

BETCK205H/BETCKH205

Second Semester B.E./B.Tech. Degree Examination, June/July 2024 Introduction to Internet of Things (IOT)

Time: 3 hrs.

USN

Max. Marks: 100

Note: 1. Answer any FIVE full questions, choosing ONE full question from each module. 2. M : Marks, L: Bloom's level, C: Course outcomes.

		Module – 1	M	L	C
0.1	3.		10	1.2	COI
	В.	With a neat diagram, explain the interdependency technology for IOT planes.	10	1.2	COI
	-	OR			1
Q.2	11.	With neat diagram, explain the network communication between two hosts following OSI model.	10	L2	COI
	b.	Explain the interdependencies and reach of IoT over various application domains and networking paradigms.	10	L2	CO1
	12	Module - 2			
Q.3	a.	Outline the basic differences between transducers, sensors and actuators.	6	L2	CO2
	b.	Explain the major factors influence the choice of sensors in IoT based sensing applications.	8	L2	CO2
	c.	Define Sensor and explain the characteristics of sensor.	6	L1	COI
		OR			
Q.4	a,	Classify the sensor based on : i) Power requirements ii) Sensor output iii) Power to be measured.	10	L2	CO2
	ь.	Classify Sensing types on the nature of the environment and the physical sensors.	10	L2	CO2
	12	Module – 3		-	
Q.5	a.	Explain IoT device design and selection considerations.	10	L2	CO2
	b.	What are the parameters considered for off loading the data and identify typical data offload locations available in context of IoT.	10	L2	CO2
	-	OR	-		
Q.6	á.	Explain event detection using onsite, offsite remote processing topology and collaborative processing technology.	10	L2	CO2
	þ.	Classify the data based on how they can be accessed and stored and the importance of processing of loT	10) L2	co
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	-	Module - 4			
Q.7	n.	Explain the classification of virtualization based on the requirements of the user.	6	1.2	CO2
	b.	Explain different types of cloud model.	10	1.2	COI
	ę.	What is SLA and mention its metrics.	4	1.2	CO2
		OR		-	
Q.8	n.	What are the advantages of virtualization?	10	1.2	COI
	b.	Explain different types of cloud simulators with its features.	10	1.2	COL
		Module – 5			
Q.9	a	Explain the different components of health care IoT.	10	1.2	COI
	б.	Explain the architecture and advantages of vehicular IoT.	10	1.2	CO2
		OR			
Q.10	a.	What is Machine Learning? What are the advantages and challenges of Machine Learning?	10	L2	CO
	b.	What are the advantages and risk of health care IoT?	10	L2	CO2

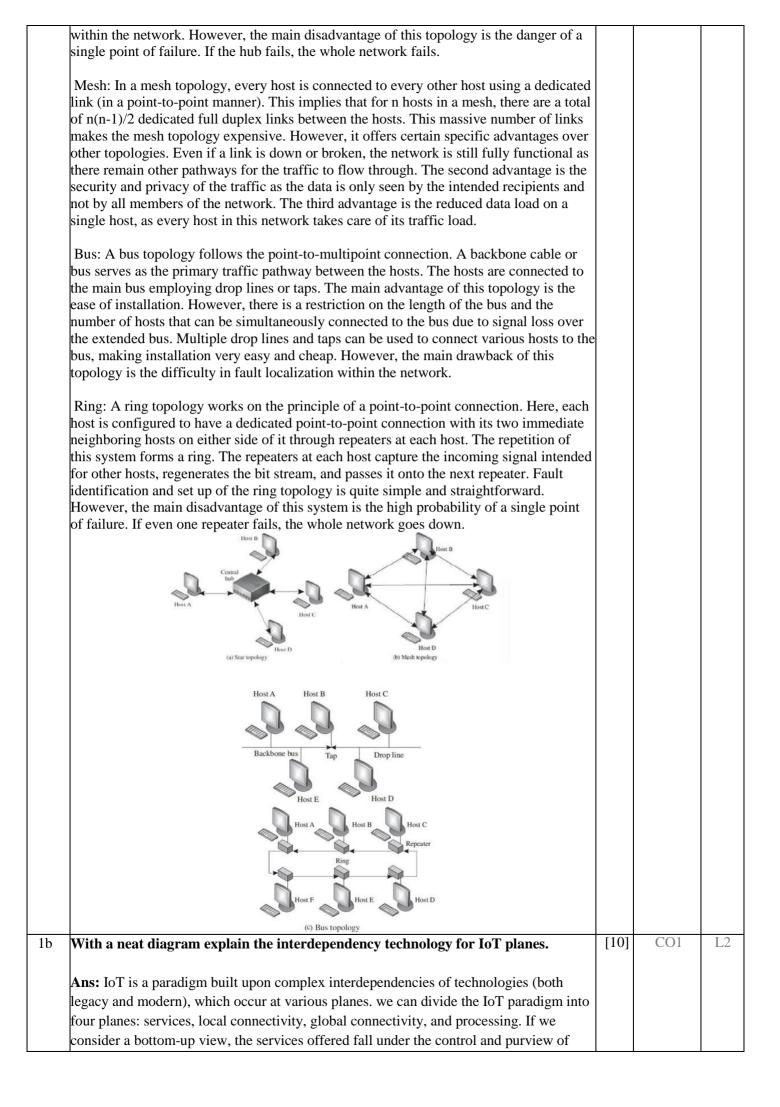
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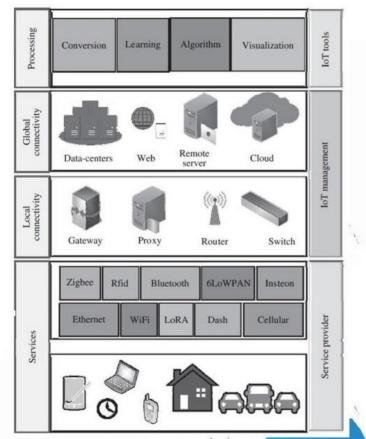
Solution QP – July 2024



