

U	JSN													CELEBRAN		
			In	terna	al As	ssessn	nent T	est 1 /	Answer se	cheme	& Solutions -	- October 2	024			GRADE BY HAAC
Sul	b:	DEEP LEA	RNIN	G							Sub Code:	21CS743	Bra	nch:	AInDS	
Da	te:	16/10/2024	16/10/2024 Duration:			n: 90 minutes Max Marks: 50			50	Sem	VII	<u> </u>		(	OBE	
	Answer any FIVE Questions								MARK	СО	RBT					
		Explain the d	lifferei	nt pa							er within diff	erent AI		S		
1		<ul> <li>Explain the different parts of an AI system relate to each other within different AI</li> <li>disciplines.</li> <li>A computer can reason about statements in these formal languages automatically using logical inference rules. This is known as the knowledge base. (2 Marks)</li> <li>AI systems need the ability to acquire their own knowledge, by extracting patterns from raw data. This capability is known as machine learning.(2 Marks)</li> <li>A representation learning algorithm can discover a good set of features for a simple task in minutes.(2 Marks)</li> <li>Deep learning allows the computer to build complex concepts out of simpler concepts.(2 Marks)</li> <li>Diagram (2 Marks)</li> <li>Explain in Detail about Probabilistic Supervised Learning and non-probabilistic supervised</li> </ul>								[10]	1	L3				
										· .						
2		<b>Explain in Det</b> <b>learning.</b> <b>Probabilistic S</b> To find the bess We have alread p(y   x) A distribution of be between 0 and squash the outpoint probability: p(y = This approach is k-nearest neight time, when we to x in the traint training set decision tree - I the decision tree - I	Superv t paran ly seen ; $\theta$ ) = 1 over a l nd 1. C out of th 1   x; $\theta$ is know stic sup bors - want to ing dat oreaks	<b>fised I</b> neter $\nabla$ that I N (y; binary Due w he line the line $T = \sigma(w)$ the second second pervise there the X. Y	Lean vect linea $\theta = x$ y var var to ear f ( $\theta T x$ logi is no duce We	rning for $\theta$ for ar regreent T, I) riable to solv function stic reference then r	( <b>5 Ma</b> or a par ression is sligh e this p on into egressic <b>ing</b> . ( <b>5</b> en really utput y eturn th	arks) rametri corres atly ma problem the in the in <b>5 Mar</b> l y a tra for a manual for a manual he ave	ric family sponds to ore compl m is to use tterval (0, <b>ks</b> ) ining stag new test in trage of th	of dist the fan licated, e the lo 1) and e or lea nput x, e corre	ributions p(y   nily because its m ogistic sigmoid interpret that arning process we find the k- sponding y va	x; θ). ean must alw function to value as a . Instead, at t nearest neig lues in the	vays est hbors	[10]	2	L3
3		List The Histo 1.Deep learning philosophical v 2.Deep learning 3.Deep learning and software) f 4.Deep learning time. (4 *1 = 4)	rical T g has h iewpoi g has b g mode or deep g has so )	ad a l ints, a ecom els hav p learn olved	long and l ie me ve g ning l inci	and r nas wa ore us rown ; has i reasin	ich hist axed ar seful as in size mprove gly cor	tory, b id war the ar over t ed. nplica	ned in pop mount of a time as co	oularity availab mputer cations	le training data infrastructure with increasin	a has increas (both hardwa gaccuracy ov	ed. are ver	[4]	1	L2
	b	Explain the Ko Deep Learning i) Deep learnin labeled exampl Diagram (1 M ii) Since the int every 2.4 years Diagram (1 M	g g algor es per lark) roduct .(2 ma	rithm catego ion of	will ory f hid	gener ( <b>2 m</b> a	rally ac a <b>rks</b> )	hieve	acceptabl	e perfo	ormance with a	around 5,000		[6]		

