

Solutions to IAT1
Subject: Microwave Engineering and Antenna Theory

Internal Assessment Test 1 – Sept. 2025

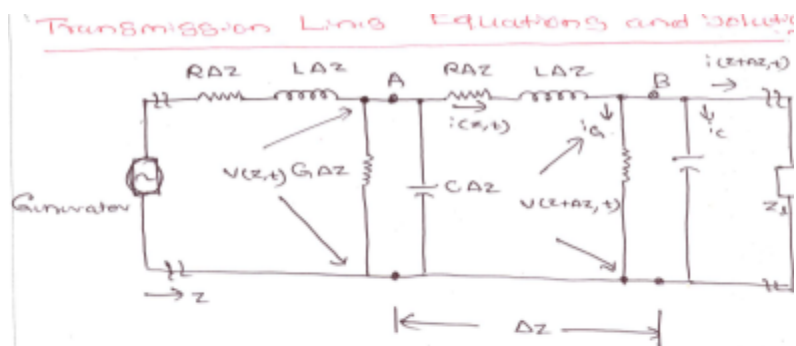
Sl.	Answer any FIVE FULL Questions	Marks	CO	RBT
1	Derive the expression for the voltage and current at any point along a uniform transmission line.	10	1	L2
2	The values of primary constants of an open-wire line per loop kilometers are as follows: $R=10\Omega$, $L=3.5\text{mH}$, $C=0.008\text{ }\mu\text{F}$ and $G=0.7\text{ }\mu\text{S}$. For signal frequency of 1000Hz, calculate the characteristic impedance and propagation constant.	10	1	L3
3	A load impedance of $Z_L=60-j80\text{ }\Omega$ is required to be matched to a 50-ohm coaxial line, by using a short-circuited stub of length 'l' located at a distance 'd' from the load. The wavelength of operation is 1m. Using the Smith chart, find 'd' and 'l'.	10	1	L3
4	Prove symmetric property and unitary property of the S-matrix.	10	2	L2

5	What is a magic tee? Derive the S-matrix of magic tee. Mention its application.	10	2	L2
6	Explain with the neat diagram the precision phase shifter.	10	2	L2
7a	Derive the characteristic impedance of the Microstrip line.	6	2	L2

7b	A certain microstrip line has the following parameters: $\epsilon_r=5.23$, $h=7$ mils, $t=2.8$ mils, $w=10$ mils. Calculate the characteristic impedance Z_0 of the line.	4	2	L3
8a	Write short notes on parallel strip lines.	5	2	L2
8b	Describe ohmic skin losses and radiation losses in micro strip lines.	5	2	L2

Solutions:

1.



Elementary Section of a transmission line.

By Kirchhoff's Voltage law, the summation of the voltage drops around the central loop is given by

$$V(z,t) = R\Delta z i(z,t) + L\Delta z \frac{\partial i(z,t)}{\partial t} + V(z+\Delta z,t)$$

$$= R\Delta z i(z,t) + L\Delta z \frac{\partial i(z,t)}{\partial t} + V(z,t) + \frac{\partial V(z,t)}{\partial z} \Delta z \quad (1)$$

Rearranging this equation, dividing it by Δz , and then omitting the argument (z,t) which is understood, we get

$$\boxed{-\frac{\partial V}{\partial z} = R i + L \frac{\partial i}{\partial t}} \quad (2)$$

Using Kirchhoff's Current law, the summation of the currents at point B can be expressed as

$$\begin{aligned} i(z,t) &= G \Delta z V(z+\Delta z, t) \\ &\quad + C \frac{\partial V(z+\Delta z, t)}{\partial t} \Delta z + i(z+\Delta z, t) \\ &= G \Delta z \left[V(z, t) + \frac{\partial V(z, t)}{\partial z} \Delta z \right] \\ &\quad + C \Delta z \frac{\partial}{\partial t} \left[V(z, t) + \frac{\partial V(z, t)}{\partial z} \Delta z \right] \\ &\quad + i(z, t) + \frac{\partial i(z, t)}{\partial z} \Delta z \quad (3) \end{aligned}$$

$$\begin{aligned} 0 &= G V(z, t) + G \frac{\partial V(z, t)}{\partial z} \Delta z + C \frac{\partial V(z, t)}{\partial t} \Delta z \\ &\quad + C \frac{\partial}{\partial t} \left[\frac{\partial V(z, t)}{\partial z} \Delta z \right] \\ &\quad + \frac{\partial i(z, t)}{\partial z} \Delta z \end{aligned}$$

$$\Rightarrow \boxed{-\frac{\partial i}{\partial z} = G V + C \frac{\partial V}{\partial t}} \quad (4)$$