Date: Feb 2024 Duration: 3 hours Max Marks: 100 Sec: II OBE	Sub:	Introductio	n to Internet of Things (IOT)	Sub Code:	BETCK205H	Bran ch:	ECE CSE CSD	l,
Ia a. Classify the network types based on Physical topologies and connection types with schematic diagram. [10] CO1 Depending on the way a host communicates with other hosts, computer networks are of two types: Point-to-point and Point-to-multipoint. [10] CO1 I. Point-to-point Point-to-point and Point-to-multipoint. I. Point-to-point connections are used to establish direct connections between two hosts. Day-to-day systems such as a remote control for an air conditioner or television is a point to point connection, where the connection has the whole channel dedicated to it only. These networks were designed to work over duplex links and are functional for both synchronous as well as asynchronous systems. II. Point-to-multipoint: In a point-to-multipoint connection, more than two hosts share the same link. This type of configuration is similar to the one-to-many connection type. Point-to-multipoint connections hose, either spatially or temporally. One common scheme of spatial sharing of the channel is frequency division multiple access (FDMA). Temporal sharing of channels include approaches such as time division multiple access (TDMA). Point to-multipoint connections find popular use in present-day networks, especially while enabling communication between a massive number of connected devices. Image: Point-to-point link Host B Image: Point-to-point link Host B Image: Point-to-multipoint link Host B Image: Point-to-point link Host B Image: Point-to-point link Host B Image: Point-to-point link Host D Image:	Date:	Feb 2024	Duration: 3 hours Max Ma	arks: 100 Sec:	II			
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Host A Host C (b) Point-to-multipoint Depending on the physical manner in which communication paths between the hosts are		two types: P I. Point-to -p between two television is dedicated to functional for multipoint: I This type of multipoint co channel is sh scheme of sp Temporal sh (TDMA). Po especially w devices.	oint-to-point and Point-to-multipoint: Point-to-point connection of hosts. Day-to-day systems sure a point to point connection, we it only. These networks were or both synchronous as well as in a point-to-multipoint connect configuration is similar to the connections find popular use in a ared between the various host boatial sharing of the channel is aring of channels include approximate to -multipoint connections hile enabling communication to -multipoint connections hile enables are consistent to -	Itipoint. Itipoint. Itipoint. Itipoint. Itipoint as a remote control where the connection designed to work over a synchronous system ction, more than two is asynchronous system ction, more than two is one-to-many connect wireless networks at ts, either spatially or if frequency division roaches such as time find popular use in p between a massive m int link Host B Host D Host C Host C Host D Host D Host D	ish direct connections ol for an air conditioner or has the whole channel er duplex links and are ms. II. Point-to- hosts share the same link. ction type. Point-to- nd IP telephony. The temporally. One common multiple access (FDMA). division multiple access present-day networks, number of connected			

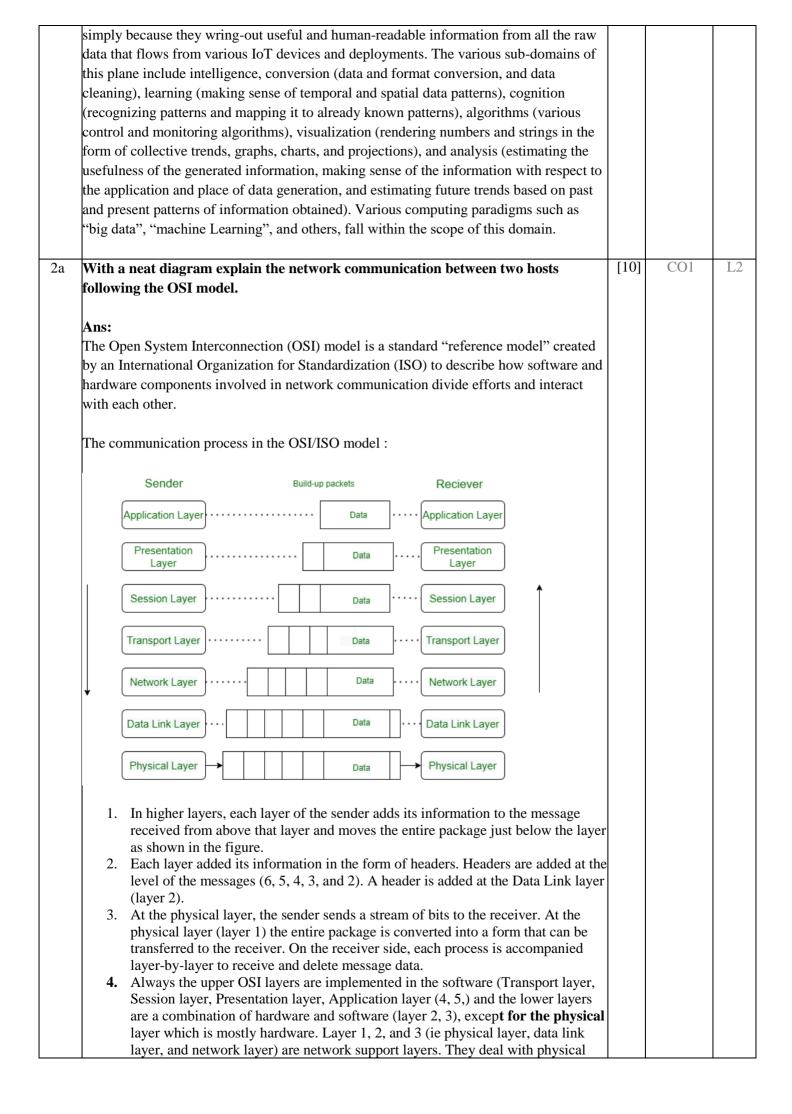


service providers. The service plane is composed of two parts: 1) things or devices and 2) low-power connectivity. Typically, the services offered in this layer are a combination of things and low-power connectivity. The things may be wearables, computers, smartphones, household appliances, smart glasses, factory machinery, vending machines, vehicles, UAVs, robots, and other such contraptions (which may even be just a sensor). The immediate low-power connectivity, which is responsible for connecting the things in local implementation, may be legacy protocols such as WiFi, Ethernet, or cellular. In contrast, modern- day technologies are mainly wireless and often programmable such as Zigbee, RFID, Bluetooth, 6LoWPAN, LoRA, DASH, Insteon, and others. The range of these connectivity technologies is severely restricted; they are responsible for the connectivity between the things of the IoT and the nearest hub or gateway to access the Internet. The local connectivity is responsible for distributing Internet access to multiple local IoT deployments. This distribution may be on the basis of the physical placement of the things, on the basis of the application domains, or even on the basis of providers of services. Services such as address management, device management, security, sleep scheduling, and others fall within the scope of this plan.



gure 9: The IoT planes, various enablers of IoT, and the complex <mark>interdependencies amon</mark>

The local connectivity plane falls under the purview of IoT management as it directly deals with strategies to use/reuse addresses based on things and applications. The modern-day "edge computing" paradigm is deployed in conjunction with these first two planes: services and local connectivity. In continuation, the penultimate plane of global connectivity plays a significant role in enabling IoT in the real sense by allowing for worldwide implementations and connectivity between things, users, controllers, and applications. This plane also falls under the purview of IoT management as it decides how and when to store data, when to process it, when to forward it, and in which form to forward it. The Web, data-centers, remote servers, Cloud, and others make up this plane. The paradigm of "fog computing" lies between the planes of local connectivity and global connectivity. The final plane of processing can be considered as a top-up of the basic IoT networking framework. The members in this plane may be termed as IoT tools



