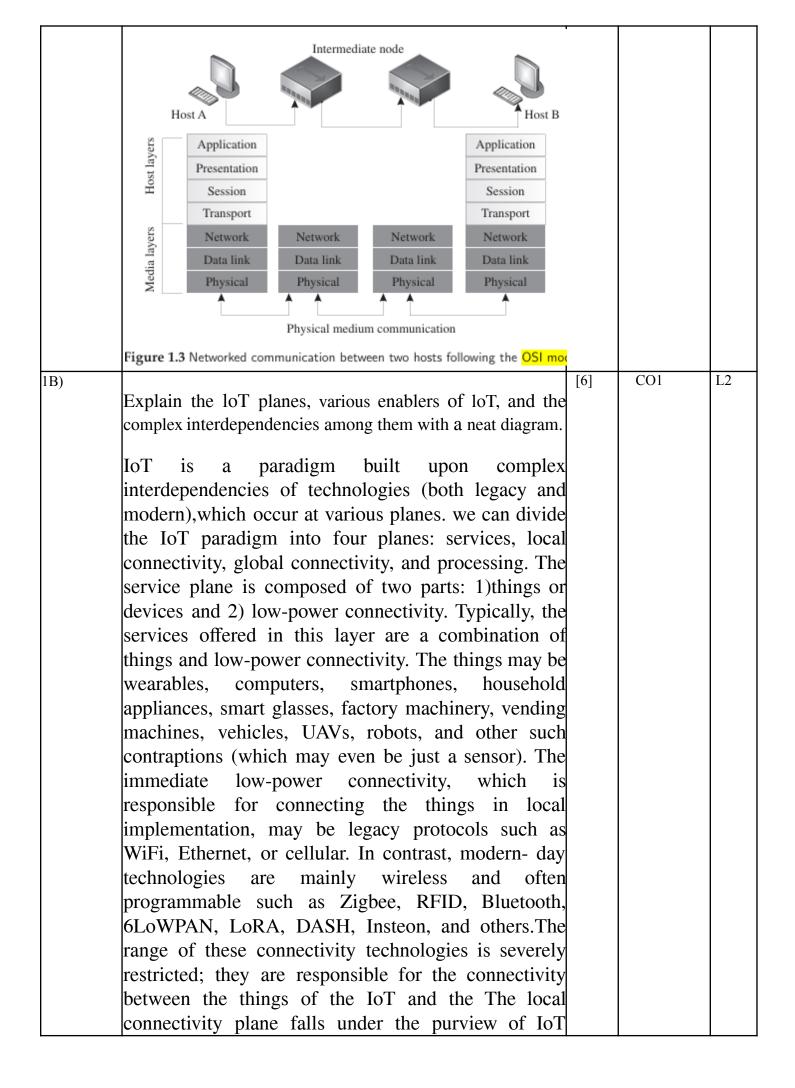


	Solution QP – Feb 2024	ы ** •		BENGALURU.
Sub:	Introduction to Internet of Things (IOT) Sub Code: BETCK105H			AIML AIDS
Date:	Feb 202 5Duration:3 hoursMax Marks:100Sec:IA-F		OBE	
		MAR KS	СО	RBT
1	 a) With a neat diagram, explain the network communication between two hosts following the OSI model. The ISO-OSI model is a conceptual framework partitions any networked communication device into see layers of abstraction, each performing distinct tasks based the underlying technology and internal structure of the hot These seven layers, from bottom-up, are as follows: Physical layer, 2) Data link layer, 3) Network layer. Transport layer, 5) Session layer, 6) Presentation layer, an Application layer. The major highlights of each of the layers are: (ii) Physical Layer: This is a media layer and is also refere to as layer 1 of the OSI model. The physical layer responsible for taking care of the electrical and mechanioperations of the host at the actual physical level. This is responsible for the topological layout of the network (smesh, bus, or ring), communication mode (simplex, dup full duplex), and bit rate control operations. The protocol unit associated with this layer is referred to as a symbol. (ii) Data Link Layer: This is a media layer and layer 2 of OSI model. The data link layer is mainly concerned with establishment and termination of the connection between hosts, and the detection and correction of errors du communication between two or more connected hosts. protocol data unit associated with this layer is a media layer and layer and lay of the OSI model. It provides a means of routing data various hosts connected to different networks through log paths called virtual circuits. These logical paths may p through other intermediate hosts (nodes) before reaching actual destination host. The primary tasks of this layer is a media addressing, sequencing of packets, conges 	tion [8] that even d on osts. (1) (4) d 7) nese rred r is iical ayer star, blex, data f the two ring The as a er 3 a to gical pass the ayer	CO1	L2

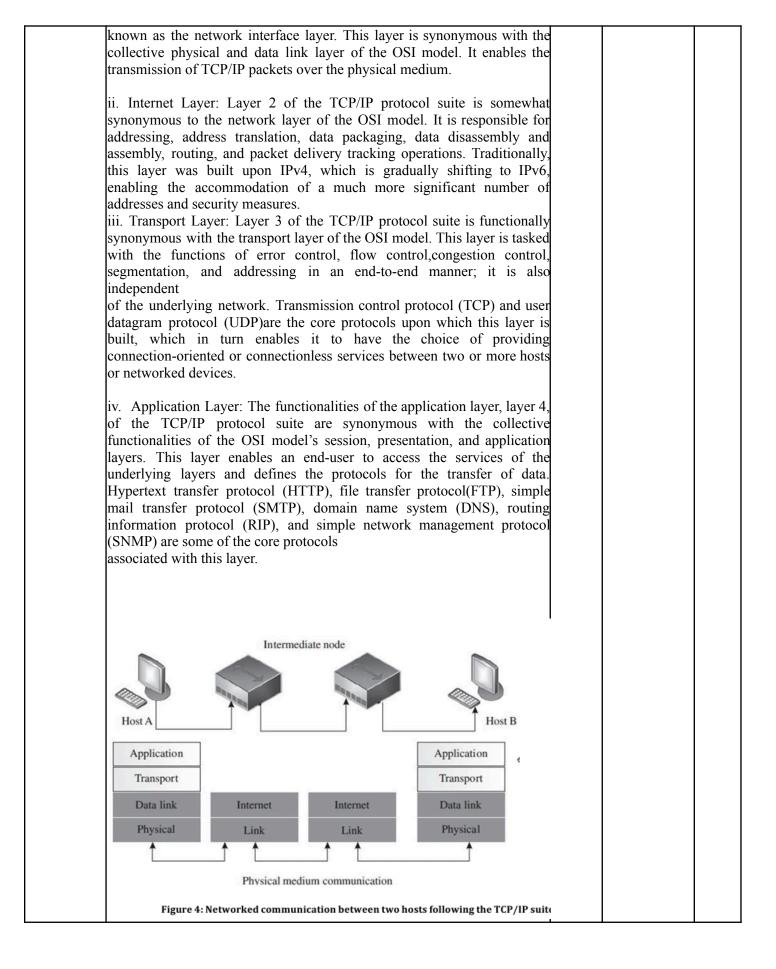
control, error handling, andInternetworking.Theprotocol data	4
unit associated with this layer is referred to as a packet.	
(iv) Transport Layer: This is layer 4 of the OSI model and is	
a host layer. The transport layer is tasked with end-to-end	
error recovery and flow control to achieve a transparent	
transfer of data between hosts. This layer is responsible for	
keeping track of acknowledgments during variable-length	u l
data transfer between hosts. In case of loss of data, or when	4
no acknowledgment is received, the transport layer ensures	, ,
that the particular erroneous data segment is re-sent to the	
receiving host. The protocol data unit associated with this	
layer is referred to as a segment or datagram.	
(v) SessionLayer:	
ThisistheOSImodel'slayer5andisahostlayer. It is responsible	
for establishing, controlling, and terminating of	
communication between networked hosts. The session layer	
sees full utilization during operations such as remote	
procedure calls and remote sessions. The protocol data unit	t l
associated with this layer is referred to as data.	
(vi) Presentation Layer: This layer is a host layer and layer 6	
of the OSI model. It is mainly responsible for data format	
conversions and encryption tasks such that the syntactic	
compatibility of the data is maintained across the network, for	
which it is also referred to as the syntax layer. The protocol	
data unit associated with this layer is referred to as data.	
(vii) Application Layer: This is layer 6 of the OSI model and	
is a host layer. It is directly accessible by an end-user through	L .
software APIs (application program interfaces) and terminals.	
Applications such as file transfers, FTP (file transfer	
protocol), e-mails, and other such operations are initiated	4
from this layer. The application layer deals with user	
authentication, identification of communication hosts, quality	, , , , , , , , , , , , , , , , , , , ,
of service, and privacy. The protocol data unit associated with	4
this layer is referred to as data	