Differentiating Eq. (2) w.r.t. z we get

$$-\frac{\partial^2 V}{\partial z^2} = R \frac{\partial i}{\partial z} + L \frac{\partial}{\partial z} \left(\frac{\partial i}{\partial t} \right) \quad (5)$$

Differentiating Eq. (4) w.r.t. t we get

$$-\frac{\partial}{\partial t} \left(\frac{\partial i}{\partial z} \right) = G \frac{\partial V}{\partial t} + C \frac{\partial^2 V}{\partial t^2} \quad (6)$$

Substituting equations (4) & (6) in Eq. (5) we get

we get

$$\begin{aligned} -\frac{\partial^2 V}{\partial z^2} &= R \left(-GV - C \frac{\partial V}{\partial t} \right) \\ &\quad + L \left(-G \frac{\partial V}{\partial t} - C \frac{\partial^2 V}{\partial t^2} \right) \\ &= -RGV - RC \frac{\partial V}{\partial t} - LG \frac{\partial V}{\partial t} - LC \frac{\partial^2 V}{\partial t^2} \end{aligned}$$

$$\boxed{\frac{\partial^2 V}{\partial z^2} = RGV + (RC + LG) \frac{\partial V}{\partial t} + LC \frac{\partial^2 V}{\partial t^2}} \quad (6)$$

~~Also~~ Differentiating Eq. (2) w.r.t. t we get

$$-\frac{\partial}{\partial t} \left(\frac{\partial V}{\partial z} \right) = R \frac{\partial i}{\partial t} + L \frac{\partial^2 i}{\partial t^2} \quad (7)$$

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Differentiating Eq. (4) w.r.t. z we get

$$-\frac{\partial^2 i}{\partial z^2} = G \frac{\partial V}{\partial z} + C \frac{\partial}{\partial z} \left(\frac{\partial V}{\partial t} \right) \quad (8)$$

Substituting Eqs. (2), (7) in Eq. (8) we get

$$\begin{aligned} -\frac{\partial^2 i}{\partial z^2} &= G \left(-Ri - L \frac{\partial i}{\partial t} \right) \\ &\quad + C \left[-R \frac{\partial i}{\partial t} - L \frac{\partial^2 i}{\partial t^2} \right] \\ &= -RGi - LG \frac{\partial i}{\partial t} - RC \frac{\partial i}{\partial t} - LC \frac{\partial^2 i}{\partial t^2} \end{aligned}$$

$$\therefore \boxed{\frac{\partial^2 i}{\partial z^2} = RGi + (LG + RC) \frac{\partial i}{\partial t} + LC \frac{\partial^2 i}{\partial t^2}} \quad (9)$$

> The Voltage and Current on the line are the functions of both position z and time t .

> The instantaneous line Voltage and Current can be expressed as

$$v(z, t) = \operatorname{Re} V(z) e^{j\omega t} \quad (10)$$

$$i(z, t) = \operatorname{Re} I(z) e^{j\omega t} \quad (11)$$

where Re stands for "real part of".

> The factors $V(z)$ and $I(z)$ are complex quantities of the sinusoidal functions of position z on the line and are known as phasors.

