

CI CCI HOD

Q 1 a) Solve by using Find-S Algorithm

Solution:

No. Page No. step 1 Initialize in to most specific Ayporthesis There are 6 avhibutes so for each attribute we initially fill of $A = \langle \phi, \phi, \phi, \phi, \phi, \phi, \phi \rangle$ step 2 Generalize initial hypothesis for first the instance of is the instance so generalise most specific hypothesis. 21 79 yes Ex Good fast yes $h₂$ y is a f y step 3 scan the next instance I It is tre so include it & math each attribute if nomatch then put g $72 - 79 - 44$ $h = \langle \gamma q \gamma q \gamma q q q q q q \rangle$ sagn 83 8+ is negative so exclude it 4 hypothesis remains same without any change $94 - 79 - 99 - 98 = 100 - 11$ so this is final hypothesis generated by find s algorithm

Q 1 b) List and Explain Perspectives and Issues in Machine Learning [5] **Perspective 2M and Issues 3M**

Solution:

- One useful perspective on machine learning is that it involves searching a very large space of possible hypotheses to determine one that best fits the observed data and any prior knowledge held by the learner.
- The learner's task is thus to search through this vast space to locate the hypothesis that is most consistent with the available training examples.
- **Issues in Machine Learning**
- What algorithms exist for learning general target functions from specific training examples?
- In what settings will particular algorithms converge to the desired function, given sufficient training data?
- Which algorithms perform best for which types of problems and representations?
- How much training data is sufficient?
- What general bounds can be found to relate the confidence in learned hypotheses to the amount of training experience and the character of the learner's hypothesis space?
- When and how can prior knowledge held by the learner guide the process of generalizing from examples?
- Can prior knowledge be helpful even when it is only approximately correct?
- What is the best strategy for choosing a useful next training experience, and
- how does the choice of this strategy alter the complexity of the learning problem?
	- Q 2) How you will design a Learning System? Explain with example [10] 2M each Step Steps are as follows:
		- Choosing the Training Experience Choosing the Target Function Choosing a Representation for the Target Function Choosing a Function Approximation Algorithm The Final Design **Choosing the Training Experience**
		- The first design choice we face is to choose the type of training experience from which our system will learn.
		- The type of training experience available can have a significant impact on success or failure of the learner
		- One key attribute is whether the training experience provides direct or indirect feedback regarding the choices made by the performance system.
		- For example, in learning to play checkers, the system might learn from *direct* training examples consisting of individual checkers board states and the correct move for each.
		- Alternatively, it might have available only *indirect* information consisting of the move sequences and final outcomes of various games played.
		- A second important attribute of the training experience is the degree to which the learner controls the sequence of training examples.
		- For example, the learner might rely on the teacher to select informative board states and to provide the correct move for each.

Choosing the Target Function

choose Targer tu steel Target Bunchan, V(b) Roard state -> b legal moves set -> B $b \rightarrow v(b)$ = 100 win state $b \rightarrow \sqrt{(b)}$ = -100 loss state v(b) = a draw state If is is not zinal state in the gen. then v(b)= v(i) where b'in the best binal board state that can be
achieved starting more in can be beer binal board state that can be
achieved starting from band play. optimally

Choosing a Representation for the Target Function
Step 2 choosing Representation for _{Targe} $SHP3$ $x_1 = no_0$ of black pieces on board
 $x_2 = 1 -$ Red $x_1 =$ $x_1 = n_0$ of black pieces on board
 $x_2 = n_1 - \text{Red}$
 $x_3 = n_0$ of black kings on board
 $x_4 = -1$ Red -1 -
 $x_5 = n_0$ of black pieces threatend $x_{6} = \frac{324}{7!}$ Red $4₁$ black $\hat{v}(b) = w_0 + w_1x_1 + w_2x_2 + w_3x_3 +$ $\omega_{L}\tau_{L}+\omega_{S}\tau_{S}+\omega_{S}\tau_{c}$ where $w_1 + w_6$ are coefficients or algorithm wo a additive constant to board value.

Choosing a Function Approximation Algorithm

over 4 choosing function Approximation degovithm o Estimating training values a Adjusting the weights In this step we need a set of training examples. It is a ordered pair (b, V(b)) eq. pollocoing training example describes board state b in which black has wen the game for which terrget zuⁿ Valye Vtain (b) = +100 It is associated with values assigned to intermediate states

+ Adjusting the weights a) are need crequire) an algo. That will a) ar wed crequire) an also. That will
incrementally refine the weights as no training example become available training example become available by Rule is as follows $\omega_{i} \leftarrow \omega_{i} + n \, (V_{\text{high}}(\epsilon) - \hat{V}(\epsilon)) \; r_{i}$ or each training example (b, Vraining) use cument weights to calculate Vhain(h) n is small constant "Which Vtrain(b) - Vhan(b) = 0 then no weight change. ") if very long what is a whole than each
weight is increased. weight is increased. **The Final Design**
The Final Design
The Final Design

