \frac{\partial D_\phi}{\partial \phi} \quad (\text{spherical})$$

Gauss's Law: $\oiint_S \vec{D} \cdot d\vec{S} = Q_{\text{enclosed}} = \iiint_V \rho_v \, dv$

Integral Form of Gauss's Law

Gauss's Law: $\text{div } \vec{D} = \vec{\nabla} \cdot \vec{D} = \rho_v$ Maxwell's First Equation of Electrostatics

This equation is also called Point (Differential) form of Gauss's law

Divergence Theorem:

This theorem applies to any vector field for which the appropriate partial derivatives exist.

This theorem can be derived from Gauss's law.

Gauss's Law: $\oiint_S \vec{D} \cdot d\vec{S} = Q_{\text{enclosed}}$

$$\oiint_S \vec{D} \cdot d\vec{S} = Q_{\text{enclosed}}$$

Maxwell's 1st Equation of electrostatics:

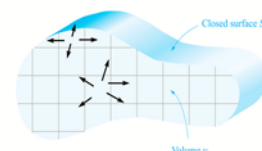
$$\rho_v = \vec{\nabla} \cdot \vec{D}$$

$$\oiint_S \vec{D} \cdot d\vec{S} = Q_{\text{enclosed}} = \iiint_V \rho_v \, dv = \iiint_V \vec{\nabla} \cdot \vec{D} \, dv$$

$$\oiint_S \vec{D} \cdot d\vec{S} = \iiint_V \vec{\nabla} \cdot \vec{D} \, dv$$

Gauss's Divergence Theorem

The divergence theorem states that the total flux crossing the closed surface is equal to the integral of the divergence of the flux density throughout the enclosed volume.

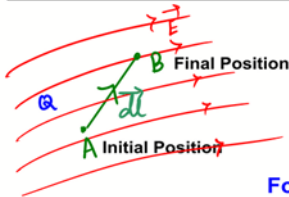


$$\oiint_S \vec{D} \cdot d\vec{S} = \iiint_V \vec{\nabla} \cdot \vec{D} \, dv$$

Gauss's Divergence Theorem

2.(a) Derive an expression for the work done in moving a point charge Q in the presence of an electric field E . [04] CO3 L2

Energy expended in moving a point charge in an electric field - (Work Done)



Work Done, $dW = \vec{F} \cdot d\vec{l}$ J
 $W = \int_{\text{Initial}}^{\text{Final}} \vec{F} \cdot d\vec{l}$

Force on the point charge in the electric field,

$$\vec{F} = q\vec{E}$$

If we attempt to move the test charge against the electric field, we have to exert a force equal and opposite to that exerted by the field, and this requires us to expend energy or do work.

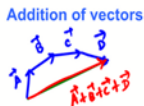
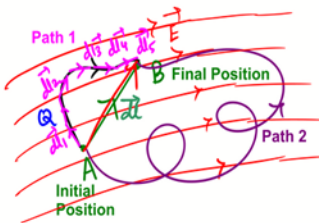
Force applied to move the charge against electric field,

$$\vec{F}_{\text{applied}} = -q\vec{E}$$

Work Done, $dW = -q\vec{E} \cdot d\vec{l}$

$$W = - \int_{\text{Initial}}^{\text{Final}} q\vec{E} \cdot d\vec{l} = -q \int_A^B \vec{E} \cdot d\vec{l} \text{ J}$$

The line integral :



$$dW = -q\vec{E} \cdot d\vec{l}$$

$$dW = -q\vec{E} \cdot d\vec{l}_1 - q\vec{E} \cdot d\vec{l}_2 - q\vec{E} \cdot d\vec{l}_3 - q\vec{E} \cdot d\vec{l}_4 - q\vec{E} \cdot d\vec{l}_5$$

$$dW = -q\vec{E} \cdot (d\vec{l}_1 + d\vec{l}_2 + d\vec{l}_3 + d\vec{l}_4 + d\vec{l}_5)$$

$$dW = -q\vec{E} \cdot d\vec{l}$$

$$W = -q \int_A^B \vec{E} \cdot d\vec{l}$$

* Work done remains same irrespective of the path chosen in moving the charge from A to B

* Work done around a closed path is zero

$$W = -q \oint \vec{E} \cdot d\vec{l} = 0$$

* In general, vectors whose line integral does not depend on the path of integration are called conservative. Thus, E is conservative field.