If we substitute $j\omega$ for $\frac{\partial}{\partial t}$ in equations (2), (4), (6) and (9) and divide each equation by $e^{j\omega t}$, the transmission-line equations in phasor form of the frequency domain become

$$\begin{aligned}\frac{dV}{dz} &= -(R + j\omega L) I \\ &= -Z I\end{aligned}\quad (12)$$

$$\begin{aligned}\frac{dI}{dz} &= -(G + j\omega C) V \\ &= -Y V\end{aligned}\quad (13)$$

$$\frac{d^2 V}{dz^2} e^{j\omega t} = RG V e^{j\omega t} + (RC + LG) j\omega V e^{j\omega t}$$

$$+ LC (j\omega)^2 V e^{j\omega t}$$

$$\frac{d^2 V}{dz^2} = RG V + (RC + LG) j\omega V + LC \omega^2 V$$

$$= \left[RG + RCj\omega + LGj\omega + LC(j\omega)^2 \right] V$$

$$\begin{aligned}&= \left[R(G + j\omega C) + j\omega L(G + j\omega C) \right] V \\ &= (R + j\omega L)(G + j\omega C) V \\ &= Z Y V\end{aligned}$$

$$\frac{d^2 V}{dz^2} = r^2 V \quad (14)$$

$$\frac{d^2 I}{dz^2} = r^2 I \quad (15)$$

in which the following substitutions have been made:

$$Z = R + j\omega L \quad (\text{ohms per unit length}) \quad (16)$$

$$Y = G + j\omega C \quad (\text{mhos per unit length})$$

$$r = \sqrt{ZY} = \alpha + j\beta \quad (\text{propagation constants})$$

α is the attenuation constant in nepers per unit length

β is the phase constant in radians per unit length

Solutions to Transmission Line Equations

The one possible solution for Eq. (14) is

$$\begin{aligned} V &= V_+ e^{-rZ} + V_- e^{rZ} \\ &= V_+ e^{-\alpha Z - j\beta Z} + V_- e^{\alpha Z + j\beta Z} \end{aligned} \quad (17)$$

2.

2. Given

$$R = 10 \Omega, L = 3.5 \text{ mH}, C = 0.08 \text{ nF}$$

$$G = 0.7 \text{ MS}, f = 1000 \text{ Hz}$$

$$Z_o = ? \quad r = ?$$

$$Z_o = \sqrt{\frac{Z}{Y}} = \sqrt{\frac{R + j\omega L}{G + j\omega C}}$$

$$= \sqrt{\frac{10 + j 2\pi \times 1000 \times 3.5 \times 10^{-3}}{0.7 \times 10^{-6} + j 2\pi \times 1000 \times 0.08 \times 10^{-6}}}$$

$$= \sqrt{\frac{10 + j 21.99}{0.7 \times 10^{-6} + j 5 \times 10^{-4}}}$$

$$= \sqrt{\frac{24.15 \angle 65.54^\circ}{5 \times 10^{-4} \angle 89.91^\circ}}$$

$$= 219.77 \angle -12.18^\circ$$

$$r = \sqrt{ZY} = \sqrt{(10 + j 22)(0.7 \times 10^{-6} + j 5 \times 10^{-4})}$$

$$= \sqrt{(24.15 \angle 65.54^\circ)(5 \times 10^{-4} \angle 89.91^\circ)}$$

$$= 0.109 \angle 77.73^\circ$$

3.

$$Z_1 = 60 - j80 \Omega$$

$$Z_0 = 50 \Omega$$

$$Z_2 = \frac{Z_1}{Z_0} = \frac{60 - j80}{50}$$

$$= 1.2 - j1.6$$

$$Y_2 = \frac{1}{Z_2} = 0.3 + j0.4$$

$$d = 0.175\lambda - 0.064\lambda$$

$$= 0.111\lambda$$

$$k = \frac{8}{1000} = \frac{8 \times 10^3}{1000}$$

$$l = 0.344\lambda - 0.25\lambda$$

$$= 0.094\lambda$$

4.

To Show that the $[S]$ matrix for a reciprocal network is Symmetric.

Assuming the characteristic impedances (Z_{0n}) of all the ports are identical. ($Z_{0n} = 1$)

Also, setting $Z_{0n} = 1$ (for convenience)

The total Voltage and Current at the n th port can be written as

$$V_n = V_n^+ + V_n^- \quad (1)$$

$$I_n = V_n^+ - V_n^- \quad (2)$$

Adding equations (1) and (2) we obtain

$$2V_n^+ = V_n + I_n$$

$$V_n^+ = \frac{1}{2} (V_n + I_n)$$

Adding equations (1) and (2) we obtain

$$2V_n^+ = V_n + I_n$$

$$V_n^+ = \frac{1}{2} (V_n + I_n)$$

$$\text{or } (3) \quad [V_n^+] = \frac{1}{2} ([V] + [I]) = \frac{1}{2} ([Z][I] + [I])$$