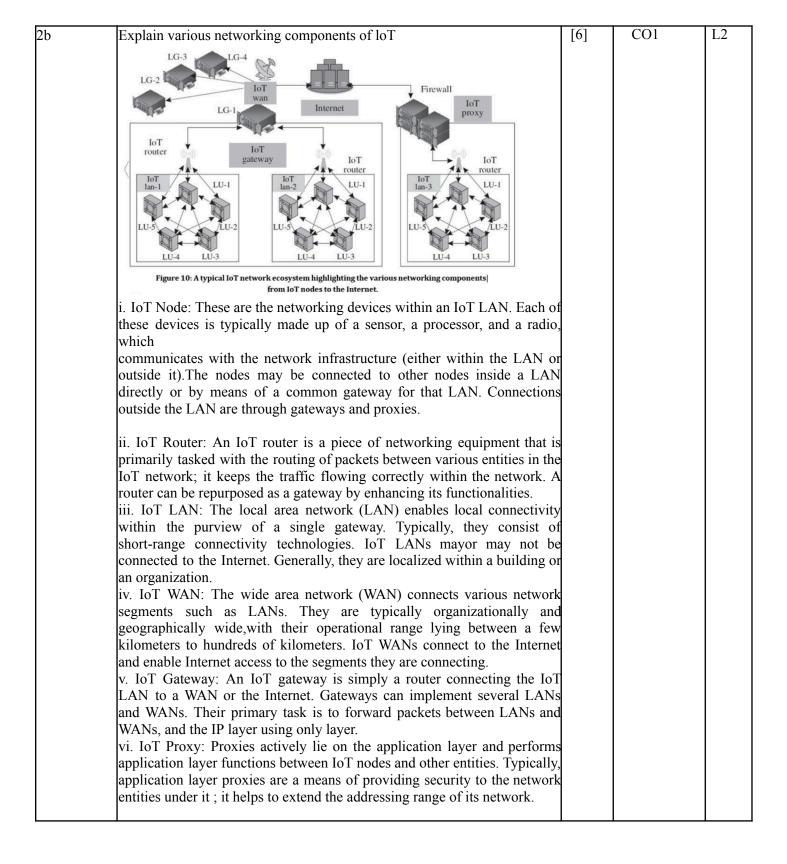


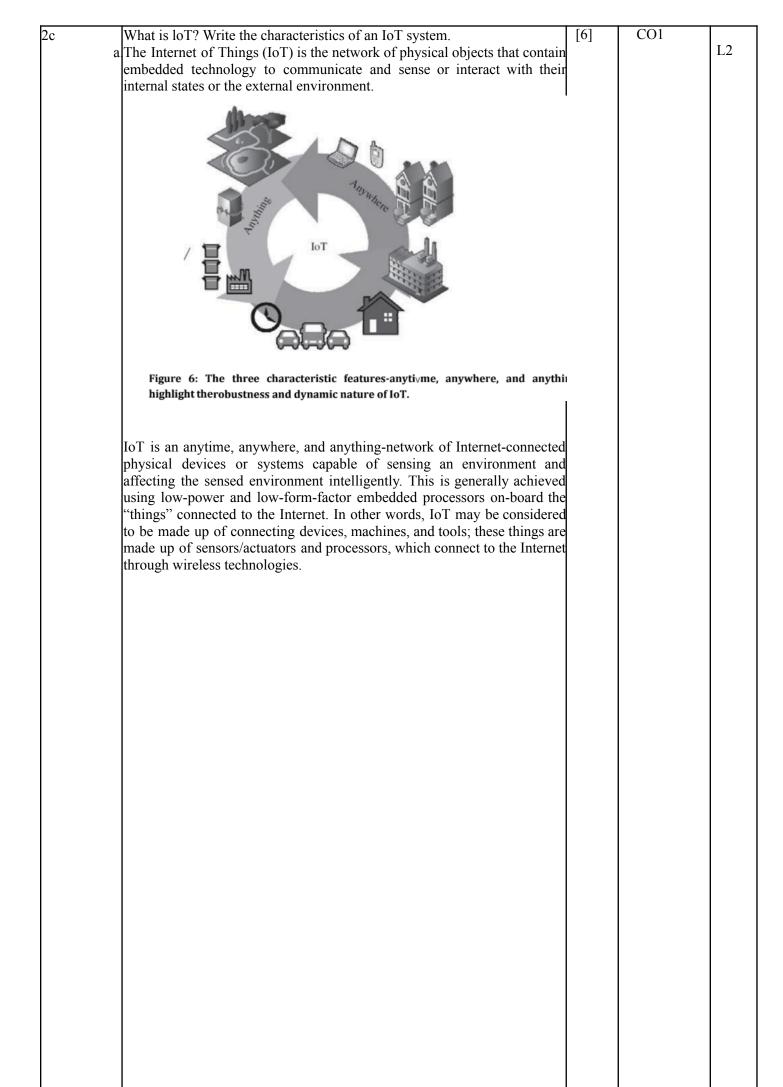
management as it directly deals with strategies to use/reuse addresses based on things and applications. The modern-day "edge computing" paradigm is deployed in conjunction with these first two planes: services and local connectivity. In continuation, the penultimate plane of global connectivity plays a significant role in enabling IoT in the real sense by worldwide implementations allowing for and connectivity between things, users, controllers, and applications. This plane also falls under the purview of IoT management as it decides how and when to store data, when to process it, when to forward it, and in which form to forward it. The Web, data-centers, remote servers, Cloud, and others make up this plane. The paradigm of "fog computing" lies between the planes of local connectivity and global connectivity. The final plane of processing can be considered as a top-up of the basic IoT networking framework. The nearest hub or gateway to access the Internet. The local connectivity is responsible for distributing Internet access to multiple local IoT deployments. This distribution may be on the basis of the physical placement of the things, on the basis of the application domains, or even on the basis of providers of services. as address management, device Services such management, security, sleep scheduling, and others fall within the scope of this plan.