2.(b) Define electric potential. Prove that electric field intensity is negative potential gradient for electrostatics.

POTENTIAL GRADIENT

Show that electric field is the negative gradient of potential for electrostatics (or) Derive the relation between electric field intensity and electric potential

$$\vec{E} = -\text{grad } V = -\vec{\nabla} V$$

Potential:

$$V = -\int_L \vec{E} \cdot d\vec{l}$$

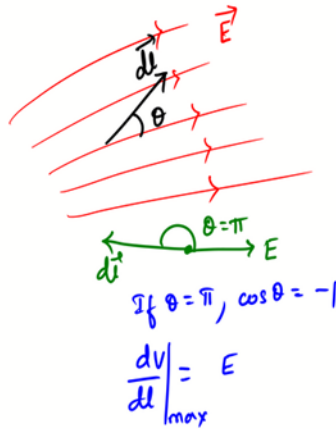
$$dV = -\vec{E} \cdot d\vec{l}$$

$$dV = -|\vec{E}||d\vec{l}|\cos\theta$$

$$\frac{dV}{dl} = -E \cos\theta$$

$$E_{\text{max}} = -\frac{dV}{dl}$$

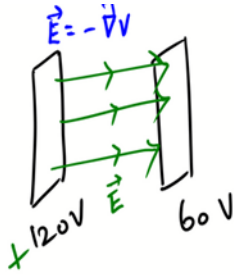
In vector representation, $\vec{E} = -\frac{dV}{dl} \hat{a}_L$ Electric field is in the direction of decreasing potential.



$$\vec{E} = -\text{grad } V = -\vec{\nabla} V$$

Electric field is negative potential gradient

For example,



Electric field is in the direction of decreasing potential.

In Rectangular system,

$$\vec{E} = -\left[\frac{\partial V}{\partial x} \hat{a}_x + \frac{\partial V}{\partial y} \hat{a}_y + \frac{\partial V}{\partial z} \hat{a}_z \right] = -\vec{\nabla} V = -\text{grad } V$$

In Cylindrical system,

$$\vec{E} = -\left[\frac{\partial V}{\partial \rho} \hat{a}_\rho + \frac{1}{\rho} \frac{\partial V}{\partial \phi} \hat{a}_\phi + \frac{\partial V}{\partial z} \hat{a}_z \right] = -\vec{\nabla} V = -\text{grad } V$$

In Spherical system,

$$\vec{E} = -\left[\frac{\partial V}{\partial r} \hat{a}_r + \frac{1}{r} \frac{\partial V}{\partial \theta} \hat{a}_\theta + \frac{1}{r \sin \theta} \frac{\partial V}{\partial \phi} \hat{a}_\phi \right] = -\vec{\nabla} V = -\text{grad } V$$

3.(a) Define current and current density. Derive the expression for equation of continuity of current. [06] CO3 L2

Current and Current Density

The current is defined as a rate of movement of charge passing a given reference point (or crossing a given reference plane) of one Coulomb per second. Current is symbolized by I.

$$I = \frac{dq}{dt} \text{ A}$$

The current density, measured in Amperes per square meter, is a vector flux density represented by J. It is defined as the current per unit cross sectional area.

$$|\vec{J}| = \frac{dI}{ds} \text{ A/m}^2 \quad dI = \vec{J} \cdot d\vec{s}$$

$$I = \iint_S \vec{J} \cdot d\vec{s}$$

Continuity Equation of current (or) Equation of continuity of current

Current flowing out of the given volume V is equal to the rate of decrease in charge within the volume