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$$[V^+] = \frac{1}{2} \{ [Z] + [I] \} [I] \quad (3)$$

~~or~~

Subtracting equation (2) from equation (1) we obtain

$$2V_n^- = V_n - I_n$$

$$V_n^- = \frac{1}{2} (V_n - I_n)$$

$$[V^-] = \frac{1}{2} ([V] - [I])$$

$$= \frac{1}{2} \{ [Z][I] - [I] \}$$

$$= \frac{1}{2} \{ [Z] - [U] \} [I] \quad (4)$$

Dividing equation (4) by equation (3),

$$\frac{[V^-]}{[V^+]} = \{ [Z] - [U] \} \{ [Z] + [U] \}^{-1}$$

$$[V^-] = \{ [Z] - [U] \} \{ [Z] + [U] \}^{-1} [V^+]$$

(5)

So that

(5)

$$[S] = \{ [Z] - [U] \} \{ [Z] + [U] \}^{-1} \quad (6)$$

Taking transpose of (6) gives

$$[S]^t = \{ ([Z] - [U])^t \} \{ ([Z] + [U])^t \}^{-1}$$

Now $[U]$ is diagonal, so $[U]^t = [U]$



and if the network is reciprocal, $[Z]$ is symmetric so that

$$[Z]^t = [Z]$$

The above then reduces to

$$[S]^t = ([Z] - [U])^t ([Z] + [U])^{-1} \quad (7)$$

Comparing equations (6) and (7), we obtain

$$[S]^t = [S]$$

for reciprocal networks.

To show that the $[S]$ matrix for a lossless network is unitary.

- If the network is lossless, then no real power can be delivered to the network.
- Thus, if the characteristic impedances of all the ports are identical and assumed to be unity, the average power delivered to the network is

$$\begin{aligned} P_{av} &= \frac{1}{2} \operatorname{Re} \{ [V]^t [I]^* \} \\ &= \frac{1}{2} \operatorname{Re} \{ ([V^+]^t + [V^-]^t) ([V^+]^* - [V^-]^*) \} \end{aligned}$$

$$\begin{aligned} P_{av} &= \frac{1}{2} \operatorname{Re} \{ [V^+]^t [V^+]^* - [V^+]^t [V^-]^* \\ &\quad + [V^-]^t [V^+]^* - [V^-]^t [V^-]^* \} \end{aligned}$$

- Since the terms $-[V^+]^t [V^-]^* + [V^-]^t [V^+]^*$ are of the form $A - A^*$, and so are pure imaginary.

$$P_{av} = \frac{1}{2} [V^+]^t [V^+]^* - \frac{1}{2} [V^-]^t [V^-]^* \quad (8)$$

- In equation (8) the term $\frac{1}{2} [V^+]^t [V^+]^*$ represents the total incident power and the term $\frac{1}{2} [V^-]^t [V^-]^*$ represents the total reflected power.

So for a lossless ~~network~~ junction, we have the intuitive result that the incident and reflected powers are equal

$$[V^+]^t [V^+]^* = [V^-]^t [V^-]^* \quad (9)$$

Using $[V^-] = [S][V^+]$ in (9) gives

$$[V^+]^t [V^+]^* = [S]^t [V^+]^t [S]^* [V^+]^*$$

If $[V^+]$ is nonzero,

$$[S]^t [S]^* = [I] \quad (10)$$

$$\text{or } [S]^* = \{[S]^t\}^{-1} \quad (11)$$

5.

Magic Tee (E-H Tee)

- Magic Tee is a combination of E-plane Tee and H-plane Tee.
- In this waveguide is cut at both width and breadth and side arms in the direction of magnetic field and electric field are inserted, respectively.
- Ports (1) and (3) form collinear ports, port (3) is called H-arm and port (1) is called E-arm.