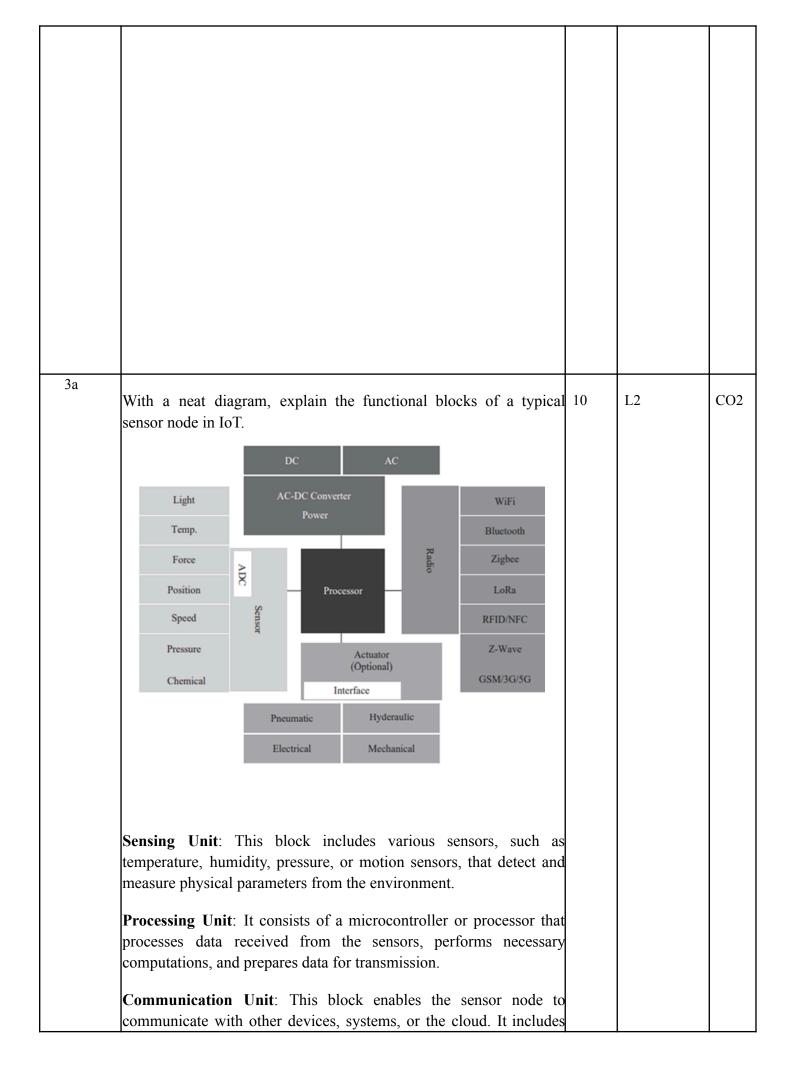
		Processing	Conversion	Learning	Algorithm	Visualization	IoT tools				
		Global connectivity	Data-centers	Wcb	Remote server	Cloud	toT management				
		Local connectivity	Gateway	Proxy	Router	Switch	IoT man	Υ.			
		Services	Zigbee Rfi Ethernet	id Bluetoo		PAN Insteon Cellular	Service provider				
	Figure		T planes, various	enablers of lo	T, and the for			among			
1.									[6]	CO1	L2
	following f i. Star: In a controller of they can o traffic exc installation However, t point of fai ii. Mesh: I using a dec hosts in a between th expensive. topologies. functional The second is only see network. T every host iii. Bus: A backbone of hosts. The taps. The However, th over the ex- various ho	on the reen four b star or hul nly d hang hang hang hang hang hang hang hang	the physical the hosts a proad topol topology, e o. The host lo so throu e. The m d the ease ain disadv If the hub mesh topol ed link (in n, there are sts. This m vever, it m if a lin ere remain antage is t t the inten- ird advant s network s topology or bus set s are conm- advantag is a restric be simultar ed bus. Mu to the bu-	manner are conn ogies: Si every hos is cannot gh the c hain adv e of fai rantage of fails, the ogy, eve a point-te e a total assive n offers c k is dow n other p he secur nded rec age is th takes can y follow rves as th exected to e of thi ction on neously of altiple di s, maki back of	in which in control in the sected, of tar, Messist has a tern training sector of the central here is the connect is the print of the lenge connect is in the ng inst	th communi- computer in h, Bus, an point-to-punicate with ub. The h of the intification opology is network fa is connect manner). 1)/2 dedice of links ma specific a proken, the s for the t privacy of and not b ed data lo traffic loa point-to-min ary traffic an bus en ogy is the gth of the s and taps allation v	nication netwood Rin oint I is one ub ac star t with the c ails. ted to This cated ikes the dvant netw raffic f the path netw raffic f the path netw raffic g all ad on d. ultipoy e eas bus a bus c can b	on orks can have the			

	iv. Ring: A ring topology works on the principle of a point-to-point connection. Here, each host is configured to have a dedicated point-to-point connection with its two immediate neighboring hosts on either side of it through repeaters at each host. The repetition of this system forms a ring. The repeaters at each host capture the incoming signal intended for other hosts, regenerates the bit stream, and passes it onto the next repeater. Fault identification and set up of the ring topology is quite simple and straightforward. However, the main disadvantage of this system is the high probability of a single point of failure. If even one repeater fails, the whole network goes down.		
	Backbone bus Host E Host D		
	Host A Host A Host B Host C Repeater Host F Host E Host D		
	(C) Bus topology		
2a	With a neat diagram, explain internet protocol suite. The Internet protocol suite is yet another conceptual framework that provides levels of abstraction for ease of understanding and development of communication and networked systems on the Internet. However, the Internet protocol suite predates the OSI model and provides only four levels of abstraction: 1) Link layer, 2) Internet layer, 3) transport layer, and 4) application layer. This collection of protocols is commonly referred to as the TCP/IP protocol suite as the foundation technologies of this suite are transmission control protocol (TCP) and Internet protocol (IP). Link Layer: The first and base layer of the TCP/IP protocol suite is also	CO1	L2





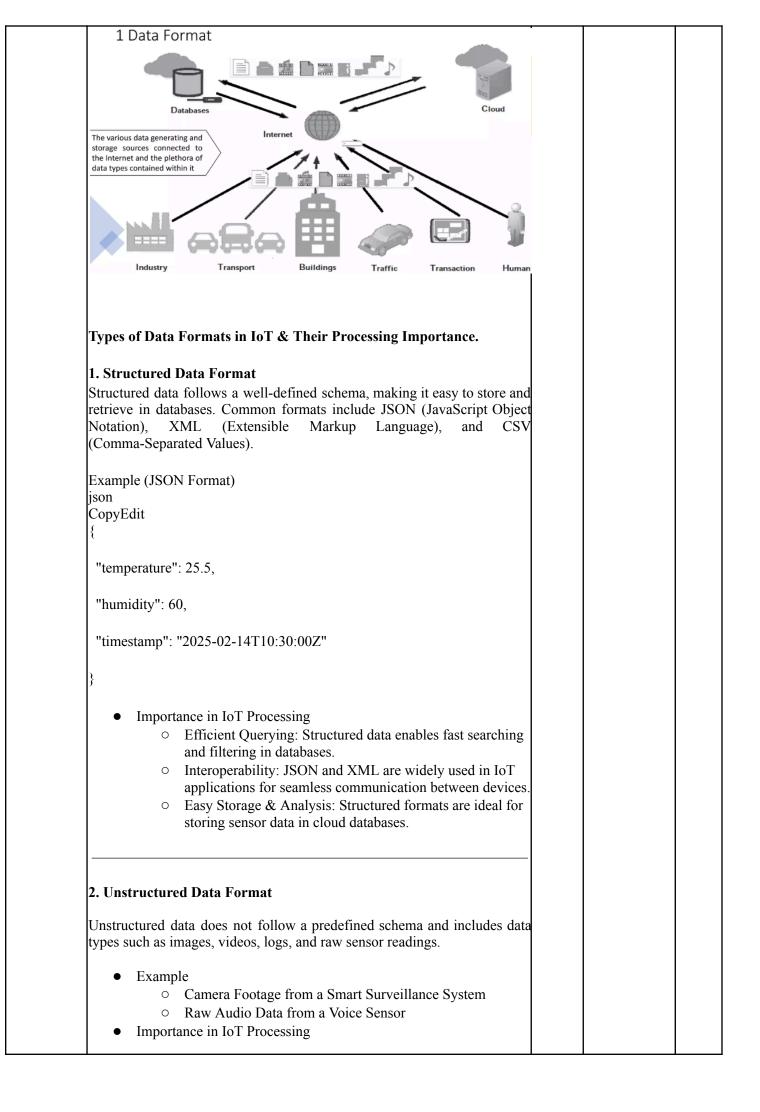




P n s	ower Su ode to to ystems, c	function. It can opreven power-over	des the necessary po come from batteries, r-wireless technologie	energy harvesting s.			
S	tored. It	could be used for	e data can be tempora or buffering data befo n for future processing	ore transmission or			
C	Outline ba	asic differences be	tween transducer, sens	sor and an actuator.	10	L4	
	Aspect	Transducer	Sensor	Actuator	1		
	Definition	A device that converts one form of energy to another.	A type of transducer that detects and measures a physical quantity, converting it to an electrical signal.	A device that converts electrical energy into physical motion or action.			
	Function	Converts energy from one form to another (e.g., mechanical to electrical).	Detects a physical parameter (e.g., temperature, pressure) and converts it into an electrical signal.	Receives an electrical signal and performs a physical task or action (e.g., moving a part).			
	Output	Can be electrical or physical.	Electrical signal (voltage, current, etc.).	Physical motion, force, or other mechanical output.			
	Example	Microphone, speaker, thermocouple.	Temperature sensor, pressure sensor, photodiode.	Electric motor, solenoid, hydraulic actuator.			
	Purpose	Energy conversion (from one form to another).	Measurement of a physical parameter for monitoring or control.	Performing a physical task or movement based on input signals.			
v	Vith a nea	_	n working mechanism	of actuator.	10	L2	
			42	Event: Factory			