Charge within the volume V,

$$Q_i = \iiint_V \rho_v dv$$

$$I = -\frac{dQ_i}{dt}$$

$$I = -\frac{d}{dt} \left[\iiint_V \rho_v dv \right]$$

Volume charge density, $\rho_v(x, y, z, t)$

Current Density, $|\vec{J}| = \frac{dI}{ds}$

$$I = \oiint_S \vec{J} \cdot d\vec{s}$$

$$I = -\iiint_V \frac{\partial \rho_v}{\partial t} dv$$

Equating the above two equations,

$$\oiint_S \vec{J} \cdot d\vec{s} = -\iiint_V \frac{\partial \rho_v}{\partial t} dv$$

Using Gauss's Divergence theorem:

$$\oiint_S \vec{J} \cdot d\vec{s} = \iiint_V \vec{\nabla} \cdot \vec{J} dv$$

$$\iiint_V \vec{\nabla} \cdot \vec{J} dv = -\iiint_V \frac{\partial \rho_v}{\partial t} dv$$

$$\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho_v}{\partial t}$$

Equation of continuity of current

3.(b) Calculate volume charge density at the point $P(3, -45^\circ, 5)$, given $D = 5z^2 a_\rho + 10\rho z a_z \frac{C}{m^2}$. [04] CO2 L3

b) $D = 5z^2 a_\rho + 10\rho z a_z$ at $P(3, -45^\circ, 5)$: In cylindrical coordinates, we have

$$\nabla \cdot D = \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho D_\rho) + \frac{1}{\rho} \frac{\partial D_\phi}{\partial \phi} + \frac{\partial D_z}{\partial z} = \left[\frac{5z^2}{\rho} + 10\rho \right]_{(3, -45^\circ, 5)} = 71.67$$

4. A cube is defined by $1 < x, y, z < 1.2$. If $\mathbf{D} = 2x^2y\mathbf{a}_x + 3x^2y^2\mathbf{a}_y \frac{C}{m^2}$. [10] CO2 L3
Evaluate both sides of divergence theorem.

Divergence Theorem:

$$\oint_S \vec{D} \cdot d\vec{s} = \iiint_V \vec{\nabla} \cdot \vec{D} dv$$

LHS

$$\begin{aligned} \Phi = Q = \oint \mathbf{D} \cdot \mathbf{n} da &= \underbrace{\int_1^{1.2} \int_1^{1.2} 2(1.2)^2 y dy dz}_{\text{front}} + \underbrace{\int_1^{1.2} \int_1^{1.2} -2(1)^2 y dy dz}_{\text{back}} \\ &+ \underbrace{\int_1^{1.2} \int_1^{1.2} -3x^2(1)^2 dx dz}_{\text{left}} + \underbrace{\int_1^{1.2} \int_1^{1.2} 3x^2(1.2)^2 dx dz}_{\text{right}} = \underline{0.1028 C} \end{aligned}$$

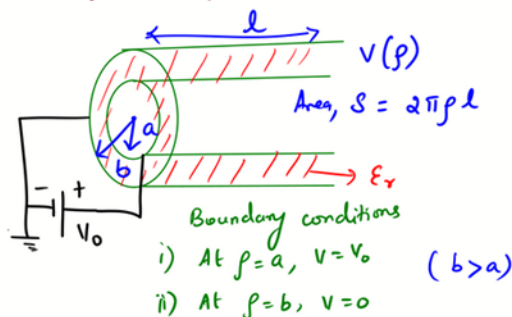
RHS

$$\nabla \cdot \mathbf{D} = [4xy + 6x^2y]$$

$$Q \doteq \nabla \cdot \mathbf{D} \Big|_{\text{center}} \times \Delta v = 12.83 \times (0.2)^3 = \underline{0.1026}$$