 Explain the interdependencies and reach of IoT over various application domains and networking paradigms. 101 CO1 Liand Control (Line) (Line)	 aspects of moving data such as electrical specifications, physical connections, physical address, and transport time and reliability from one device to another. Layer 4, Transport layer end to end ensures reliable data transmission. 5. Each layer is assumed to handle messages or data from the layers that are above or below it. 6. Thus, each layer takes data from the adjacent layer, Handles it according to these rules, and then sends the processed data to the next layer on the other side. 			
 Technological interdependencies of IoT with other domains and networking paradigms Will Machine to-Machine Paradigm sensing Processing & Actuation - Reduka Markana Markana		[10]	CO1	L2
 Technological interdependencies of IoT with other domains and networking paradigms Will Machine to-Machine Paradigm sensing Processing & Actuation - Reduka Markana Markana	Ans:			
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 Sensing, Processing & Actuation - Readback Mechanis IoE: Internet of Environment Paradigm minimizing & reversing the III-effects of intermet-based technologies Industry 4.0: 4th industrial revolution digitization of manufacturing industry IoP: Internet of People Decentratize Online Social Interactions, Payments, Transactions M2M refers to communications and interactions between machines and devices. These interactions occurs in cloud computing infrastructure M2M refers to communication and interactions between machines and devices. These interactions occurs in cloud computing infrastructure M2M collects data from machinery and sensors, also enabling device management and device interactions via one or more communication networks (e.g., 30, 46, 56, satellite, public networks). M2M is part of the IoT and is considered as one of its sub-domains IoT is vaster than M2M and comprises a broader range of interactions such as the interactions between devices/things, things and people, things and applications, and people with applications; M2M enables the amalgamation of workflows comprising such interactions within IoT. M2M enables the amalgamation of workflows comprising such interactions within IoT. M2M is part of the JOP encompasses sensing, control, actuation and feedback as a package. A digital twin is a vitual system-model relation, in which the system signifies a physical system or equipment or a piece of machinery, while the model represents the mathematical model or representation of the physical system is belavior or operation. A digital twin is used parallel to a physical system, especially in CPS as it allows for the comparison of the physical system or use easily given corrective direction/commands to obtain desirable outputs. A based on feedback from the digital twin, a physical system is on be easily given corrective direction/commands to obtain desirab	M2M: Machine-to-Machine Paradigm Talk Amongst Themselves without Human Interventic			
Internet-based technologies Industry 4.0; 4th industrial revolution digitization of manufacturing industry IoP: Internet of People Description of manufacturing industry Description of the probability of	Sensing, Processing & Actuation - Feedback Mechanis • IOE: Internet of Environment Paradigm			
 IoP: Internet of People Descriptive Online Social Interactions, Payments, Transactions IOT vs M2M M2M refers to communications and interactions between machines and devices. These interactions occurs in cloud computing infrastructure W2M Collects data from machinery and sensors, also enabling device management and device interaction. Telecommunication services providers introduced the term M2M and technically emphasized on machine interactions via one or more communication networks (e.g., 3G, 4G, 5G, satellite, public networks). M2M is part of the IoT and is considered as one of its sub-domains IoT is vaster than M2M and comprises a broader range of interactions such as the interactions between devices/things, things and people, things and applications, and people with applications; W2M enables the amalgamation of workflows comprising such interactions within IoT. VEM enables the amalgamation of workflows comprising such interactions within IoT. A digital twin is a trached to a CPS-based system. A digital twin is a trached to a CPS-based system. A digital twin is a virtual system-model relation, in which the system signifies a physical system requipment or a piece of machinery, while the model represents the mathematical model or representation of the physical system can be easily given corrective directions/commands to obtain desirable outputs. A digital twin is used parallel to a physical system, can be easily given corrective directions/commands to obtain desirable outputs. The IoT paradigm does not compulsorily need feedback or a digital twin system. IoT is more focused on networking than controls. A sub-systems in an IoT environment may include feedback and controls too CPS is also one of the sub-domains of IoT. 	Internet-based technologies CPS Industry 4.0			
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CPS is also one of the sub-domains of IoT.				

		NoT) paradigm enable	s access and control over IoT resources an	d	
		applications are built	using technologies such as HTML 5.0, Java	Script, Ajax,	
	PHP and others.		ne of the key enablers of WoT.	4 M B B	
		and a second second second second second second	PIs enables both developers and deployer irity of existing web technologies without	s to benefit	
	redeploy solutions.				
	 Still, designing and b when trying to build 	uilding the WoT parad a globally uniform Wo	igm has various adaptability and security c T.	hallenges,	
	 As IoT is focused on applications, which do 	creating networks com	prising objects, things, people, systems ar fication aspect and the limitations of the various areas of IoT into the existing Web.	nd Internet the	
	layer.		oplication layer-based hat added over the		
	 However, the scope of systems that are not 	of IoT applications is m accessible through the	uch broader; IoT also which includes non- e web.	IP-based	
a	Outline the basic	differences bet	ween Sensors, Actuators and '	TRansducers.	
			the differences between transducers		
	Paramotors	Transducers	Sensors	Actuators	
	Definition	Converts energy from	Converts various forms of energy into electrical signals.	Converts electrical signals into	
		one form to	energy mus electrical signals.	various forms of	
		another.		energy, typically	
				mechanical	
	Domain	Can be used	It is an input transducer.	energy. It is an output	
	Domain	to represent a	and an any at transacteer.	transducer.	
		sensor as well			
		as an actuator.	** **		
	Function	Can work as a sensor or an	Used for quantifying environmental stimuli into	Used for converting signals	
		actuator but not	signals.	into proportional	
		simultaneously.		mechanical or	
		11		electrical outputs.	
	Examples	Any sensor or actuator	Humidity sensors, Temperature sensors, Anemometers	Motors (convert electrical energy	
		actuator	(measures flow velocity),	to rotary motion),	
			Manometers (measures fluid	Force heads	
			pressure), Accelerometers	(which impose	
			(measures the acceleration of a body), Gas sensors (measures	a force), Pumps (which convert	
			concentration of specific gas or	rotary motion of	
			gases), and others	shafts into either a	
				pressure or a fluid	
				velocity).	
b	Explain the Major	r factors that influ	uence the choice of sensors in Io	oT based sensing	
	applications				
			nsor node is critical and can eith		
	-		The following major factors infl		
	sensors in IoT-bas	sed sensing solut	ions: 1) Sensing range, 2) accur	acy and precision, 3)	
	energy, and 4) dev	vice size.			
	Sensing Range:				
	-	-	ode defines the detection fidelit		
		—	the sensing range in deployment	ts include fixed k-	
	coverage and dyn	-			
	-	-	ds to usher in redundancy as it r		
			of some of which may also ove	-	
	•	-	ncorporates mobile sensor node	-	
		•	solution and may not be deploy	able in all operational	
	areas and terrains	•			

