

Internal Assessment Test 2 – Dec 2024

CI CCI HOD

Internal Assessment Test 2 – Nov 2024 Solution

a) What is dynamic hashing? Explain the following techniques with examples:. Dynamic hashing using directories

Directory less dynamic hashing

Solution: Dynamic hashing is a hashing technique that allows the hash table to grow and shrink dynamically as the data changes. It efficiently handles scenarios where the data set size is unpredictable, preventing excessive memory usage or frequent rehashing.

Dynamic Hashing Using Directories

In this technique, a directory (array of pointers) is used to manage access to the buckets. The directory size can grow or shrink as necessary. A hash function determines the index in the directory, and the directory points to corresponding buckets. The technique is commonly implemented using **extendible hashing**.

Process

- 1. **Hash Function:** A bit-string hash function is used (e.g., taking the first d bits).
- 2. **Directory:** Points to buckets, where the buckets store records.
- 3. **Splitting Buckets:** When a bucket overflows, only that bucket splits, and the directory adjusts accordingly.
- 4. **Doubling Directory:** If all buckets at a given level are full, the directory size doubles to accommodate new data.

Advantages

- Efficient memory use.
- Handles overflows with minimal rehashing

Directory-Less Dynamic Hashing

This technique eliminates the directory and directly manages data in buckets using techniques like **linear hashing**.

Process 1. **Buckets:** Organized sequentially. 2. **Hash Function:** A series of hash functions, h0,h1,h2,…, is applied as the table grows. 3. **Bucket Splitting:** When a bucket overflows, the next bucket in the sequence splits, redistributing records based on the next-level hash function. 4. **Pointerless:** No directory; pointers are internal to buckets. **Advantages** • No additional memory overhead for directories. ● Simpler structure compared to directory-based methods. b) Construct the hash table to insert the keys: 7, 24, 18, 52, 36, 54, 11, 23 in a chained hash table of 9 memory locations. Use $h(k) = k \text{ mod } m$. Solution: $h(7)=7$ mod $9=7$ $h(24)=24$ mod 9=6 $h(18)=18$ mod 9=0 h(52)=52mod  9=7 $h(36)=36$ mod $9=0$ $h(54)=54$ mod $9=0$ $h(11)=11$ mod $9=2$ $h(23)=23 \text{mod } 9=5$ $\overline{36}$ 54 \circ $\overline{18}$ \mathbf{I} $\overline{11}$ $\overline{2}$ $\overline{\mathbf{3}}$ 4 $\overline{23}$ 5 $\overline{24}$ $\overline{6}$ 52 $\overline{\mathcal{F}}$ $\overline{\mathcal{F}}$ $\overline{8}$ 6 a) Define min Leftist tree. Meld the given min leftist trees \overline{c} $\overline{}$ 50 \mathbf{R} 80 10 13 20 18 15

Solution: A **Min Leftist Tree** is a type of binary tree designed for efficient priority queue operations, adhering to two key properties: the **Min-Heap Property** and the **Leftist Property**. The Min-Heap Property ensures that the key value at any node is smaller than or equal to the keys of its children, maintaining a hierarchical ordering. The Leftist Property requires that the **Null Path Length (NPL)** of the left child is always greater than or equal to the NPL of the right child, promoting a structure with a shorter right spine for efficient merging. The NPL of a node is defined as the length of the shortest path from the node to a null child, with a null node having an NPL of −1-1−1. These properties collectively ensure that Min Leftist Trees are balanced and optimized for operations like melding, insertion, and deletion.

Megge 50 $\widehat{(\mathcal{R})}$ Condition 10 Add left side $\n *next*\n$

b) Explain the optimal binary search tree with a suitable example.

Solution: An Optimal Binary Search Tree (OBST), also known as a Weighted Binary Search Tree, is a binary search tree that minimizes the expected search cost. In a binary search tree, the search cost is the number of comparisons required to search for a given key. In an OBST, each node is assigned a weight that represents the probability of the key being searched for. The sum of all the weights in the tree is 1.0. The expected search cost of a node is the sum of the product of its depth and weight, and the expected search cost of its children.