5. Using Laplace's equation, derive an expression for capacitance of a coaxial cylindrical capacitor. [10] CO3 L3

2) Coaxial Cylindrical Capacitor:



Laplace's Equation:

$$\nabla^2 V = 0$$

$$\nabla^2 V = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial V}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 V}{\partial \phi^2} + \frac{\partial^2 V}{\partial z^2} = 0$$

Since Potential V is a function of only one dimension 'r', $V(r)$

$$\nabla^2 V = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial V}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 V}{\partial \phi^2} + \frac{\partial^2 V}{\partial z^2} = 0$$

$$\nabla^2 V = \frac{1}{r} \frac{d}{dr} \left(r \frac{dV}{dr} \right) = 0$$

$$\frac{d}{dr} \left(r \frac{dV}{dr} \right) = 0$$

$$\text{Integrating w.r.t. } r \Rightarrow \int \frac{d}{dr} \left(r \frac{dV}{dr} \right) dr = \int 0 dr$$

$$r \frac{dV}{dr} = 0 + C_1$$

$$\frac{dV}{dr} = \frac{C_1}{r}$$

$$\frac{dv}{dp} = \frac{C_1}{p}$$

Integrating w.r.t. $p \Rightarrow \int \frac{dv}{dp} dp = \int \frac{C_1}{p} dp$

$$V = C_1 \ln p + C_2$$

Applying Boundary Conditions to get the constants C_1 and C_2 ,

i) At $p=a, v=V_0 \Rightarrow V_0 = C_1 \ln a + C_2$
 ii) At $p=b, v=0 \Rightarrow 0 = C_1 \ln b + C_2$ ($b > a$)

Solving the above two equations, we get constants C_1 and C_2 ,

$$V_0 - 0 = C_1 \ln a - C_1 \ln b$$

$$-V_0 = C_1 \ln(b/a)$$

$$C_1 = \frac{-V_0}{\ln(b/a)}$$

$$C_2 = -C_1 \ln b$$

$$C_2 = \frac{V_0 \ln b}{\ln(b/a)}$$

i) $V(p) = \frac{-V_0}{\ln(b/a)} \ln p + \frac{V_0 \ln b}{\ln(b/a)}$ V

2) $\vec{E} = -\vec{\nabla}V = -\left[\frac{\partial V}{\partial \rho} \hat{a}_\rho + \frac{1}{\rho} \frac{\partial V}{\partial \phi} \hat{a}_\phi + \frac{\partial V}{\partial z} \hat{a}_z \right]$

$$= -\left[\frac{-V_0}{\ln(b/a)} \frac{1}{\rho} \hat{a}_\rho \right]$$

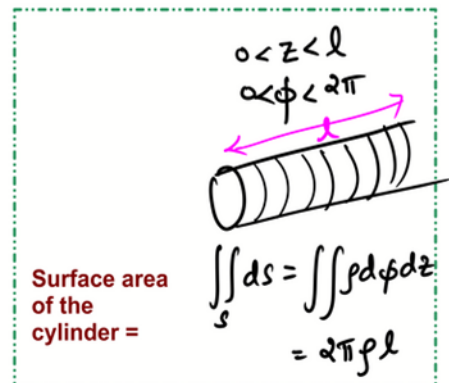
$$\vec{E} = \frac{V_0}{\rho \ln(b/a)} \hat{a}_\rho \quad \text{V/m}$$

3) $\vec{D} = \epsilon_0 \epsilon_r \vec{E} = \frac{\epsilon_0 \epsilon_r V_0}{\rho \ln(b/a)} \hat{a}_\rho$ C/m²

4) $Q = \iint_S \vec{D} \cdot d\vec{s} = \iint_S \frac{\epsilon_0 \epsilon_r V_0}{\rho \ln(b/a)} \hat{a}_\rho \cdot d\vec{s}$

$$Q = \frac{\epsilon_0 \epsilon_r V_0}{\rho \ln(b/a)} \cdot 2\pi \rho l$$

$$Q = \frac{2\pi \epsilon_0 \epsilon_r l V_0}{\ln(b/a)} \quad \text{C}$$



6.(a) Starting from the Gauss's law deduce Poisson's and Laplace's equations. Write [07] CO3 L2
the equations in Cartesian, Cylindrical and Spherical coordinate systems.