Data Collection by Sensors:		
• Sensors in an IoT system continuously monitor physical parameters, such as temperature, humidity, pressure, light, or motion. The data from these sensors is sent to a processing unit (e.g., microcontroller or cloud platform).		
Data Processing:		
• The processing unit analyzes the sensor data to determine whether any action needs to be taken. This could be based on specific conditions, thresholds, or user commands (e.g., if temperature exceeds a certain limit, the actuator must activate).		
Sending Command to Actuator:		
• Once the processing unit decides that an action is required, it sends a command to the actuator. This command can be transmitted via wireless communication protocols like Wi-Fi, Bluetooth, Zigbee, or LoRa, depending on the system's configuration.		
Actuator Response:		
 The actuator receives the electrical signal or command from the controller or IoT system. It then converts this electrical signal into a physical action. For example: A motor actuator might move a robotic arm. A servo actuator might adjust the position of a valve. A solenoid actuator might open or close a door or valve. A heater actuator might turn on or off based on temperature data. 		
Feedback and Control:		
• In many IoT systems, the actuator's action might also be monitored by sensors to provide feedback. For example, after the actuator turns on a fan, temperature sensors could monitor whether the temperature has decreased. If the desired condition is met, the actuator can be turned off automatically.		

Aspect Definition	Mechanical Actuators Actuators that use	Soft Actuators	Shape Memory-based Actuators			
Definition			shape memory based Actuators			
	mechanical force or motion to perform tasks, typically through gears, motors, or levers.	Actuators made from flexible, deformable materials that can change shape when activated.	Actuators that change shape or move in response to temperature or other external stimuli, utilizing materials with shape memory properties.			
Operating Principle	Converts electrical, hydraulic, or pneumatic energy into mechanical motion.	Utilize materials that can deform elastically or plastically in response to stimuli like pressure or temperature.	Rely on materials (like shape memory alloys) that "remember" specific shape and return to it when heated or cooled.			
Common Materials	Metals (e.g., steel, aluminum), plastics, or composites.	Elastomers, soft polymers, and gels.	Shape memory alloys (e.g., Nitinol), polymers.			
Movement Type	Typically linear or rotary movement.	Often flexible, bending, or stretching motions.	Change in shape (e.g., bending, contracting) based on temperature.			
Response Time	Typically fast, with precise movement control.	Generally slower compared to mechanical actuators.	Response time is dependent on the material and temperature change; can be slower.			
Power Source	Electric motors, hydraulic fluid, pneumatic pressure.	Pressure (air or liquid), electric current, or thermal energy.	Heat or temperature changes, sometimes electrical current.			
Precision and Control	High precision and control, often used in robotics and machinery.	Less precise, suited for applications where flexibility is more important than exact control.	Moderate precision, with shape change being predictable but not as precise as mechanical systems.			
Examples	Electric motors, hydraulic cylinders, pneumatic	Pneumatic artificial muscles, soft robots,	Nitinol-based actuators, thermoresponsive polymer			
		wo types of data for	ormats and processing	10	L2	
iagram:						
	Materials Movement Type Response Time Power Source Precision and Control Examples	Materialsaluminum), plastics, or composites.Movement TypeTypically linear or rotary movement.Response TimeTypically fast, with precise movement control.Power SourceElectric motors, hydraulic fluid, pneumatic pressure.Precision and ControlHigh precision and control, often used in robotics and machinery.ExamplesElectric motors, hydraulic cylinders, pneumaticTith a neat diagram, Explain typortance in IOT.	Common MaterialsMetals (e.g., steel, aluminum), plastics, or composites.Elastomers, soft polymers, and gels.Movement TypeTypically linear or rotary movement.Often flexible, bending, or stretching motions.Response Time Power SourceTypically fast, with precise movement control.Generally slower compared to mechanical actuators.Power Source ControlElectric motors, hydraulic fluid, pneumatic pressure.Pressure (air or liquid), electric current, or thermal energy.Precision and ControlHigh precision and control, often used in robotics and machinery.Less precise, suited for applications where flexibility is more important than exact control.ExamplesElectric motors, hydraulic cylinders, pneumaticPneumatic artificial muscles, soft robots,	Common MaterialsMetals (e.g., steel, aluminum), plastics, or composites.Elastomers, soft polymers, and gels.Shape memory alloys (e.g., Nitinol), polymers.Movement TypeTypically linear or rotary movement.Often flexible, bending, or stretching motions.Change in shape (e.g., bending, contracting) based on temperature.Response TimeTypically fast, with precise movement control.Generally slower compared to mechanical actuators.Response time is dependent on the material and temperature change; can be slower.Power SourceElectric motors, hydraulic fluid, pneumatic pressure.Pressure (air or liquid), electric current, or thermal energy.Heat or temperature changes, sometimes electrical current.Precision and ControlHigh precision and control, often used in robotics and machinery.Less precise, suited for applications where important than exact control.Moderate precision, with shape change being predictable but not as precise as mechanical systemsExamplesElectric motors, hydraulic cylinders, pneumaticPneumatic artificial muscles, soft robots,Nitinol-based actuators, thermoresponsive polymerTith a neat diagram, Explain two types of data formats and processing nportance in IOT.Typicalis two types of data formats and processing thermoresponsive polymer	Common MaterialsMetals (e.g., steel, aluminum), plastics, or composites.Elastomers, soft polymers, and gels.Shape memory alloys (e.g., Nitinol), polymers.Movement TypeTypically linear or rotary movement.Often flexible, bending, or stretching motions.Change in shape (e.g., bending, contracting) based on temperature.Response TimeTypically fast, with precise movement control.Generally slower compared to mechanical actuators.Response time is dependent on the material and temperature change; can be slower.Power SourceElectric motors, hydraulic fluid, pneumatic pressure.Pressure (air or liquid), electric current, or thermal energy.Heat or temperature changes, sometimes electrical current.Precision and ControlHigh precision and control, often used in robotics and machinery.Less precise, suited for applications where flexibility is more important than exact control.Nitinol-based actuators, thermoresponsive polymerFith a neat diagram, Explain two types of data formats and processing protance in IOT.10	Common MaterialsMetals (e.g., steel, aluminum), plastics, or composites.Elastomers, soft polymers, and gels.Shape memory alloys (e.g., Nitinol), polymers.Movement TypeTypically linear or rotary movement.Often flexible, bending, or stretching motions.Change in shape (e.g., bending, contracting) based on temperature.Response Time Power SourceTypically fast, with precise movement control.Generally slower compared to mechanical actuators.Response time is dependent on the material and temperaturePower Source ControlElectric motors, hydraulic fluid, pneumatic pressure.Pressure (air or liquid), electric current, or thermal energy.Heat or temperature changes, sometimes electrical current.Precision and ControlLess precise, suited for applications where flexibility is more important than exact control.Moderate precision, with shape change being predictable but not as precise as mechanical systemsExamplesElectric motors, hydraulic cylinders, pneumaticPneumatic artificial musdes, soft robots,Nitinol-based actuators, thermoresponsive polymerTith a neat diagram, Explain two types of data formats and processing hoportance in IOT.10L2