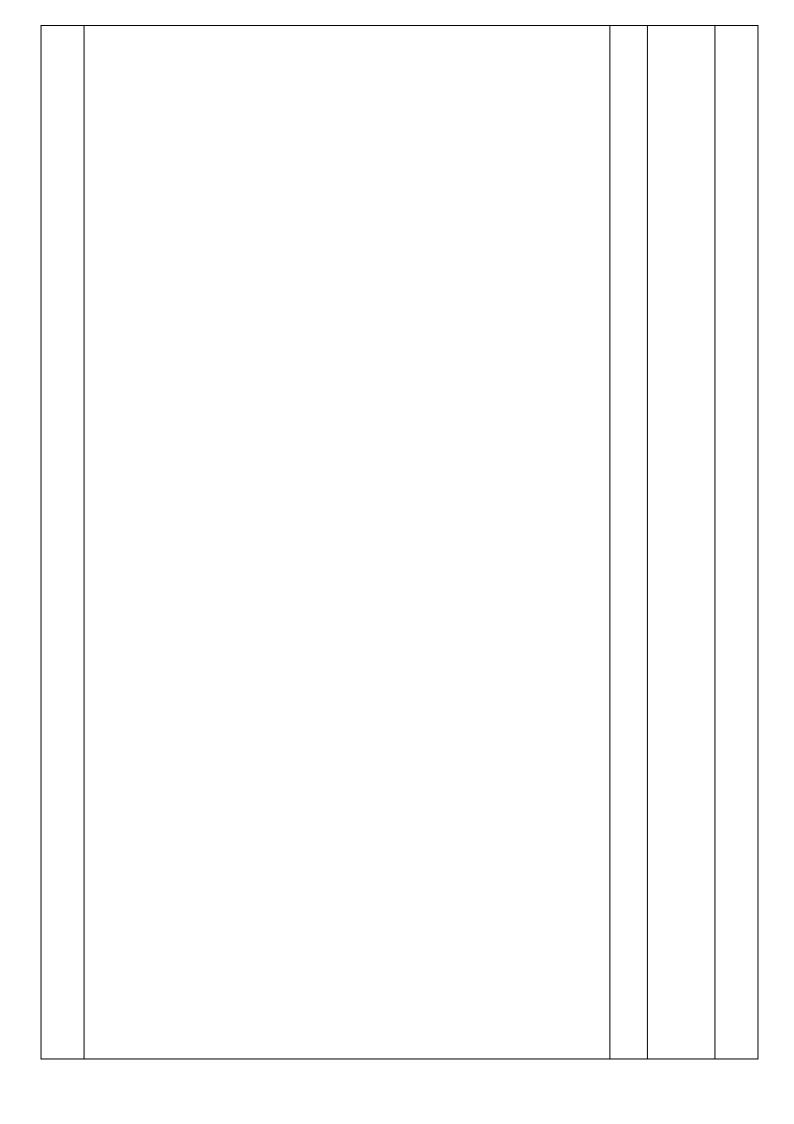
• Additionally, the sensing range of a sensor may also be used to signify the upper and		
lower bounds of a sensor's measurement range.		
• For example, a proximity sensor has a typical sensing range of a couple of meters.		
• In contrast, a camera has a sensing range varying between tens of meters to hundreds		
of meters. As the complexity of the sensor and its sensing range goes up, its cost		
significantly increases.		
Accuracy and Precision:		
• The accuracy and precision of measurements provided by a sensor are critical in		
deciding the operations of specific functional processes.		
• For example, a standard temperature sensor can be easily integrated with conventional		
components for hobby projects and day-to-day applications, but it is not suitable for		
industrial processes.		
• Regular temperature sensors have a very low-temperature sensing range, as well as		
relatively low accuracy and precision. The use of these sensors in industrial applications,		
where a precision of up to 3–4 decimal places is required, cannot be facilitated by these		
sensors. • Industrial sensors are typically very sophisticated, and as a result, very costly.		
However, these industrial sensors have very high accuracy and precision score, even		
under harsh operating conditions.		
Energy • The energy consumed by a sensing solution is equal to determine the		
Energy: • The energy consumed by a sensing solution is crucial to determine the lifetime of that solution and the estimated cost of its deployment. • If the sensor or the		
sensor node is so energy inefficient that it requires replenishment of its energy sources		
quite frequently, the effort in maintaining the solution and its cost goes up; whereas its		
deployment feasibility goes down. ● Consider a scenario where sensor nodes are		
deployed on the top of glaciers. Once deployed, access to these nodes is not possible.		
If the energy requirements of the sensor nodes are too high, such a deployment will not		
last long, and the solution will be highly infeasible as charging or changing of the energy		
sources of these sensor nodes is not an option.		
Device Size: • Most of the applications of IoT require sensing solutions which are so		
small that they do not hinder any of the regular activities that were possible before the		
sensor node deployment was carried out. • Larger the size of a sensor node, larger is the		
obstruction caused by it, higher is the cost and energy requirements, and lesser is its		
demand for the bulk of the IoT applications. • Consider a simple human activity		
detector. If the detection unit is too large to be carried or too bulky to cause hindrance to		
regular normal movements, the demand for this solution would be low. • The wearable		
sensors are highly energy-efficient, small in size, and almost part of the wearer's regular		
wardrobe.		
Classify sensors based on: 1) Power requirement ii) Sensor output iii) Power to be		
measured.		
Ans:		
1) Based upon the power requirement sensors may be of two kinds:		
Dessive sensory it does not need any additional energy source and directly generates an		1
Passive sensor: it does not need any additional energy source and directly generates an		
electric signal in response to an external stimulus. That is, the input stimulus energy is		
electric signal in response to an external stimulus. That is, the input stimulus energy is converted by the sensor into the output signal. Most of passive sensors are direct sensors		
electric signal in response to an external stimulus. That is, the input stimulus energy is converted by the sensor into the output signal. Most of passive sensors are direct sensors as we defined them earlier. Example: a thermocouple, a photodiode, and a piezoelectric		
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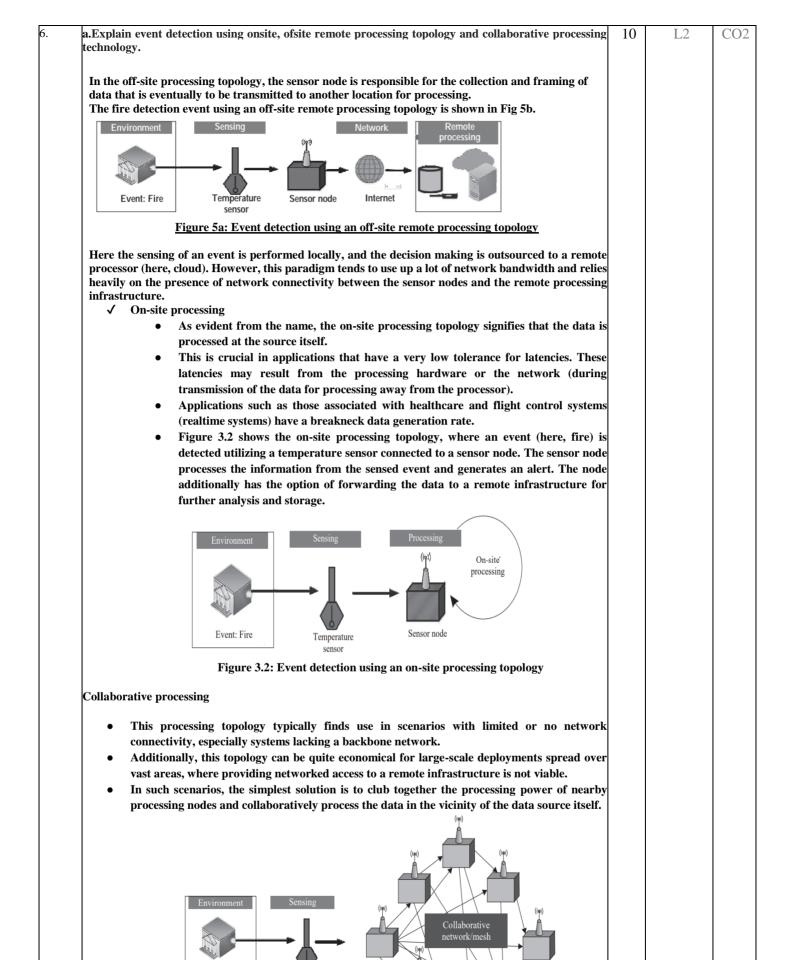
	thermistor is a temperature sensitive resistor. It does not generate any electric signal, but	
	by passing an electric current through it (excitation signal) its resistance can be measured by detecting variations in current and/or voltage across the thermistor.	
	2) Based upon the sensor output, sensors may be of two kinds:	
	Analog Sensors: It produce an output signal which is usually in the form of voltage, current, or resistance, proportional to the measured quantity.	
	Digital Sensors: It provide discrete or digital data as output.	
	3) Based upon the power to be measured sensors may classified as:	
	(i) Physical sensors: Physical sensors measure a physical quantity and convert it into a signal, which can be identified by the user. These sensors can detect envi- ronmental changes, such as force, acceleration, rate of flow, mass, volume, den- sity, and pressure.	
	(ii) Chemical sensors: A chemical sensor is defined as, "a device that converts chemical information into an analytically useful signal ranging from the concentration of a particular sample component to total composition analysis." Chemical sensor is employed to monitor the activity or concentration of the respective chemical species in the gas or liquid phase.	
	(iii) Thermal sensors: A thermal sensor is a device that is used to measure the tem- perature of an environment and transforms the input data into electronic data to record or monitor signal of temperature changes. Examples of temperature sensors include thermocouples, thermistors, and RTDs.	
	(iv) Biological sensors: Biological sensors monitor biomolecular processes, such as antibody/antigen interactions, DNA interactions, enzymatic interactions, or cellular communication processes.	
b	Classify sensing types on the nature of the environment and the physical sensors.	
	Ans: The final classification of the sensors are Analog and Digital, these produce an analog output i.e., a continuous output signal (usually voltage but sometimes other quantities like Resistance etc.) with respect to the quantity being measured. Digital, in contrast to Analog, work with discrete or digital data. The data in digital sensors, which is used for conversion and transmission, is digital in nature.	
	The following is a list of different types of sensors that are commonly used in various applications with examples. All these types are used for measuring one of the physical properties like Temperature, Resistance, Capacitance, Conduction, Heat Transfer etc.	