- Performance System is the module that must solve the given performance task, in this case playing checkers, by using the learned target function(s).
- It takes an instance of a new problem (new game) as input and produces a trace of its solution (game history) as output.
- **The Critic** takes as input the history or trace of the game and produces as output a set of training examples of the target function
- The **Generalizer** takes as input the training examples and produces an output hypothesis that is its estimate of the target function.
- **Experiment Generator** takes as input the current hypothesis (currently learned function) and outputs a new problem (i.e., initial board state) for the Performance System to explore.
- Its role is to pick new practice problems that will maximize the learning rate of the overall system.

Q 3) Apply ID3 algorithm for constructing Decision Tree for the following training example

Solution:

 $\overline{1}$

Rasic algo extension - $c4.5$ Decision Tree 003 Algoritors which whibute fire Here first an have to gind man" informal root node 4 then build the tree Values coutlook) = sunny, overcast, Roch Bur first we have to collulate 2+ is denoted as 's 1 formula 4 0.3576 $3 = [94, 5-]$ rotal = 14 9 = 9 responses are the $S - 2$ $S - 4$ $V = 2$ \rightarrow $S = - \frac{9}{14} \left[\frac{3a}{14} - \frac{5}{14} \right]$ $= 6.642$
 $= 0.35717$ $|s = 0.94|$ Now calculate Energy of Sunny, overcase of Fat, S_{Sunny} \leftarrow total S $[\frac{1}{2}t, 3-]$ $\frac{2}{5}$ or $\left(S_{s_{unn}}\right) = -\frac{2}{5}$ $\log_{2} \frac{2}{5} = \frac{3}{5}$ $\log_{2} \frac{3}{5}$ $= 0.971$ Sovercast \leftarrow total 4 [4+0] Source = $\frac{4}{4}$ $109\frac{4}{3} - \frac{0}{4}$ $109\frac{4}{4}$

Stain & total = $5\text{ }5^{+12-}$ $\int cos (Srain) = -\frac{3}{9}log_2 \frac{3}{4} - \frac{2}{5}log_2 \frac{1}{4}$ $= 0.971$ Gain (s, outlook) = Entroly $157 - \mathcal{I} = \begin{bmatrix} s_y \\ s_y \end{bmatrix}$ = Entry S = $\frac{5}{14}$ x Entro Ssunny = $\frac{4}{14}$ Entro $-\frac{5}{14}$ Entro (Srain) = 0.94 - $\frac{5}{14} \times 0.971 - \frac{4}{14} \times 0 - \frac{5}{14} \times 0.971$ $= 0.2464$ Inf^m_{far} In similar way calculate Ensory Da attribute Temp, Humidity, Wind $Tem_{p} = S = 0.94$ $S_{HJL} = 1.0 - i\ell$ the $k - \kappa$ are equal then $value = 1.0$ $Smith = 0.9183$ $S_{Cf, d1} = 0.8113$

New dataser becomes excluding avertook day rome Humidity wind play Jonnie
1 Hot Ligh weak No rumido , which is trong
thigh Strong
thigh weak NO $\begin{array}{c}\n\mu \sigma \rightarrow \\
m \uparrow \uparrow d \\
\cos \rho\n\end{array}$ $H₃$ \mathcal{R} H_0 α Normal areat yes Normal Strong yes 11 mild S_{Sung} = $5L2+3-7$ Entroity (Ssyon) = = $\frac{2}{5}$ soq ($\frac{2}{5}$) = $\frac{3}{5}$ sm_a({ $= 0.97$ Temp Hot, Mild, cool $S_{hot} = 2 [D7, 2-] = 0$ $Entropy(Shgr) = 0$ $Smilal = 2$ $C1+, 1-7 = 1$ $S = [-6 + 7] = 10052$ $Gain(Ssum, Temp) = converge - \frac{2}{5}xBmin$ $-\frac{2}{5}$ Entroited $-\frac{1}{5}$ Entro cost $0.97 - \frac{2}{5} \times 0 - \frac{2}{5} \times 1 - \frac{1}{5} \times 0$ $= 0.97 - 0 - \frac{2}{5} - 0$ $20.97 - 0.4 =$ 0.57