	 AI & ML Applications: Image recognition and audio processing enable advanced IoT functionalities. Predictive Maintenance: Analyzing unstructured sensor logs can detect faults before failure. Security & Monitoring: Unstructured video streams aid in real-time surveillance. 	10	L2	CO1
5b).	Explain IoT Device selection considerations.	[10]	CO3	L2
	 Device Compatibility & Interoperability Must support standard communication protocols (e.g., MQTT, CoAP, HTTP, Bluetooth, Zigbee). Should integrate seamlessly with existing IoT platforms and cloud services. Ensure support for multiple operating systems (Linux, Windows, RTOS) if needed. Example: A smart thermostat should be able to communicate with both mobile apps and home automation systems like Google Home or Alexa. 			
	 2. Power Consumption & Battery Life Devices should be optimized for low power consumption, especially for battery-powered IoT devices. Consider devices supporting low-power communication protocols (LoRaWAN, Zigbee, NB-IoT). Energy-efficient components (e.g., ARM Cortex M processors) are preferred for longevity. Example: Wearable fitness trackers must have long battery life and low power consumption. 			
	 3. Connectivity & Network Requirements Wired vs. Wireless: Choose between Ethernet (wired) or Wi-Fi, 4G/5G, LoRaWAN, and NB-IoT (wireless). Ensure network coverage and signal strength in the deployment area. Latency considerations: Real-time applications like healthcare monitoring require ultra-low latency networks. Example: A smart irrigation system in agriculture might require LPWAN (LoRaWAN) for long-range connectivity. 			
	4. Processing Power & Storage			

	 Devices must have sufficient processing capability (MCU vs. MPU) based on application needs. Edge computing is useful for reducing cloud dependency and enhancing local processing. Storage considerations: Devices collecting high-resolution images/videos require more onboard storage. Example: A video surveillance IoT device needs high processing power and storage for local video analytics. 		
	 5. Security & Data Protection Must support encryption protocols (TLS, AES) to protect data transmission. Devices should have secure boot mechanisms to prevent unauthorized firmware modifications. Authentication features (biometric, password, or key-based access) should be included. Example: A smart home security camera should encrypt live feeds and use two-factor authentication for access. 		
	 6. Scalability & Future Upgradability Devices should support firmware updates (OTA - Over-the-Air) for future security patches and upgrades. Should be modular and scalable, allowing new sensors or features to be added. Cloud compatibility ensures future expansion of IoT networks. Example: A smart city lighting system should be easily upgradable to add new sensors or AI-based automation. 		
	 7. Cost & Return on Investment (ROI) Consider initial costs vs. long-term operational costs (maintenance, power consumption). Subscription & licensing fees for IoT platforms or cloud storage should be factored in. Devices should provide a clear business value or operational efficiency improvement. Example: In industrial IoT, selecting rugged, durable sensors with lower maintenance needs can save long-term costs. 		
6 a)	Discuss with a neat diagram event detection using offsite using remote and collaborative processing topologies. Diagram:		

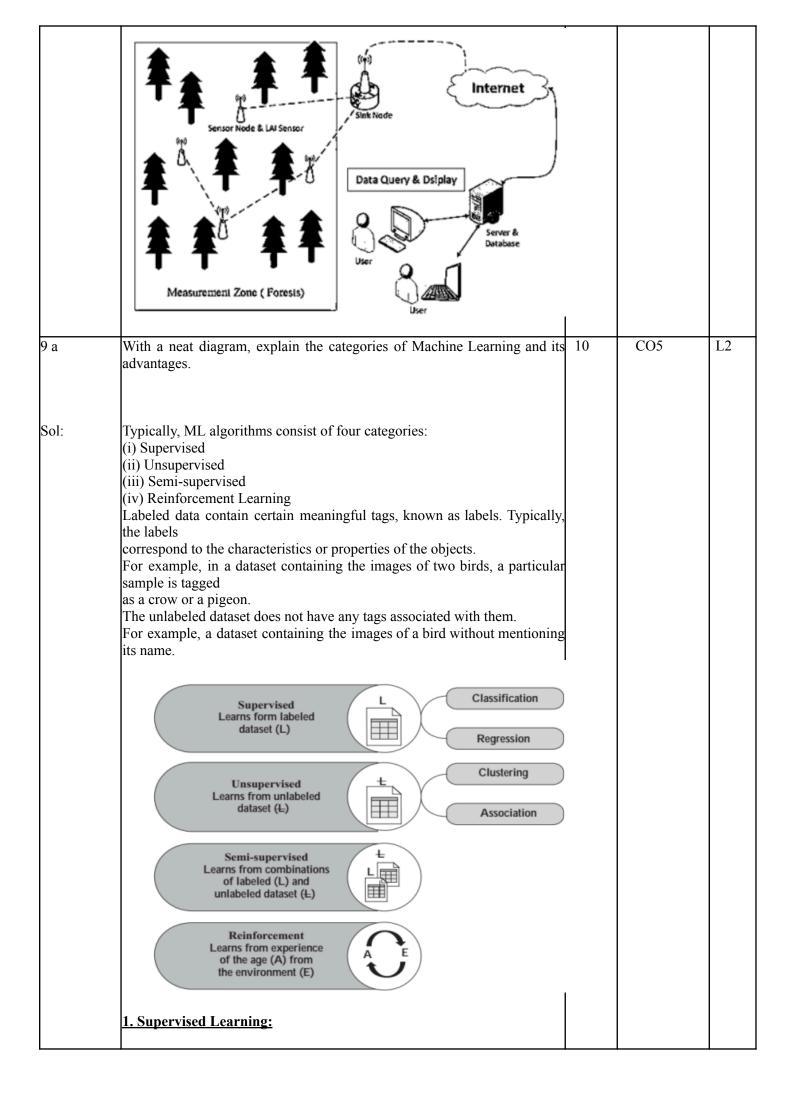
Environment Event: Fire	Sensing Temperature sensor vent detection using an off-s	Sensor node	Network	Remote processing		
Event detection to specific occu failure) using se	in IoT refers to the rrences (e.g., temp ensor data. Two ma cessing and Collab	e process o erature rise, ajor topolog	f identifying motion deteries for offsite	ction, equipment		
	essing, IoT devices oud or data c					
Workflow:	z take place.					
 Data is 4G/5G, The clo event de 	sors collect real-tin transmitted to the c LoRaWAN, or MC ud platform proces etection. r actions are sent b	loud or a re TT. ses the data	using AI/MI	_ models for		
Advantages:						
V Centralized	tational power for data storage & long evice hardware req	g-term analy				
Disadvantages:						
	twork dependency dth consumption d			nsmission.		
Use Case Exam	ple:					
	ffic monitoring sy stion and accident		cameras ser	id footage to the		
2. Collaborative	Processing Topolo	ogy				
	processing, edge re processing wor efficiency.					
Workflow:						
1. IoT sen process	sors collect data an	d perform i	nitial local fi	ltering or		