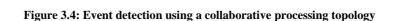
Type of Sensor	Used For		
Temperature Sensor	Controlling HVAC systems in homes and offices		
Proximity Sensor	Detecting objects in automatic doors		
Accelerometer Sensor	Screen orientation in smartphones		
IR Sensor (Infrared Sensor)	Remote controls for TVs and other devices		
Pressure Sensor	Monitoring tire pressure in vehicles		
Light Sensor	Adjusting screen brightness on smartphones		
Ultrasonic Sensor	Parking assistance in cars		
Flow and Level Sensor	Managing water levels in tanks		
Smoke, Gas and Alcohol Sensor	Detecting smoke and gas leaks in homes		
Microphone (Sound Sensor)	Voice recognition in smart speakers		
Touch Sensor	Touchscreens on smartphones and tablets		
Color Sensor	Color detection in industrial sorting machines		
Humidity Sensor	Controlling humidity levels in greenhouses		
Magnetic Sensor (Hall Effect Sensor)	Detecting the position of a rotating object		
Position Sensor	Tracking the position of machine parts		
Tilt Sensor	Detecting the tilt of gaming controllers		
PIR Sensor	Motion detection in security systems		
IoT Device Design and Selection Considerations Size: > This decides the form factor and the energy > The larger the form factor, the larger the energy > The energy requirements of a processor a consideration. > The higher the energy requirements, the large replacement frequency. Cost > The cost is the driving force in deciding the sensor nodes for IoT-based solutions. > The cheaper cost of the hardware enables hardware deployment by users of an IoT solution > For example, cheaper gas and fire detects to include much more sensing hardware for a less IoT Device Design and Selection Considerations Memory: > Features such as local data processing, of formatting and other features rely heavily on the devices. > The memory requirements (both volatile a devices determine the capabilities of the device. > However, devices with higher memory ter reasons.	gy consumption of a sensor node. energy consumption of the are the most important higher the energy source (battery) e density of deployment of s a much higher density of t. ion solutions would enable users ser cost. lata storage, data filtering, data memory capabilities of and non-volatile memory) of IoT		
Processing power: • Processing power decides what type of sensors	and the type of application		

that is accommodated with the IoT device/node, and what processing		
features can integrate on-site with the IoT device.		
Typically, applications that handle video and image data require IoT devices		
with higher processing power as compared to applications requiring simple		
sensing of the environment.		
I/O rating		
• The input–output (I/O) rating of an IoT device is the deciding factor in		
determining the circuit complexity, energy usage, and requirements for		
support of various sensing solutions and sensor types.		
• Newer processors have a meagre I/O voltage rating of 3.3 V, as compared to		
5 V for the somewhat older processors.		
Add-ons		
• The support of various add-ons to a processor like analogue to digital		
conversion (ADC) units, in-built clock circuits, connections to USB and		
ethernet, inbuilt wireless access capabilities and others help in defining the		
robustness and usability of a processor or IoT device in various application		
scenarios.		
 Additionally, these add-ons also decide how fast a solution can be 		
developed, especially the hardware part of the whole IoT application.		
• The presence of these options with the processor makes the processor ordevice highly lucrative to the		
users/ developers.		

b. What are the parameters considered for offloading the data and identify typical data offload locations	[10]	CO2	
available in the context of IOT.	[-•]		L2
There are a few offloading parameters which need to be considered while deciding upon the			
offloading type to choose. □ Bandwidth: The maximum amount of data that can be simultaneously transmitted over			
the network between two points is the bandwidth of that network. The bandwidth of a			
wired or wireless network is also considered to be its data-carrying capacity and often			
used to describe the data rate of that network.			
□ Latency: It is the time delay incurred between the start and completion of an operation.			
In the present context, latency can be due to the network (network latency) or the			
processor (processing latency). In either case, latency arises due to the physical			
limitations of the infrastructure, which is associated with an operation. The operation can			
be data transfer over a network or processing of a data at a processor			
□ Criticality: It defines the importance of a task being pursued by an IoT application. The			
more critical a task is, the lesser latency is expected from the IoT solution. For example,			
detection of fires using an IoT solution has higher criticality than detection of agricultural field parameters. The former requires a response time in the tune of milliseconds,			
whereas the latter can be addressed within hours or even days.			
□ Resources: It signifies the actual capabilities of an offload location. These capabilities			
may be the processing power, the suite of analytical algorithms, and others. For example,			
it is futile and wasteful to allocate processing resources reserved for real-time multimedia			
processing (which are highly energy-intensive and can process and analyze huge volumes			
of data in a short duration) to scalar data (which can be addressed using nominal			
resources without wasting much energy).			
□ Data volume: The amount of data generated by a source or sources that can be			
simultaneously handled by the offload location is referred to as its data volume handling			
capacity. Typically, for large and dense IoT deployments, the offload location should be			
robust enough to address the processing issues related to massive data volume.			