S-matrix of Magic Tee

$$[S]_{MT} = \begin{bmatrix} S_{11} & S_{12} & S_{13} & S_{14} \\ S_{21} & S_{22} & S_{23} & S_{24} \\ S_{31} & S_{32} & S_{33} & S_{34} \\ S_{41} & S_{42} & S_{43} & S_{44} \end{bmatrix} \quad (1)$$

$$S_{13} = S_{33} \quad (2) \quad (\text{From H-plane tee action})$$

$$S_{14} = -S_{24} \quad (3) \quad (\text{From E-plane tee action})$$

Due to the geometry, power fed at port 3 cannot come out of port 4, and vice versa.

$$S_{34} = S_{43} = 0 \quad (4)$$

Assume ports 3 and 4 are matched

$$S_{33} = S_{44} = 0 \quad (5)$$

Magic Tee is reciprocal. Hence, Symmetric property also holds good.

$$S_{ij} = S_{ji} \quad (6)$$

Using equations (2) to (6) in equation (1), the S-matrix simplifies to the following matrix

$$[S]_{MT} = \begin{bmatrix} S_{11} & S_{12} & S_{13} & S_{14} \\ S_{12} & S_{22} & S_{13} & -S_{14} \\ S_{13} & S_{13} & 0 & 0 \\ S_{14} & -S_{14} & 0 & 0 \end{bmatrix} \quad (7)$$

$$[S][S]^* = [U] \quad (8)$$

(from Unitary property)

$$\begin{bmatrix} S_{11} & S_{12} & S_{13} & S_{14} \\ S_{12} & S_{22} & S_{13} & -S_{14} \\ S_{13} & S_{13} & 0 & 0 \\ S_{14} & -S_{14} & 0 & 0 \end{bmatrix} = \begin{bmatrix} S_{11}^* & S_{12}^* & S_{13}^* & S_{14}^* \\ S_{12}^* & S_{22}^* & S_{13}^* & -S_{14}^* \\ S_{13}^* & S_{13}^* & 0 & 0 \\ S_{14}^* & -S_{14}^* & 0 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$|S_{11}|^2 + |S_{12}|^2 + |S_{13}|^2 + |S_{14}|^2 = 1 \quad (10)$$

$$|S_{12}|^2 + |S_{22}|^2 + |S_{13}|^2 + |S_{14}|^2 = 1 \quad (11)$$

$$|S_{13}|^2 + |S_{13}|^2 = 1 \quad (12)$$

$$|S_{14}|^2 + |S_{14}|^2 = 1 \quad (13)$$

$$S_{13} S_{11}^* + S_{13} S_{12}^* = 0 \quad (14)$$

$$\text{From (12), } 2|S_{13}|^2 = 1$$

$$|S_{13}|^2 = \frac{1}{2}$$

$$S_{13} = \frac{1}{\sqrt{2}} \quad (15)$$

From (13), $2|S_{14}|^2 = 1$

$$|S_{14}|^2 = \frac{1}{2}$$

$$S_{14} = \frac{1}{\sqrt{2}} \quad (16)$$

Using (15) and (16) in (10) and (11),

$$|S_{11}|^2 + |S_{12}|^2 + \frac{1}{2} + \frac{1}{2} = 1$$

$$|S_{11}|^2 + |S_{12}|^2 = 0 \quad (17)$$

$$|S_{12}|^2 + |S_{22}|^2 = 0 \quad (18)$$

$$\Rightarrow S_{11} = S_{22} \quad (19)$$

Equation (17) is possible only when $S_{11} = S_{12} = 0$

$$[S]_{MT} = \begin{bmatrix} 0 & 0 & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 0 & 0 & \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 & 0 \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} & 0 & 0 \end{bmatrix}$$

Applications of Magic Tee

- (i) As an impedance bridge for measurement of impedance at microwave frequencies.
- (ii) As balanced mixer in Superhetrodyne receiver.
- (iii) As E-H tuner for impedance matching.
- (iv) As power combiner.
- (v) As a duplexer in radar system.

Rotary phase shifter (Precision type phase shifter)

→ Because of its accuracy, the rotary phase shifter is used as a calibration standard in most microwave laboratories.