 Edge devices (e.g., local servers, fog nodes, or AI-capable IoT devices) process event-related data. Only critical data or detected events are transmitted to the cloud. The cloud aggregates and refines event detection for large-scale decision-making. 	
Advantages:	
 Low latency event detection due to local processing. Reduced bandwidth usage, as only processed data is transmitted. Increased reliability, since local processing reduces dependency on cloud connectivity. 	
Disadvantages:	
 Requires more advanced edge devices with computational capabilities. Complexity in managing distributed processing nodes. 	
Use Case Example:	
An industrial predictive maintenance system, where local edge gateways analyze vibration and temperature data from machines to detect early signs of failure before sending alerts to the cloud.	
Explain different data offloading strategies with location and decision making.	
Data offloading in IoT refers to transferring data processing tasks from resource-constrained devices to more powerful computing entities (edge servers, cloud servers, or fog nodes) to enhance performance and efficiency. Different offloading strategies depend on where the processing occurs and how decisions are made.	
1. Location-Based Data Offloading Strategies	
Data offloading can occur at different locations within an IoT ecosystem, affecting latency, bandwidth, and computational efficiency.	
a) Edge Offloading (Near the Device)	
 Where? Data is processed on local edge devices (gateways, routers, or microservers). Best for: Real-time applications with low latency needs. Example: Smart cameras performing face recognition locally before sending only metadata to the cloud. 	
b) Fog Offloading (Between Edge and Cloud)	
 Where? Data is processed at fog nodes (local servers closer to devices but more powerful than edge devices). Best for: Applications needing moderate processing with some cloud support. Example: Industrial IoT (IIoT) systems analyzing machine sensor data at fog nodes to predict maintenance needs. 	
	 devices) process event-related data. Only oritical data or detected events are transmitted to the cloud. The cloud aggregates and refines event detection for large-scale decision-making. Advantages: Low latency event detection due to local processing. Reduced bandwidth usage, as only processed data is transmitted. Increased reliability, since local processing reduces dependency on cloud connectivity. Disadvantages: Requires more advanced edge devices with computational capabilities. Complexity in managing distributed processing nodes. Use Case Example: An industrial predictive maintenance system, where local edge gateways analyze vibration and temperature data from machines to detect early signs of failure before sending alerts to the cloud. Explain different data offloading strategies with location and decision making. Data offloading in IoT refers to transferring data processing tasks from resource-constrained devices to more powerful computing entities (edge servers, cloud servers, or fog nodes) to enhance performance and efficiency. Different offloading strategies Data offloading tarte data foffloading strategies depend on where the processing occurs and how decisions are made. 1. Location-Based Data Offloading Strategies Data offloading (Near the Device) Where? Data is processed on local edge devices (gateways, routers, or microservers). Best for: Real-time applications with in without ant OT ecosystem, affecting latency, bandwidth, and computational efficiency. Best for: Real-time applications with low latency needs. Example: Smart cameras performing face recognition locally before sending only metadata to the cloud. b) Fog Offloading (Retween Edge and Cloud) Where? Data is processed of fog nodes (local servers closer to devices but more powerful than edge devices

		1		11
	c) Cloud Offloading (Remote Processing)			
	 Where? Data is sent to centralized cloud servers for processing. Best for: Applications requiring heavy computation and long-term storage. Example: Smart healthcare systems where patient health data is analyzed in cloud AI models. 			
	2. Decision-Based Data Offloading Strategies			
	The decision to offload data can be static (predefined rules) or dynamic (real-time conditions).			
	a) Full Offloading (All Data is Sent for Processing)			
	 Decision: The device always offloads 100% of its data to the cloud or edge. Advantage: No need for complex decision-making algorithms. Disadvantage: High bandwidth usage, potential latency issues. Use Case: IoT security cameras streaming continuous video to a cloud-based AI for surveillance analysis. 			
	b) Partial Offloading (Selective Data Transmission)			
	 Decision: Only critical or high-priority data is offloaded. Advantage: Reduces bandwidth usage and optimizes resource allocation. Disadvantage: Requires intelligent filtering mechanisms on the device. Use Case: A smart city traffic system analyzing road congestion locally and sending only alerts to cloud servers. 			
7a	What is service level agreement (SLA)? Explain its importance and merits 10 used while defining SLA. 10	(CO4	L2
	A Service Level Agreement (SLA) is a formal contract between a service provider and a customer that defines the level of service expected. It outlines key performance indicators (KPIs), service quality, responsibilities, and penalties for non-compliance. SLAs are commonly used in IT services, cloud computing, customer support, and managed services to ensure consistent and reliable service delivery.			
	 Importance of SLA Clarifies Expectations – Clearly defines the services, performance standards, and responsibilities of both parties. Improves Service Quality – Encourages the provider to maintain a high level of performance. Enhances Accountability – Establishes penalties or compensation if the service provider fails to meet agreed standards. Minimizes Disputes – Provides a legal framework that prevents misunderstandings and conflicts. Ensures Business Continuity – Guarantees service availability, response time, and resolution time, which are crucial for business operations. 			
	Merits Used While Defining SLA Service Scope – Clearly defines what services are covered under the agreement.			

	Performance Metrics – Includes measurable standards like uptime (e.g.,			
	99.9% availability), response time, and resolution time.			
	Roles and Responsibilities – Specifies duties of both the service provider			
	and the client.			
	Monitoring and Reporting – Details how service performance will be			
	measured and reported.			
	Escalation Process – Defines steps for issue resolution if services fall			
	below agreed standards.			
	Penalties and Remedies – Specifies consequences for failing to meet SLA commitments, such as refunds or service credits.			
	Review and Updates – Allows periodic revisions to reflect changes in			
	business needs and service requirements.			
7b	Explain cloud models and its features of commercial cloud Amazon Web	10	CO4	L2
/0	Servers (AWS)			
	Cloud computing is categorized into three main models based on the			
	service provided:			
	Infrastructure as a Service (IaaS)			
	Platform as a Service (PaaS)			
	Software as a Service (SaaS)			
	Cloud Models Explanation			
	1. Infrastructure as a Service (IaaS)			
	Provides virtualized computing resources over the internet.			
	Users can access virtual machines (VMs), storage, networking, and OS			
	on-demand.			
	Example: Amazon EC2, Google Compute Engine, Microsoft Azure Virtual Machines			
	Features:			
	✓ Scalable and flexible computing resources			
	 Scalable and nextble computing resources Pay-as-you-go pricing 			
	✓ Full control over virtual machines			
	✓ Ideal for IT administrators and developers			
	• Tubur for FF unifiliations und ub reference			
	2. Platform as a Service (PaaS)			
	Provides a development and deployment environment for applications.			
	Users get a platform to build, test, and deploy applications without			
	managing infrastructure.			
	Example: AWS Elastic Beanstalk, Google App Engine, Microsoft Azure			
	App Services			
	Features:			
	 Supports multiple programming languages 			
	✓ Automates OS updates and system maintenance			
	✓ Scalable and cost-efficient			
	✓ Ideal for developers			
	2 Software of a Samian (Sach)			
	3. Software as a Service (SaaS)			
	Provides ready-to-use software applications over the internet. Users don't need to install, maintain, or update software manually.			
	Example: Google Workspace, Microsoft 365, Dropbox			
	Features:			
	✓ Accessible from any device with an internet connection			
	✓ No need for software installation or maintenance			
	✓ Subscription-based pricing			
	✓ Ideal for end-users			
				-