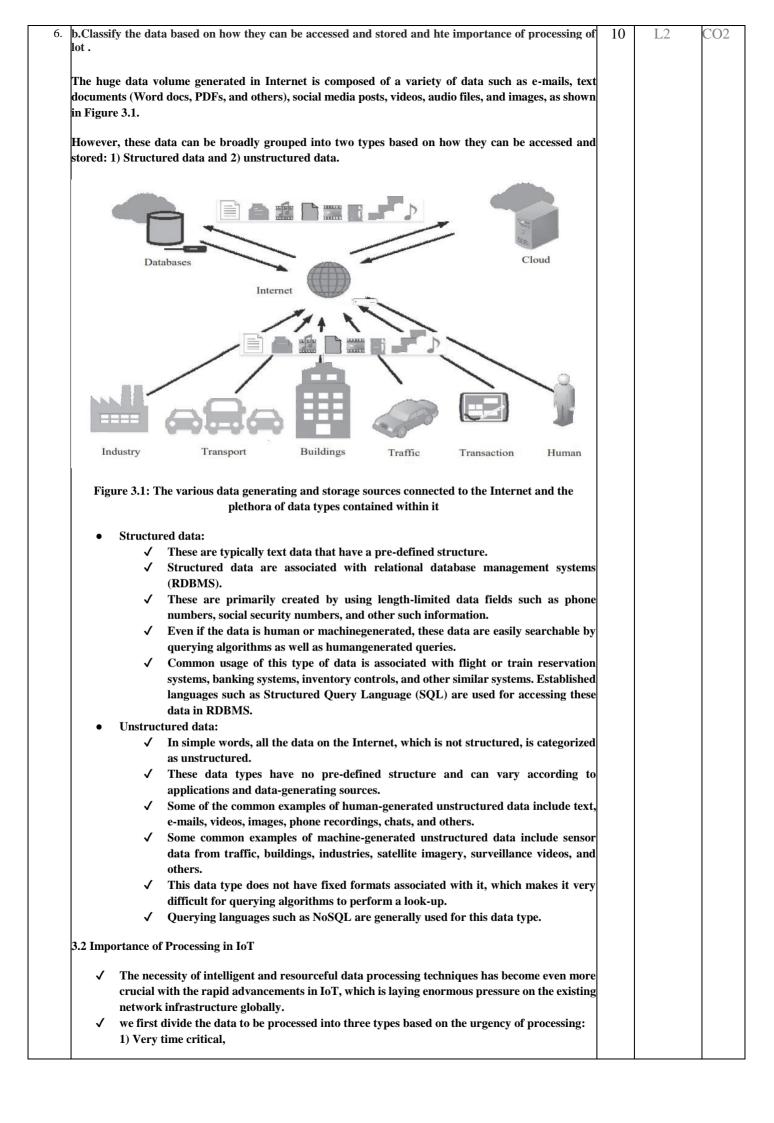


node

Temperature

sensor

Event: Fire



 2) Time critical, and 3) Normal. ✓ Data from sources such as flight control systems, healthcare, and other such sources, which need immediate decision support, are deemed as very critical. These data have a very low threshold of processing latency, typically in the range of a few milliseconds. ✓ Data from sources that can tolerate normal processing latency are deemed as timecritical data These data, generally associated with sources such as vehicles, traffic, machine systems, smarthome systems, surveillance systems, and others, which can tolerate a latency of a few seconds fall in this category. ✓ Finally, the last category of data, normal data, can tolerate a processing latency of a few minutes to a few hours and are typically associated with less data-sensitive domains such as agriculture, environmental monitoring, and others. 	, , ,	L2	CO1

7a	Explain the classification of virtualization based on the requirements of the user.	6	L2	CO2
	 Hardware Virtualization: This type of virtualization indicates the sharing of hardware resources among multiple users. For example, a single processor appears as many different processors in a cloud computing architecture. Storage Virtualization: In storage virtualization, the storage space from different entities are accumulated virtually, and seem like a single storage location. 			
	 Application Virtualization: A single application is stored at the cloud end. However, as per requirement, a user can use the application in his/her local computer without ever actually installing the application. 			
	 Desktop Virtualization: This type of virtualization allows a user to access and utilize the services of a desktop that resides at the cloud. The users can use the desktop from their local desktop. 			
7b	Explain different types of cloud model.			
	 As per the National Institute of Standards and Technology (NIST) [1] and Cloud Computing Standards Roadmap Working Group, the cloud model can be divided into two parts: 	10	L2	CO1
	Service model and			
	Deployment model			
	Further the service model is categorized as:			
	Software-as-a-Service (SaaS),			
	Platform-as-a-Service (PaaS), and			
	 Infrastructure-as-a-Service (IaaS). On the other hand, the deployment model is further categorized as: 			
	Private cloud,			
	Community cloud,			
	Public cloud, and			
	 Hybrid cloud. Software-as-a-Service (SaaS): This service provides access to different software applications to an end user through Internet connectivity. Ex : Google Workspace, Dropbox, Salesforce 			
	 Platform-as-a-Service (PaaS): PaaS provides a computing platform, by which a user can develop and run different applications. Ex: AWS Elastic Beanstalk, Windows Azure, Heroku, Force.com, Google App Engine 			
	 Infrastructure-as-a-Service (IaaS): IaaS provides infrastructure such as storage, networks, and computing resources. A user uses the infrastructure without purchasing the software and other network components. Google Compute Engine (GCE) 			

		Ι	
Service model Platform-as-a-service Infrastructure-as-a-service Private cloud			
Deployment model - Community cloud Hybrid cloud			
Figure 10.4 Cloud model			
Deployment Model			
 Private Cloud: This type of cloud is owned explicitly by an end user organization. The internal resources of the organization maintain the private cloud. Community Cloud: This cloud forms with the collaboration of a set of 			
organization has some shared interests.			
 Public Cloud: The public cloud is owned by a third party organization, which provides services to the common public. The service of this cloud is available for any user, on a payment basis. 			
Hybrid Cloud: This type of cloud comprises two or more clouds (priva public, or community)	te,		
What is SLA and mention its metrics.	4	L2	CO2
 The most important actors in cloud computing are the end user/custo and CSP. 	mer		
 Cloud computing architecture aims to provide optimal and effic services to the end users and generate revenue from them as per t usage. 			
• Therefore, for a clear understanding between CSP and the customer at the services, an agreement is required to be made, which is know service-level agreement (SLA).			
• An SLA provides a detailed description of the services that will be rece by the customer.	ived		
 Customer Point of View: Each CSP has its SLA, which contains a deta description of the services. If a customer wants to use a cloud serv he/she can compare the SLAs of different organizations. Therefor customer can choose a preferred CSP based on the SLAs. 	/ice,		
• CSP Point of View: In many cases, certain performance issues may o for a particular service, because of which a CSP may not be able to pro			