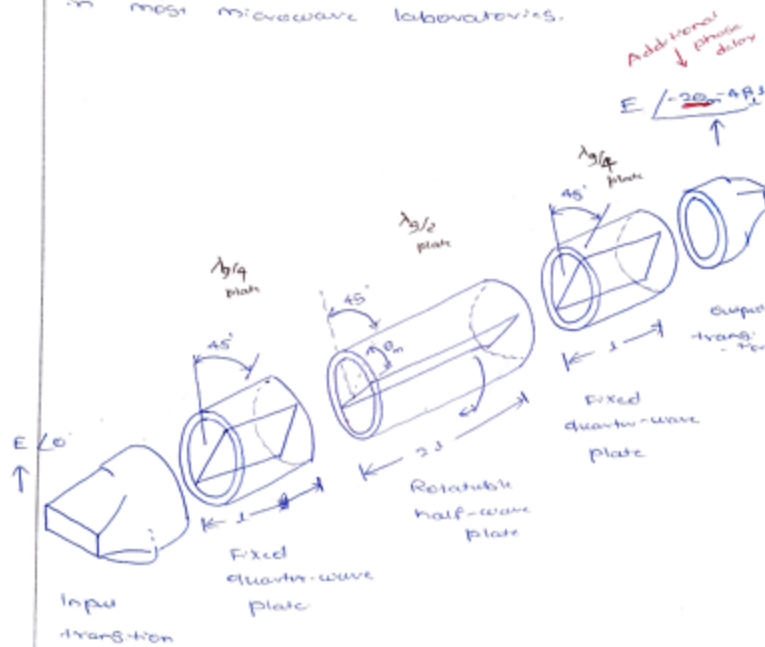


Fig 1 Rotary Phase Shifter

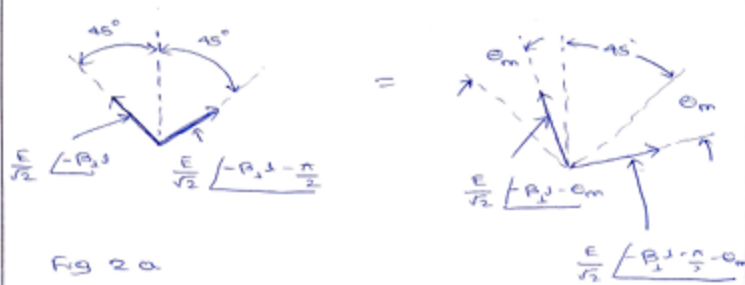


Fig 2a

Vector-phasor components at the input to the rotatable section

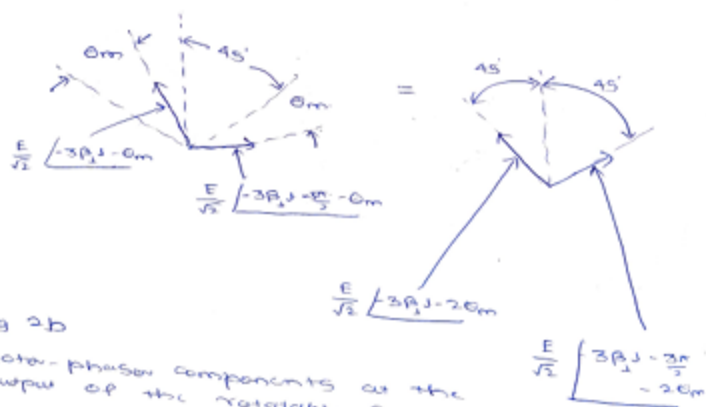


Fig 2b

Vector-phasor components at the output of the rotatable section

Vector-phasor representation

Working

- The vector-phaser $E \angle 0$ represents the vertically polarized input wave.
- It may be decomposed into two components, one perpendicular and one parallel to the dielectric slab of the input quarter-wave plate.
- The value of each component is $\frac{E \angle 0}{\sqrt{2}}$.
- When $\Theta_m = 0$, all three dielectric slabs are in phase line. In this case, the perpendicular and parallel components arrive at the output phase delayed $4\beta_{\perp}L$ and $4\beta_{\parallel}L + 2\pi$, respectively, where $\beta_{\perp}$ represents the phase constant of the circular guide for the perpendicular component and $4L$ is the overall length of the three circular sections.
- With the two components in phase (or rad being equivalent to zero phase).

the output is a vertically polarized wave of value $E \sqrt{-4B_{\perp} I}$.