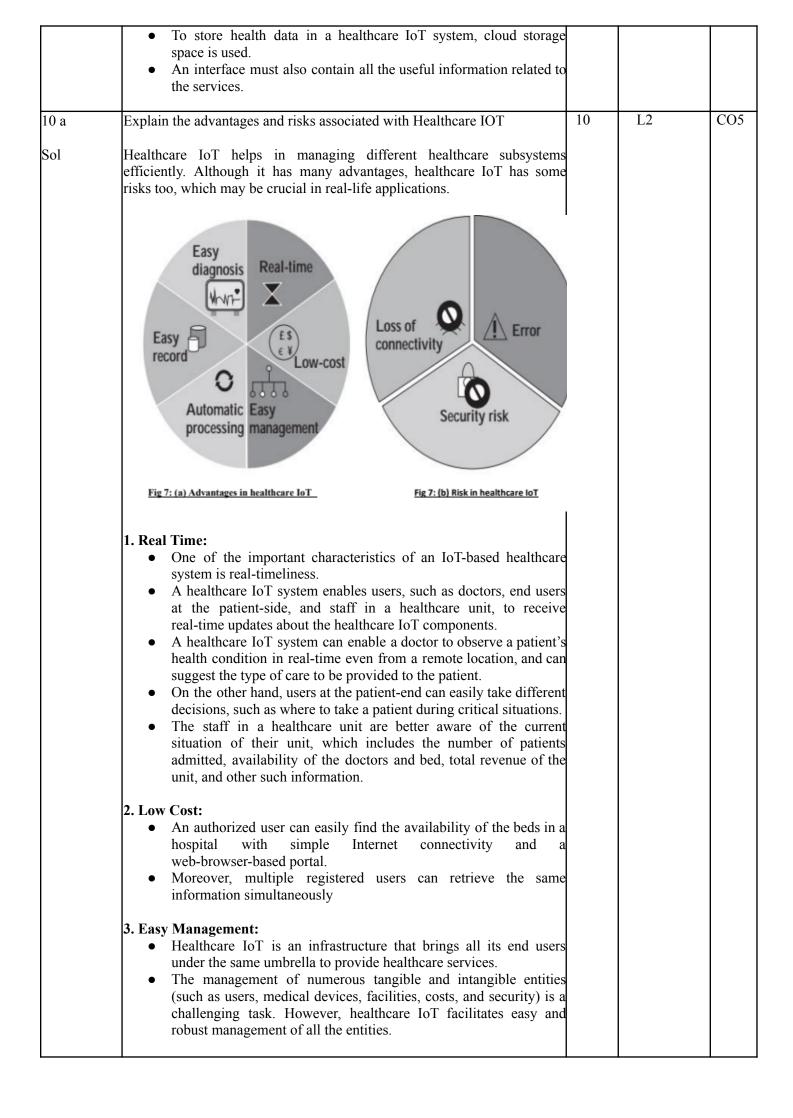
8a.	What is virtualization? Explain its advantages from end-user and service provider point of view.	10	CO4	L2
	Virtualization is a technology that allows multiple virtual instances of operating systems, applications, or servers to run on a single physical machine. It is achieved through a software layer called a hypervisor, which creates and manages these virtual machines (VMs).			
	 From an End-User Perspective: Cost Savings – Users can access virtual desktops or applications without needing expensive hardware. Flexibility and Accessibility – Users can access their virtual machines or applications from anywhere, on any device. Enhanced Security – Virtual desktops provide a controlled and secure environment, reducing the risk of malware infections. Improved Performance – Applications run smoothly with centralized management and optimized resource allocation. Disaster Recovery – Users' data and applications can be quickly restored in case of system failure. 			
	 From a Service Provider Perspective: Efficient Resource Utilization – Virtualization allows providers to maximize server utilization, reducing the need for excess hardware. Scalability – Service providers can easily allocate or scale resources based on demand. Reduced Operational Costs – Less physical infrastructure means lower power, cooling, and maintenance costs. Faster Deployment – Virtual machines can be created, cloned, or migrated quickly, improving service efficiency. High Availability and Reliability – Virtualization enables redundancy and load balancing, ensuring continuous service delivery. 			
8b	 With a diagram, briefly explain the architecture of the leaf Area Index system. The Leaf Area Index (LAI) system architecture consists of several key components designed to measure and analyze canopy structure. It typically includes a light sensor (such as a ceptometer or sunfleck sensor) to capture the amount of sunlight passing through the foliage, along with a canopy analyzer or digital camera to record leaf coverage. These sensors send data to a processing unit, which calculates the LAI based on light attenuation or image analysis. In some advanced systems, a wireless communication module enables real-time data transmission to cloud storage or remote servers for further analysis. This system helps researchers and farmers assess plant growth, optimize irrigation, and improve crop yields. 		CO4	L2



1.	This type of learning supervises or directs a machine to learn	
2	certain activities using labeled datasets. Consider an example of a student who tries to learn to solve	
2.	equations using a set of labeled formulas.	
	The labels indicate the formulae necessary for solving an equation.	
4.	The student learns to solve the equation using suitable formulae	
5	from the set. In the case of a new equation, the student tries to identify the set of	
5.	formulae necessary for solving it.	
6.	Similarly, ML algorithms train themselves for selecting efficient	
_	formulae for solving equations.	
7.	Supervised ML algorithms are popular in solving classification and regression problems.	
8	The classification deals with predictive models that are capable of	
	approximating a mapping function from input data to categorical	
	output.	
9.	The Regression provides the mapping function from input data to	
10	numerical output. We use regression to estimate the relationship among a set of	
10.	dependent variables with independent variables, as shown in Fig	
	11.	
11.	The dependent variables are the primary factors that we want to predict.	
let x	and y be the independent and dependent variables, respectively.	
	natically, a simple regression model is represented as:	
	$\begin{pmatrix} x_1 \end{pmatrix} \beta_1 \qquad \beta_0$	
	p_1	
($x_2 \qquad y = \beta_0 x_0 + \beta_0 x_0 + \beta_0 x_0 + \dots + \beta_0 x_0 + \varepsilon$	
	(x_1)	
	β_{\star}	
$\mathbf{v} = \mathbf{\beta}0\mathbf{z}$	$x0 + \beta x + \varepsilon$	
	β represents the amount of impact of variable x on y and denotes an	
error.		
	ly, for multiple variables, say n, the regression model is represented	
as:		
$y = \Sigma \beta$	ixi +ε	
$y = \sum \beta$	ixi + ε	
2. Uns	upervised Learning:	
2. Uns	upervised Learning: Unsupervised learning algorithms use unlabelled datasets to find	
2. Uns 1.	upervised Learning: Unsupervised learning algorithms use unlabelled datasets to find scientific trends.	
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2. Uns 1. 2.	upervised Learning: Unsupervised learning algorithms use unlabelled datasets to find scientific trends. Consider an example of the student similar to that described in the case of supervised learning, and illustrate how it differs in case of unsupervised	
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2. Uns 1. 2. 3. 4. 5.	 upervised Learning: Unsupervised learning algorithms use unlabelled datasets to find scientific trends. Consider an example of the student similar to that described in the case of supervised learning, and illustrate how it differs in case of unsupervised learning. ML algorithms in this category try to identify the nature and properties of the input equation and the nature of the formulae responsible for solving it. 	