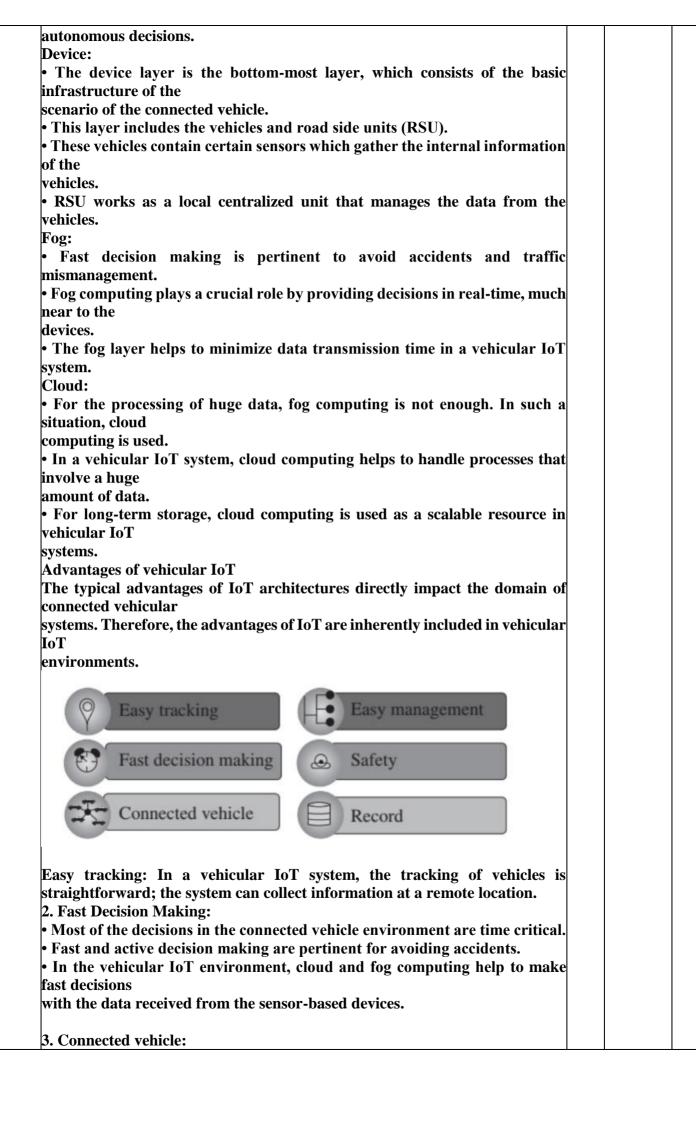
the services efficiently. Thus, in such a situation, a CSP can explicitly mention in the SLA that they are not responsible for inefficient service.	7		
 Availability: This metric signifies the amount of time the service will be accessible for the customer. 			
• Response Time: The maximum time that will be taken for responding to a customer request is measured by response time.			
• Portability: This metric indicates the flexibility of transferring the data to another service.			
 Problem Reporting: How to report a problem, whom and how to be contacted, is explained in this metric. Penalty: The penalty for not meeting the promises mentioned in the SLA. 			
What are advantages off virtualization?	10	L2	CO1
Advantages for End Users			
Variety: The process of virtualization in cloud computing enables an end user organization to use various types of applications based on the requirements.			
Availability: Virtualization creates a logical separation of the resources of multiple entities without any intervention of end users.	-		
Portability: Portability signifies the availability of cloud computing services from anywhere in the world, at any instant of time.			
 Elasticity: Through the concept of virtualization, an end user can scale-up or scale-down resource utilization as per requirements. Resource Utilization: Typically, a CSP in a cloud computing architecture procures resources on their own or get them from third parties. These resources are distributed among different users dynamically as per their requirements. 			
• Effective Revenue Generation: A CSP generates revenue from the end users based on resource utilization.			
Applications (APP) APP APP APP Operating system (OS) Virtualization software			
(a) Desktop (b) Virtualization			
Figure 10.2 Traditional desktop versus virtualization			
Explain different types of cloud simulation with its features.			
Cloud simulation			
Real deployment of the cloud is a complex and costly procedure.			

Thus, there is a requirement for simulating the system through a cloud simulator before real implementation.	
There are many cloud simulators that provide pre-deployment test services for repeatable performance evaluation of a system.	
Typically, a cloud simulator provides the following advantages to a customer:Pre-deployment test before real implementation	
System testing at no cost	
Repeatable evaluation of the system	
Pre-detection of issues that may affect the system performance	
Flexibility to control the environment	
CloudSim:	
 Description: CloudSim is a popular cloud simulator that was developed at the University of Melbourne. This simulator is written in a Java-based environment. 	
 In CloudSim, a user is allowed to add or remove resources dynamically during the simulation and evaluate the performance of the scenario. Features: CloudSim has different features, which are listed as follows: 	
(1) The CloudSim simulator provides various cloud computing data centers along with different data center network topologies in a simulation environment.	
(2) Using CloudSim, virtualization of server hosts can be done in a simulation.	
(3) A user is able to allocate virtual machines (VMs) dynamically.	
(4) It allows users to define their own policies for the allocation of host resources to VMs.	
(5) It provides flexibility to add or remove simulation components dynamically.	
(6) A user can stop and resume the simulation at any instant of time.	
CloudAnalyst:	
 Description: CloudAnalyst [4] is based on CloudSim. This simulator provides a graphical user interface (GUI) for simulating a cloud environment, easily. The CloudAnalyst is used for simulating large-scale cloud applications. 	
(b) Features:	
(1) The CloudAnalyst simulator is easy to use due to the presence of the GUI.	
(2) It allows a user to add components and provides a flexible and high level of configuration.	
(3) A user can perform repeated experiments, considering different parameter values.	
• (4) It can provide a graphical output, including a chart and table.	
GreenCloud:	