Poisson's and Laplace's Equations:

Starting from Maxwell's first equation of electrostatics (Point form of Gauss's Law):

$$\vec{\nabla} \cdot \vec{D} = \rho_V$$

We can make the substitutions,

$$\vec{D} = \epsilon \vec{E}$$

$$\vec{E} = -\vec{\nabla} V$$

For a Linear, Isotropic, Homogeneous Medium, ϵ is constant

$$\vec{\nabla} \cdot (\epsilon \vec{E}) = \rho_V$$

$$\epsilon \vec{\nabla} \cdot \vec{E} = \rho_V$$

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho_V}{\epsilon}$$

$$\vec{\nabla} \cdot (-\vec{\nabla} V) = \frac{\rho_V}{\epsilon}$$

$$\vec{\nabla} \cdot \vec{\nabla} V = -\frac{\rho_V}{\epsilon}$$

Divergence of Gradient of potential function 'V' $\Rightarrow \vec{\nabla} \cdot \vec{\nabla} = \nabla^2$ (Laplacian operator)

Poisson's Equation:

$$\nabla^2 V = -\frac{\rho_V}{\epsilon}$$

Laplace's Equation is a special case of Poisson's Equation, when the region is free of charges.

$$\rho_V = 0$$

$$\nabla^2 V = 0$$

Laplace's Equation

Poisson's and Laplace's Equations in rectangular system:

$$\nabla^2 V = -\frac{\rho_V}{\epsilon}$$

$$\nabla^2 V = 0$$

Divergence of Gradient of potential function 'V' $\Rightarrow \nabla^2 V = \vec{\nabla} \cdot \vec{\nabla} V$

$$\text{grad } V = \vec{\nabla} V = \frac{\partial V}{\partial x} \vec{a}_x + \frac{\partial V}{\partial y} \vec{a}_y + \frac{\partial V}{\partial z} \vec{a}_z$$

$$\text{div } \vec{A} = \vec{\nabla} \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$$

$$\nabla^2 V = \frac{\partial}{\partial x} \left(\frac{\partial V}{\partial x} \right) + \frac{\partial}{\partial y} \left(\frac{\partial V}{\partial y} \right) + \frac{\partial}{\partial z} \left(\frac{\partial V}{\partial z} \right)$$

$$\nabla^2 V = \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2} = -\frac{\rho_V}{\epsilon} \quad \leftarrow \text{Poisson's Equation}$$

$$\nabla^2 V = \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2} = 0 \quad \leftarrow \text{Laplace's Equation}$$

Poisson's and Laplace's Equations in cylindrical system:

$$\nabla^2 V = -\frac{\rho_V}{\epsilon}$$

$$\nabla^2 V = 0$$

Divergence of Gradient of potential function 'V' $\Rightarrow \nabla^2 V = \vec{\nabla} \cdot \vec{\nabla} V$

$$\text{grad } V = \frac{\partial V}{\partial \rho} \vec{a}_\rho + \frac{1}{\rho} \frac{\partial V}{\partial \phi} \vec{a}_\phi + \frac{\partial V}{\partial z} \vec{a}_z$$

$$\text{div } \vec{A} = \vec{\nabla} \cdot \vec{A} = \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho A_\rho) + \frac{1}{\rho} \frac{\partial}{\partial \phi} (A_\phi) + \frac{\partial}{\partial z} (A_z)$$

$$\nabla^2 V = \vec{\nabla} \cdot \vec{\nabla} V = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial V}{\partial \rho} \right) + \frac{1}{\rho} \frac{\partial}{\partial \phi} \left(\frac{1}{\rho} \frac{\partial V}{\partial \phi} \right) + \frac{\partial}{\partial z} \left(\frac{\partial V}{\partial z} \right)$$