attibule Hymidity - High Morman Bo elson becomes become book Rain overcast C_{1100} $Snormal = 2 [24, 0 -] - 20$ \mathbf{I} $\overline{ }$ $\sqrt{ }$ Yes $\overline{\mathbf{3}}$ $\sqrt{H_{umidl+4}}$ $Gain = 0.97 - \frac{3}{5} \times 5 \text{high} - \frac{2}{5} \text{Snyrma}$ romp Hunt wind $8 - 7$ \int_{0}^{∞} seigh a reigh $min d$ $-20.97 - \frac{3}{5} \times 0 - \frac{2}{7} \times 0$ 04 $d + d$ $d | 3238$ 05 cord Hormal W.
06 cord Hormal &
010 mild Hormal W.
011 mild stight & Normal Co_d yes Normal S N $\sqrt{44n} = 0.97$ N° \overline{u} Temps mild cool autribute wind. Strong, weak $S_{rain} = S C 3 + 2 S_{strong} = 2$ [H, 1-] = 1 $\int 6nt \arctan x^2 dx = -\frac{3}{2} \arctan x (\frac{6}{2}) - \frac{2}{2} \arctan x (\frac{2}{2} - \frac{2}{3} \arctan x)$ $S_{\text{check}} = 3 [\sqrt[4]{7}, 2-3]$ $S_{mid} = 3 [2^{+}, 1-]$ $8 = -\frac{1}{3}log_2\frac{1}{3} - \frac{2}{3}log_2\frac{2}{3}$ $\frac{2}{3}log_{2}(\frac{2}{3})-\frac{1}{3}log_{2}(\frac{1}{3})$ 0.9183 0.9183 = 2 C_1 + $[-3]$ = 1-0 $\pi a_0 h = 0.97 - \frac{2}{5}x1 - \frac{2}{5}x^0$ 9183 $= 0.97 - \frac{2}{3} \times 0.9163 - \frac{2}{3} \times 1.0$ $= 0.97 - 0.4 - 0.6 \times 0.9183$ $0 - 0192$ $(6a)h = 0.019$

Q 4 a) Explain different types of Machine Learning and Main Challenges of Machine Learning [Types 3 M Challenges 2 M]

• There are so many different types of Machine Learning systems that it is useful to classify them in broad categories based on:

- Whether or not they are trained with human supervision (supervised, unsupervised, semisupervised, and Reinforcement Learning)
- Whether or not they can learn incrementally on the fly (online versus batch learning)
- Whether they work by simply comparing new data points to known data points, or instead detect patterns in the training data and build a predictive model, much like scientists do (instance-based versus model-based learning)
- In *supervised learning*, the training data you feed to the algorithm includes the desired solutions, called *labels*
- In *unsupervised learning*, as you might guess, the training data is unlabeled.
- The system tries to learn without a teacher.
- Some algorithms can deal with partially labeled training data, usually a lot of unlabeled data and a little bit of labeled data. This is called *semisupervised learning*
- Reinforcement Learning: The learning system, called an *agent* in this context, can observe the environment, select and perform actions, and get *rewards* in return (or *penalties* in the form of negative rewards
- It must then learn by itself what is the best strategy, called a *policy*, to get the most reward over time.
- A policy defines what action the agent should choose when it is in a given situation.
- **Main Challenges of ML**
- Insufficient Quantity of Training Data
- Nonrepresentative Training Data
- Poor-Ouality Data
- Irrelevant Features
- Overfitting the Training Data
- Underfitting the Training Data
- Testing and Validating

Q 4 b) Explain the concept of Entropy and Information Gain Solution

In order to define information gain precisely, we begin by defining a measure commonly used in information theory, called *entropy,* that characterizes the (im)purity of an arbitrary collection of examples.

Given a collection S, containing positive and negative examples of some target concept, the entropy of S relative to this boolean classification is

$Entropy(S) \equiv -p_{\oplus} \log_2 p_{\oplus} - p_{\ominus} \log_2 p_{\ominus}$

where p, is the proportion of positive examples in S and p, is the proportion of negative examples in S. In all calculations involving entropy we define 0 log 0 to be 0.

To illustrate, suppose S is a collection of 14 examples of some Boolean concept, including 9 positive and 5 negative examples (we adopt the notation [9+, **5-]** to summarize such a sample of data). Then the entropy of S relative to this boolean classification is

$Entropy([9+, 5-]) = -(9/14) log₂(9/14) - (5/14) log₂(5/14)$

$= 0.940$

Given entropy as a measure of the impurity in a collection of training examples, we can now define a measure of the effectiveness of an attribute in classifying the training data. The measure we will use, called *information gain,* is simply the expected reduction in entropy caused by partitioning the examples according to this attribute. More precisely, the information gain, *Gain(S, A)* of *an* attribute **A,** relative to a collection of examples *S,* is defined as

$$
Gain(S, A) \equiv Entropy(S) - \sum_{v \in Values(A)} \frac{|S_v|}{|S|} Entropy(S_v)
$$

where *Values(A)* is the set of all possible values for attribute A, and *S,* is the subset of S for which attribute A has value v (i.e., $S = \{s \in SIA(s) = v\}$)

Q 5) Define Following Terms:

- a) Concept Learning
- b) Version Space
- c) Consistent Hypothesis
- d) General Boundary
- e) Specific Boundary

Concept Learning:

Version Space:

A hypothesis *h* is **consistent** with a set of training examples *D* of target concept *c* if and only if $h(x)=c(x)$ for each training example in *D*.

$$
Consistent(h, D) \equiv (\forall \in D) h(x) = c(x)
$$

The **version space**, *VSH,D*, with respect to hypothesis space *H* and training examples *D*, is the subset of hypotheses from *H* consistent with all training examples in *D*.