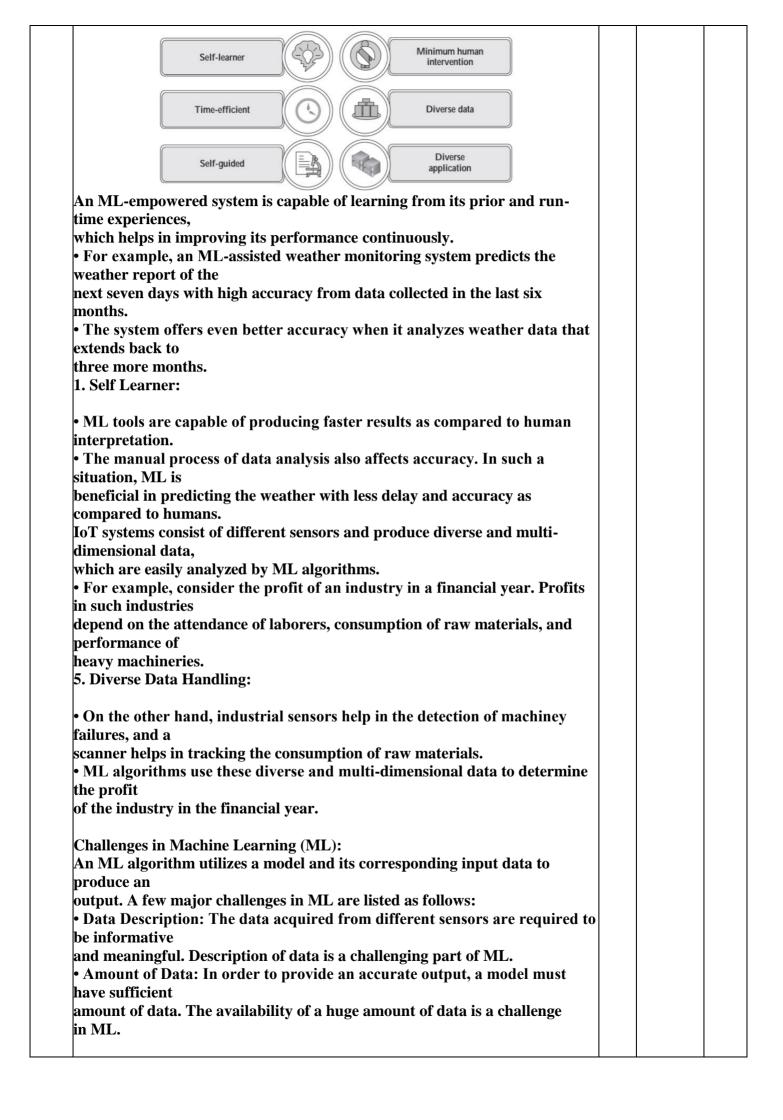
network simulator, NS2. This simulator can monitor the energy consum different network components such as servers and switches.		
(b) Features:		
(1) GreenCloud is an open-source simulator with user-friendly GUI.		
(2) It provides the facility for monitoring the energy consumption of the and its various components.	network	
(3) It supports the simulations of cloud network components.		
(4) It enables improved power management schemes.		
(5) It allows a user to manage and configure devices, dynamically, in sim	ulation.	

 1. Sensors: Layer 1 mainly consists of physiological sensors that collect the physiological parameters of the patient. Few commonly used physiological sensors and their uses are depicted in Table 1. 2. Wireless Connectivity: The communication between the wearable sensors and the LPU is through either wired or wireless communication between the physiological sensors and LPU occurs with the help of Bluetooth and ZigBee. The wireless connectivity: The communication between the LPU and the cloud or server takes place with Internet connectivity such as WiFi and WLAN. Sensors Sensors Sensors Sensors LPU and LPU to cloud/server Wireless connectivity Transmit data from sensors to LPU and LPU to cloud/server Wireless connectivity Secure the sensitive health data Privacy and security Secure the sensitive health data Cloud and for computing Store the data for short-term and long-term basis for future use Interface Provide an easy-access the application For example, when a service is received by a cellphone, it uses GSM (global system for server); Moreover, between LPU and the server/cloud, different networking devices work via network hops (from one networked device to another) to transmit the data. If any of these devices are compromised, it may result in the theft of health data aptient, leading to serious security breaches and custure is a network hops (from one networked device to another) to transmit the data. If any of these devices are compromised, it may result in the theft of health data for a patient, leading to serious security breaches and custure is an entryption and protection schemes. 	 I. Sensors: Layer 1 mainly consists of physiological sensors that collect the physiological parameters of the patient. Few commonly used physiological sensors and their uses are depicted in Table 1. 2. Wireless Connectivity: The communication between the wearable sensors and the LPU is through either wired or wireless communication between the physiological sensors and LPU occurs with the help of Bluetooth and ZigBee. The wireless communication between the LPU and the cloud or server takes place with Internet connectivity such as WiFi and WLAN. Sensors Sensors Sensors Sensors to LPU and LPU to cloud/server Sensors Sensors Security Secure the sensitive health data Privacy and security Secure the sensitive health data Privacy and security Secure the sensitive health data Cloud and for computing Store the data for short-term and long-term basis for future use Interface Provide an easy-access the application For example, when a service is received by a cellphone, it uses GSM (global system for mobile communications). On the other hand, if the same service is received on a desktop, it can be through Ethernet or Wi-Fi. Privacy and Security: Moreover, hetween LPU and the server/cloud, different networking devices work via (network hops (from one networked device to another) to transmit the data. If any of these devices are compromised, it may result in the theft of health data appleterion in the data data of appleterion the data data and playsuits. In order to increase the security of the healthcare data encryption and protection 	components that work together	Things) consists of various interconnected to provide efficient, real-time healthcare	10	L2	CO1
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	• A vehicular IoT system provides an opportunity to remain connected and share information			
	among different vehicles.			
	4. Easy management:			
	• Vehicular IoT systems consist of different types of sensors, a communication unit, processing			
	devices, and GPS, the management of the vehicle becomes easy.			
	 The connectivity among different components in a vehicular IoT enables systems to track 			
	every activity in and around the vehicle.			
	• IoT infrastructure helps in managing the huge number of users located at			
	different			
	geographical coordinates.			
	5. Safety:			
	• With easy management of the system, both the internal and external sensors			
	placed at			
	different locations play an important role in providing safety to the vehicle,			
	its occupants, as			
	well as the people around it.			
	6. Record:			
	• Storing different data related to the transportation system is an essential			
	component of a			
	vehicular IoT.			
	• The record may be of any form, such as video footage, still images, and			
	documentation.			
	• By taking advantage of cloud and fog computing architecture, the vehicular			
	IoT systems			
	•			
	keep all the required records in its database.			
10	10 a. Machine Learning:	10	L2	CO2
- •	• The term "machine learning" was coined by Arthur Lee Samuel, in 1959.			
	• Machine learning as a "field of study that gives computers the ability to			
	learn without			
	being explicitly programmed".			
	• ML is a powerful tool that allows a computer to learn from past			
	experiences and its			
	mistakes and improve itself without user intervention.			
	• To this end, different ML models play a crucial role in designing intelligent			
	systems in IoT by			
	systems in IoT by leveraging the massive amount of generated data and increasing the			
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• Selection of Model: Multiple models may be suitable for serving a particular purpose.			
However, one model may perform better than others. In such cases, the			
proper selection of			
the model is pertinent for ML. • Erroneous Data: A dataset may contain noisy or erroneous data. On the	10	L2	CO2
other hand, the learning of a model is heavily dependent on the quality of data. Since			
erroneous data misleads the ML model, its identification is crucial.			
• Quality of Model: After the selection of a model, it is difficult to determine			
the quality of the selected model. However, the quality of the model is essential in an ML-			
based system.			
10 b. Risk in Healthcare IoT			
In a healthcare IoT system, there are multiple risks as well. 1. Loss of Connectivity:			
• Intermittent connectivity may result in data loss, which may result in a life-			
threatening situations for the patient.			
Loss of Connectivity			
Security risk			
• Proper and continuous connectivity is essential in a healthcare IoT system. 2. Security:			
 The healthcare system must keep the data confidential. On the other hand, different persons and devices are associated with a 			
healthcare IoT system. In such a system, the risk of data tampering and unauthorized			
access is quite high. 3. Error:			
• In the healthcare system, errors in data may lead to misinterpretation of symptoms			
and lead to the wrong diagnosis of the patient.			
• It is a challenging task to construct an error-free healthcare IoT architecture.			