$$\nabla^2 V = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial V}{\partial \rho} \right) + \frac{1}{\rho^2} \frac{\partial^2 V}{\partial \phi^2} + \frac{\partial^2 V}{\partial z^2} = -\frac{\rho_V}{\epsilon} \quad \leftarrow \text{Poisson's Equation}$$

$$\nabla^2 V = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial V}{\partial \rho} \right) + \frac{1}{\rho^2} \frac{\partial^2 V}{\partial \phi^2} + \frac{\partial^2 V}{\partial z^2} = 0 \quad \leftarrow \text{Laplace's Equation}$$

$$\nabla^2 v = -\frac{\rho}{\epsilon}$$

$$\nabla^2 v = 0$$

Divergence of Gradient of potential function 'v' $\Rightarrow \nabla^2 v = \vec{\nabla} \cdot \vec{\nabla} v$

$$\text{grad } v = \frac{\partial v}{\partial r} \vec{a}_r + \frac{1}{r} \frac{\partial v}{\partial \theta} \vec{a}_\theta + \frac{1}{r \sin \theta} \frac{\partial v}{\partial \phi} \vec{a}_\phi$$

$$\text{div } \vec{A} = \vec{\nabla} \cdot \vec{A} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 A_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta A_\theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} (A_\phi)$$

$$\nabla^2 v = \vec{\nabla} \cdot \vec{\nabla} v = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial v}{\partial r} \right) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial v}{\partial \theta} \right) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} \left(\frac{1}{r \sin \theta} \frac{\partial v}{\partial \phi} \right)$$

$$\nabla^2 v = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial v}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial v}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v}{\partial \phi^2} = -\frac{\rho}{\epsilon} \quad \leftarrow \text{Poisson's Equation}$$

$$\nabla^2 v = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial v}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial v}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v}{\partial \phi^2} = 0 \quad \leftarrow \text{Laplace's Equation}$$

6.(b) Given potential function $V = x^2 yz + Ay^3 z$. Find A so that Laplace's equation is satisfied. [03] CO3 L3

$$\nabla^2 V = 0$$

$$\frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2} = 0$$

$$\frac{\partial}{\partial x} (2xy^2z) + \frac{\partial}{\partial y} (x^2z + 3y^2Az) + \frac{\partial}{\partial z} (x^2y + Ay^3) = 0$$

$$2y^2z + by^2A = 0$$

$$2y^2(1 + 3A) = 0$$

$$3A = -1$$

$$A = -\frac{1}{3}$$

7.(a) State and prove the Uniqueness theorem. [07] CO3 L2

Uniqueness Theorem:

If a solution to Laplace's equation can be found that satisfies the boundary conditions, then the solution is Unique.

The theorem applies to any solution of Poisson's or Laplace's equation in a given region or closed surface.

Proof:

The theorem is proved by contradiction.

We assume that there are two solutions V_1 and V_2 of Laplace's equation (or Poisson's equation) both of which satisfy the prescribed boundary conditions.

Proof:

If V_1 and V_2 are two different solutions:

case (i)
Poisson's Equation: $\nabla^2 V = -\frac{\rho_v}{\epsilon}$

$\nabla^2 V_1 = -\frac{\rho_v}{\epsilon} \rightarrow (1)$

$\nabla^2 V_2 = -\frac{\rho_v}{\epsilon} \rightarrow (2)$

$(1) - (2) \Rightarrow \nabla^2 V_1 - \nabla^2 V_2 = 0$

case (ii)
Laplace's Equation: $\nabla^2 V = 0$

$\nabla^2 V_1 = 0 \rightarrow (3)$

$\nabla^2 V_2 = 0 \rightarrow (4)$

$(3) - (4) \Rightarrow \nabla^2 V_1 - \nabla^2 V_2 = 0$

$V_1(x, y, z) - V_2(x, y, z) = V_d(x, y, z)$

Differential operator is distributive and hence we can write the above equation as follows:

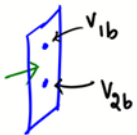
$\nabla^2 (V_1 - V_2) = 0$

(or)

$\nabla^2 V_d = 0 \rightarrow (5)$

Considering the boundary conditions with atleast one conducting boundary,

Conductor surface is equipotential



$V_{1b} = V_{2b}$

$V_{1b} - V_{2b} = 0$

$V_{db} = 0 \rightarrow (6)$

Any Scalar $\rightarrow \alpha(x, y, z)$
Any vector $\rightarrow \vec{A}(x, y, z)$

Vector Identity: $\nabla \cdot (\alpha \vec{A}) = \alpha \nabla \cdot \vec{A} + \vec{A} \cdot \nabla \alpha$

In our case,
 $\alpha = V_d(x, y, z)$
 $\vec{A} = \nabla V_d$


$\nabla \cdot (V_d \nabla V_d) = V_d \nabla \cdot \nabla V_d + \nabla V_d \cdot \nabla V_d$

$\vec{A} \cdot \vec{A} = |\vec{A}|^2$

Integrating the above expression over the volume 'V' enclosed by the closed surface

$\iiint_V \nabla \cdot (V_d \nabla V_d) dV = \iiint_V V_d \nabla^2 V_d dV + \iiint_V |\nabla V_d|^2 dV$

From Eqn (5)



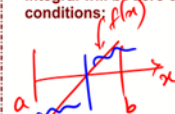
Using Divergence theorem, $\oiint_S \vec{A} \cdot d\vec{s} = \iiint_V \nabla \cdot \vec{A} dV$

$\oiint_S V_d \nabla V_d \cdot d\vec{s} = \iiint_V |\nabla V_d|^2 dV$

From eqn (6) as integration is around the closed surface, which is the boundary itself.

$0 = \iiint_V |\nabla V_d|^2 dV$

Integral will be zero under any one of the below conditions:



$\int_a^b f(x) dx = 0$

i) $f(x) = 0$

ii) $f(x)$ is odd function

But the integrand is a square function, which cannot be odd. Hence Integrand must be zero.

$0 = \iiint_V |\nabla V_d|^2 dV$

$|\nabla V_d|^2 = 0$

$\nabla V_d = 0$

$\nabla V_d = 0$ only if $V_d = \text{constant}$

For equipotential surface (i.e. at the boundary),

$V_d = 0$

$V_1 - V_2 = 0$

$V_1 = V_2$

Thus V_1 and V_2 are not two different solutions. They are both same. Hence Uniqueness Theorem is proved.

- 7.(b) Determine whether or not the given potential field satisfy the Laplace equation: [03] CO3 L3
 $V = \rho^2 + z^2$.

Solution
 Cylindrical system: Laplace's equation $V = \rho^2 + z^2$

$$\nabla^2 V = 0$$

$$\nabla^2 V = \frac{1}{\rho} \left(\frac{\partial}{\partial \rho} \rho \frac{\partial V}{\partial \rho} \right) + \frac{1}{\rho^2} \frac{\partial^2 V}{\partial \phi^2} + \frac{\partial^2 V}{\partial z^2}$$

$$= \frac{1}{\rho} \left(\frac{\partial}{\partial \rho} \left(\rho \cdot \frac{\partial}{\partial \rho} (\rho^2 + z^2) \right) \right) + 0 + \frac{\partial^2}{\partial z^2} (\rho^2 + z^2)$$

$$= \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho \cdot 2\rho) + \frac{\partial}{\partial z} (2z)$$

$$= \frac{1}{\rho} (2 \times 2\rho) + 2$$

$$\nabla^2 V = \boxed{\frac{4+2}{\rho}} = 6 \neq 0$$

V does not satisfy Laplace's equation