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problems: clustering and association.8. Clustering divides the data into multiple groups. In contrast,			
 supervised and unsupervised learning. Algorithms under this category use a combination of both labeled and unlabeled datasets for training. Labeled data are typically expensive and are relatively difficult to label correctly. Unlabeled data is less expensive than labeled data. Unsupervised learning is usually applied to solve two types of problems: clustering and association. Traditionally, semi-supervised learning uses mostly unlabeled data, which makes it efficient to use, and capable of overcoming samples with missing labels. Reinforcement Learning: Reinforcement learning establishes a pattern with the help of its experiences by interacting with the environment. Typically, the model starts with an initial state of a problem, for which different solutions are available. Based on the output, the model receives either a reward or a penalty from the environment. The output and reward act as inputs for proceeding to the next state. Thus, reinforcement learning models continue learning iteratively 			
from their experiences while inducing correctness to the output.	10	CO5	L2
With the help of a block diagram explain the components of IoT Health care.			
 that are essential to generate the whole architecture. Figure depicts different components and their usage in an IoT healthcare system. Each of these components plays a distinct role in the smooth execution of the system as a whole. 1. Sensors: Layer 1 mainly consists of physiological sensors that collect the physiological parameters of the patient. Few commonly used physiological sensors and their uses are depicted in Table 1. 2. Wireless Connectivity: The communication between the wearable sensors and the LPU is through either wired or wireless connectivity. The wireless communication between the physiological sensors and LPU occurs with the help of Bluetooth and ZigBee. The communication between the LPU and the cloud or server takes place with Internet connectivity such as WiFi and WLAN. For example, when a service is received by a cellphone, it uses GSM (global system for mobile communications). On the other 			
	 problems: clustering and association. 8. Clustering divides the data into multiple groups. In contrast, association discovers the relationship or association among the data in a dataset. 3. Semi-Supervised Learning: Semi-supervised learning belongs to a category between supervised and unsupervised learning. Algorithms under this category use a combination of both labeled and unlabeled datasets for training. Labeled data are typically expensive and are relatively difficult to labele correctly. Unlabeled data is less expensive than labeled data. Unsupervised learning is usually applied to solve two types of problems: clustering and association. Traditionally, semi-supervised learning uses mostly unlabeled data, which makes it efficient to use, and capable of overcoming samples with missing labels. 4. Reinforcement Learning: Reinforcement learning establishes a pattern with the help of its experiences by interacting with the environment. 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3. Priv	acy and Security:		
•	Moreover, between LPU	and the server/cloud, different	
		a network hops (from one networked	
	device to another) to transmi		
•		compromised, it may result in the theft eading to serious security breaches and	
	ensuing lawsuits.	eading to serious security breaches and	
•		curity of the healthcare data, different	
		s and organizations are implementing	
	healthcare data encryption ar	nd protection schemes.	
	Sensors	Sense the physiological parameter value	
	3013013	from a patient's body	
	Wireless connectivity	Transmit data from sensors to LPU and	
	willeless connectivity	LPU to cloud/server	
f f			
	Privacy and security	Secure the sensitive health data	
-	••	Extract a meaningful inference from the	
2	Analytics	data and apply them in an application	
		Store the data for short-term and	
	Cloud and for computing	long-term basis for future use	
	Interface	Provide an easy-access the application	
4. Ana	lytics:	nents of healthcare IoT	
4. Ana • •	lytics: For converting the raw data important role in healthcare I Several actors, such as doc healthcare information in a d Analytics plays a vital role system access to meaningfu	a into information, analytics plays an IoT. etors, nurses, and patients, access the	
4. Ana • •	lytics: For converting the raw data important role in healthcare I Several actors, such as doc healthcare information in a d Analytics plays a vital role system access to meaningfu healthcare data.	a into information, analytics plays an IoT. etors, nurses, and patients, access the lifferent customized format. e in providing different actors in the al information extracted from the raw diagnosing a disease from the raw	
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	 4. Automatic Processing: Automatic processing features can remove such manual intervention with a fingerprint sensor/device. Healthcare IoT enables end-to-end automatic processing in different units and also consolidates the information across the whole chain: from a patient's registration to discharge. 			
	 5. Easy Record Keeping: A healthcare IoT enables the user to keep these records in a safe environment and deliver them to the authorized user as per requirement. Moreover, these recorded data are accessible from any part of the globe. 			
	 6. Easy Diagnosis: For diagnosing a disease, a huge chunk of prior data is required. The diagnosis of the disease becomes easier with the help of certain learning mechanisms along with the availability of prior datasets. 			
	Risk in Healthcare IoT In a healthcare IoT system, there are multiple risks as well. 1. Loss of Connectivity:			
	 Intermittent connectivity may result in data loss, which may result in a life- threatening situations for the patient. Proper and continuous connectivity is essential in a healthcare IoT system. 			
	 2. Security: The healthcare system must keep the data confidential. On the other hand, different persons and devices are associated with a healthcare IoT system. In such a system, the risk of data tampering and unauthorized access is quite high. 			
	 3. Error: In the healthcare system, errors in data may lead to misinterpretation of symptoms and lead to the wrong diagnosis of the patient. It is a challenging task to construct an error-free healthcare IoT 			
	architecture.			
10 b	Explain the fog framework of intelligent public safety in vehicular environment with a block diagram.	10	L2	CO5
Sol	The primary aim of this system is to ensure smart transportation safety (STS) in public bus services. The system works through the following three steps: 1. The vehicle is equipped with a smart surveillance system, which			
	 is capable of executing video processing and detecting criminal activity in real time. 2. A fog computing architecture works as the mediator between a vehicle and a police vehicle. 3. A mobile application is used to report the crime to a nearby police agent 			
	The architecture of the fog-FISVER consists of different IoT components. The developers utilized the advantages of the low-latency fog computing architecture for designing their system. Fog-FISVER is based on a three-tiered architecture, as shown in Fig 4.			
		ſ	<u>ــــــــــــــــــــــــــــــــــــ</u>	

	· · · · · · · · · · · · · · · · · · ·	
Tier 1	Image processorEvent dispatcherCrime definition downloaderEvent notificationCrime definition storageData gathererAlgorithm launcherVirtual sensor interface	
Tier 2	Target object training Notification factory	
Tier 3	Crime assist unit	
	Fig 4: Architecture of Fog-FISVER	
1 Tio	· 1 In-vehicle FISVER STS Fog :	
1. Tier	A fog node is placed for detecting criminal activities. This tier	
•	accumulates the real sensed data from within the vehicle and	
	processes it to detect possible criminal activities inside the vehicle.	
	This tier is responsible for creating crime-level metadata and	
•	transferring the required information to the next tier.	
Tier 1	consists of two subsystems: Image processor and event dispatcher	
	consists of two subsystems. Image processor and event dispatcher	
Image	Processor:	
i mage	The image processor inside Tier 1 is a potent component, which	
	has a capability similar to the human eye for detecting criminal	
	activities.	
•	Developers of the system used a deep-learning-based approach for	
	enabling image processing techniques in the processor.	
•	To implement the fog computing architecture in the vehicle, a	
	Raspberry-Pi-3 processor board is used, which is equipped with a	
	high-quality camera.	
•	This architecture uses template matching and correlation to detect	
	the presence of dangerous articles (such as a pistol or a knife) in	
	the sub-image of a video frame.	
	hage processor is divided into the following three parts:	
	me definition downloader: This component periodically checks for	
· ·	esence of new crime object template definitions in fog-FISVER STS	
	frastructure. If a new crime object template is available, it is stored	
locally	. me definition storage: In order to use template matching, the crime	
	template definition is required to be stored in the system. The crime	
	ion storage is used to store all the possible crime object template	
definit		
	orithm launcher: This component initiates the instances of the	
	red algorithm in order to match the template with the video captured	
	camera attached in the vehicles. If a crime object is matched with	
	leo, criminal activity is confirmed.	
	dispatcher:	
	vent dispatcher is responsible for accumulating the data sensed from	
	es and the image processor. After the successful detection of criminal	
1 1	y, the information is sent to the fog-FISVER STS fog infrastructure.	
	mponents of the event dispatcher are as follows:	
	ent notifier: It transfers the data to the fog-FISVER STS fog	
	ructure, after receiving it from the attached sensor nodes in the	
vehicle		
	ta gatherer: This is an intermediate component between the event	
	r and the physical sensor; it helps to gather sensed data.	

c) Virtual sensor interface: Multiple sensors that sense data from	
different locations of the vehicle are present in the system. The virtual	
sensor interface helps to maintain a particular procedure to gather data.	
This component also cooperates to register the sensors in the system.	
2. Tier 2 FISVER STS Fog Infrastructure :	
Tier 2 works on top of the fog architecture. Primarily, this tier has three	
responsibilities— keep updating the new object template definitions,	
classifying events, and finding the most suitable police vehicle to notify the	
event. FISVER STS fog infrastructure is divided into two sub-components.	
(i) Towast Okiest Training.	
 (i) Target Object Training: This subcomponent of Tier 2 is responsible for creating, updating, 	
and storing the crime object definition.	
• The algorithm launcher uses these definitions in Tier 1 for the	
template matching process.	
• The template definition includes different features of the crime	
object such as color gradient and shape format. A new object	
definition is stored in the definition database.	
• The database requires to be updated based on the availability of	
new template definitions.	
(ii) Notification Factory:	
• This sub-component receives notification about the events in a different vehicle with the installed system.	
 Further, this component receives and validates the events. In order 	
to handle multiple events, it maintains a queue.	
to hundre maniple events, it maintains à queue.	
3. Tier 3 consists of mobile applications that are executed on the users'	
devices. The application helps a user, who witnesses a crime, to notify the	
police.	

COURSE INSTRUCTOR

CCI

HOD