 $\mathcal{W}\mathcal{S}_{H,D} \equiv \{h \in H \mid Consistent\left(h,D\right)\}$

Example Version Space

G: $\{ \langle 2, ?, \text{Round}, ?, ? \rangle \langle 3, ? \rangle \}$

 $\langle 2,2,2\rangle$ Round, $2,1$ Yes $\langle 2,1\rangle$ Triangle, Round, $2,2$, $\langle 2,1\rangle$ Triangle, $2,2$, $\langle 1,2\rangle$ Yes

S; $\{ \langle .2, \text{Triangle}, \text{Round}, ? \text{Yes} \rangle \}$

Representing Version Spaces

The **General boundary**, G, of version space *VSH,D* is the set of its maximally general members.

The **Specific boundary**, S, of version space V_{SHD} is the set of its maximally specific members.

Consistent Hypothesis:

We need to take the combination of sets in 'G' and check that with 'S'. When the combined set fields are matched with fields in 'S', then only that is included in the version space as consistent hypothesis

General Boundary:

The **General boundary**, G, of version space *VSH,D* is the set of its maximally general members.

Every member of the version space lies between General and Specific boundaries

$$
VS_{H,D} = \{ h \in H \mid (\exists s \in S)(\exists g \in G)(g \ge h \ge s) \}
$$

where $x \geq y$ means x is more general or equal to y

Specific Boundary:

The **Specific boundary**, S, of version space *VSH,D* is the set of its maximally specific members.

Q 6) Explain Candidate Elimination Algorithm with Example

 $G =$ maximally general hypotheses in H S = maximally specific hypotheses in *H* For each training example *d*, do If *d* **is a positive example** Remove from G any hypothesis that does not include *d* For each hypothesis *s* in S that does not include *d* Remove *s* from S Add to S all minimal generalizations *h* of *s* such that 1. *h* includes *d*, and 2. Some member of G is more general than *h* Remove from S any hypothesis that is more general than another hypothesis in S If *d* **is a negative example** Remove from S any hypothesis that does include *d* For each hypothesis *g* in G that does include *d* Remove *g* from G Add to G all minimal generalizations *h* of *g* such that 1. *h* does not include *d*, and

2. Some member of S is more specific than *h* Remove from G any hypothesis that is less general than another hypothesis in G If G or S ever becomes empty, data not consistent (with H)

Elimination nt No siyporthosis Candidate openitive $\sqrt{ }$ $\mathbf{q}_{t_{n}}$ $d \not\!$ Myportesis 訓 \mathbb{Z} General $\sqrt{ }$ a. $, 1$ $\frac{1}{1}$ ϵ $\bar{\gamma}$ د. e ? ? ?? indermediate \hat{S} $\overline{}$ Nexsion space - 2+ 4 movement. ڡ λ \mathcal{L} مــا $\frac{1}{2}$ $\sqrt{ }$ \overline{v} $\overline{}$ پ s and &
s and &
sf example/record is the theo $\hat{\mathcal{E}}$ s and G $\overset{\circ}{\leq}$ \wedge $\overline{\mathcal{E}}$ af example/record in the ones
af example/record s => & CTUP to by مب \cup $\frac{1}{\sqrt{2}}$ $\widetilde{\mathcal{E}}$ ه is -ve, theo of record Gris. (bottom to. up) \overline{M} \bigwedge move from طأ ్త \sum ϕ ϕ ϕ ϕ \sim $\frac{1}{2}$ $s_{0} = \langle \phi \phi$ ೊ Page No.: $9 2 1)$ \sim \vee ree $40 = 49$ $\overline{9}$ م 81 = < s w N . s w s > ف ú ڂ ع م $G = C199991)$ λ خ $\overline{\delta}$ م $\overline{\mathcal{L}}$ $\sqrt{2}$ S $S₂$ 250 Ω 42 221 222 S W S S W S $c2$ WE $G_3 = 8 5599999$ 2201199 Ar Kray $\left.\begin{array}{c|c} \hline \left\langle \begin{array}{c} \hline \end{array}\right\rangle & \hline \end{array}\right\} \hline$ H_{α}