The SVD is helpful to show that PCA results in a diagonal $Var[z]$	The SVD is helpful to show that SVD of $\boldsymbol{X}$ , we can express the variant $\operatorname{Var}[\boldsymbol{x}] = \frac{1}{m}$ $= \frac{1}{m}$ $= \frac{1}{m}$ where we use the fact that $\boldsymbol{U}^{\top}\boldsymbol{U} = \frac{1}{m}$ decomposition is defined to be orthogonal we can ensure that the covariance of $\operatorname{Var}[\boldsymbol{z}] = \frac{1}{m}$ $= \frac{1}{m}$	gular vectors of $\boldsymbol{X}$ . To see this, let nposition $\boldsymbol{X} = \boldsymbol{U}\boldsymbol{\Sigma}\boldsymbol{W}^{\top}$ . We then $\boldsymbol{W}$ as the eigenvector basis: $\boldsymbol{W}^{\top} \Big)^{\top} \boldsymbol{U}\boldsymbol{\Sigma}\boldsymbol{W}^{\top} = \boldsymbol{W}\boldsymbol{\Sigma}^{2}\boldsymbol{W}^{\top}$ . At PCA results in a diagonal Var[ $\boldsymbol{z}$ iance of $\boldsymbol{X}$ as: $\frac{1}{-1}\boldsymbol{X}^{\top}\boldsymbol{X}$ $\frac{1}{-1}(\boldsymbol{U}\boldsymbol{\Sigma}\boldsymbol{W}^{\top})^{\top}\boldsymbol{U}\boldsymbol{\Sigma}\boldsymbol{W}^{\top}$ $\frac{1}{-1}\boldsymbol{W}\boldsymbol{\Sigma}^{\top}\boldsymbol{U}^{\top}\boldsymbol{U}\boldsymbol{\Sigma}\boldsymbol{W}^{\top}$ $\frac{1}{-1}\boldsymbol{W}\boldsymbol{\Sigma}^{2}\boldsymbol{W}^{\top}$ , <b>i</b> because the $\boldsymbol{U}$ matrix of the si- nogonal. This shows that if we tak- of $\boldsymbol{z}$ is diagonal as required: $\frac{1}{n-1}\boldsymbol{Z}^{\top}\boldsymbol{Z}$ $\frac{1}{n-1}\boldsymbol{W}^{\top}\boldsymbol{X}^{\top}\boldsymbol{X}\boldsymbol{W}$	[10]	2	L2
$= \frac{m-1}{m-1} \boldsymbol{\Sigma}^2,$	n in				
(6 Marks)       (6 Marks)         5       a         Learning is our means of attaining the ability to perform the task (1 Mark)         Examples : Classification ,Regression,Transcription,Machine Translation etc (4 Marks)	11		[5]	1	L2

		Explain Deep Feedforward Networks in detail.			
		Deep feedforward networks, also often called feedforward neural networks, or multilayer			
		perceptrons (MLPs), are the quintessential deep learning models. ( <b>2 Marks</b> )			
	h	Linear models also have the obvious defect that the model capacity is limited to linear functions,	[5]	2	L2
	U	so the model cannot understand the interaction between any two input variables. To extend linear	[5]	2	L2
		models to represent nonlinear functions of x, we can apply the linear model not to x itself but to a			
		transformed input $\varphi(x)$ , then how to choose the mapping $\varphi$ . (3 Marks)			
		What is Gradient-Based Learning ?Explain about Cost Function.			
		For feedforward neural networks, it is important to initialize all weights to small random values. The biases may be initialized to zero or to small positive values. The iterative gradient-based			
		optimization algorithms used to train feedforward networks and almost all other deep models.train			
		models such as linear regression and support vector machines with gradient descent too, and in			
		act this is common when the training set is extremely large. (3 Marks)			
	a	In most cases, our parametric model defines a distribution $p(y   x; \theta)$ and we simply use the	[5]	2	L3
		principle of maximum likelihood. This means we use the cross-entropy between the training data			
		and the model's predictions as the cost function, where rather than predicting a complete			
		probability distribution over y, we merely predict some statistic of y conditioned on x. Specialized			
		loss functions allow us to train a predictor of these estimates. The total cost function used to train			
		a neural network will often combine one of the primary cost functions described here with a			
-		regularization term. (2 Marks)			
-		Explain Softmax Units for Multinoulli Output Distributions.			
6		linear layer predicts unnormalized log probabilities:			
		z = WT h + b			
		where $z_i = \log \tilde{P}(y = i   x)$ . The softmax function can then exponentiate and normalize z to obtain			
		the desired y <sup>^</sup> . Formally, the softmax function is given by $softmax(z)i = exp(zi) / \sum exp(zj)$ .			
		to maximize log P ( $y = i; z$ ) = log softmax(z)i. Defining the softmax in terms of exp is natural			
		because the log in the log-likelihood can undo the exp of the softmax:			<b>T</b> 0
	b	$logsoftmax(z)i=zi-log(j\sum exp(zj))$	[5]	2	L3
		To see that the softmax function responds to the difference between its inputs, observe that the			
		softmax output is invariant to adding the same scalar to all of its inputs:			
		softmax(z) = softmax(z + c).			
		Using this property, we can derive a numerically stable variant of the softmax:			
		softmax(z) = softmax(z - imaxzi) (5 Marks)			