- The orientation of the output transition is such that the wave is delivered to the output rectangular guide without reflection or loss.
- The following analysis shows that the output wave experiences an additional phase delay of $2\theta_m$ when the half wave plate is rotated by an angle θ_m .
- Also, the output remains vertically polarized which means that the phase shifter is lossless and reflectionless for any position of the rotatable section.
- As indicated earlier, the input wave may be decomposed into two components. The effect of the input quarter-wave plate is to delay the perpendicular component $B_{\perp} I$ and the parallel component $B_{\parallel} I + \pi/2$, which

- results in a clockwise circularly polarized wave at the input to the rotatable section.
- When $\Theta_m \neq 0$, it is convenient to replace these components ~~by~~ by two ~~other~~ other components, one perpendicular to the dielectric slab in the rotatable section and one parallel to it.
 - Both sets of components are shown in Fig. 2(a).
 - With the length of the half-wave plate equal to $2d$, the perpendicular and parallel components are further delayed $2\beta_{\perp}d$ and $2\beta_{\parallel}d + \pi$, respectively.
 - The resultant components are shown in Fig. 2(b).
 - This now represents a counterclockwise circularly polarized wave.
 - As before, these components may be replaced by an equivalent set that are perpendicular and parallel to the output dielectric slab.

- Their vector representation is shown on the right side of ~~part c~~ in Fig 2 b.
- Propagation through the output quarter wave plate delays these components an additional $\beta_z d$ and $\beta_z d + \pi/2$, respectively.
- As a result, the value of the output components are
- $$\frac{E}{\sqrt{2}} \angle -4\beta_z d - 2\theta_m \quad \text{and} \quad \frac{E}{\sqrt{2}} \angle -4\beta_z d - 2\pi - 2\theta_m$$
- With the waves in phase, vector addition results in a vertically polarized output wave of value $E \angle -4\beta_z d - 2\theta_m$, which is shown in Figure 1.
- Thus, the analysis verifies that rotating the center section an angle θ_m causes the output to be phase delayed an additional $2\theta_m$.
- Also, with the orientation of the output transition as shown, the vertically

Characteristic Impedance

Obtained from wire-over ground model

$$\epsilon_{re} = 0.475 \epsilon_r + 0.67$$

- ϵ_{re} is called effective dielectric constant
- ϵ_r is called relative dielectric constant

$$Z_0 = \frac{87}{\sqrt{\epsilon_r + 1.41}} \ln \left[\frac{5.98h}{0.8w + t} \right] \quad \text{for } h < 0.8w$$

$$Z_0 = \frac{377}{\sqrt{\epsilon_r}} \frac{h}{w} \quad \text{for } w \gg h$$

Example 11-1-1: Characteristic Impedance of Microstrip Line

A certain microstrip line has the following parameters:

$$\begin{aligned}\epsilon_r &= 5.23 \\ h &= 7 \text{ mils} \\ t &= 2.8 \text{ mils} \\ w &= 10 \text{ mils}\end{aligned}$$

Calculate the characteristic impedance Z_0 of the line.

Solution

$$\begin{aligned}Z_0 &= \frac{87}{\sqrt{\epsilon_r + 1.41}} \ln \left[\frac{5.98h}{0.8w + t} \right] \\ &= \frac{87}{\sqrt{5.23 + 1.41}} \ln \left[\frac{5.98 \times 7}{0.8 \times 10 + 2.8} \right] \\ &= 45.78 \, \Omega\end{aligned}$$

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Ohmic Losses

- Comes into picture due to finite conductivity of microstrip conductor
- Attenuation constant due to ohmic loss of a wide microstrip line ($w > h$) is given by

$$\alpha_c = \frac{8.686}{Z_0 w} \sqrt{\frac{\pi f \mu}{\sigma}} \text{ dB/cm}$$

Radiation Losses

- At microstrip frequencies, the microstrip line acts as an antenna, resulting in radiation losses.
- The ratio of radiated power to the total dissipated power in the microstrip is given by

$$\frac{P_{rad}}{P_t} = \frac{R_r}{Z_0}$$

- R_r = radiation resistance of the microstrip

$$R_r = 240\pi^2 \left(\frac{h}{\lambda_0}\right)^2 F(\epsilon_{re})$$

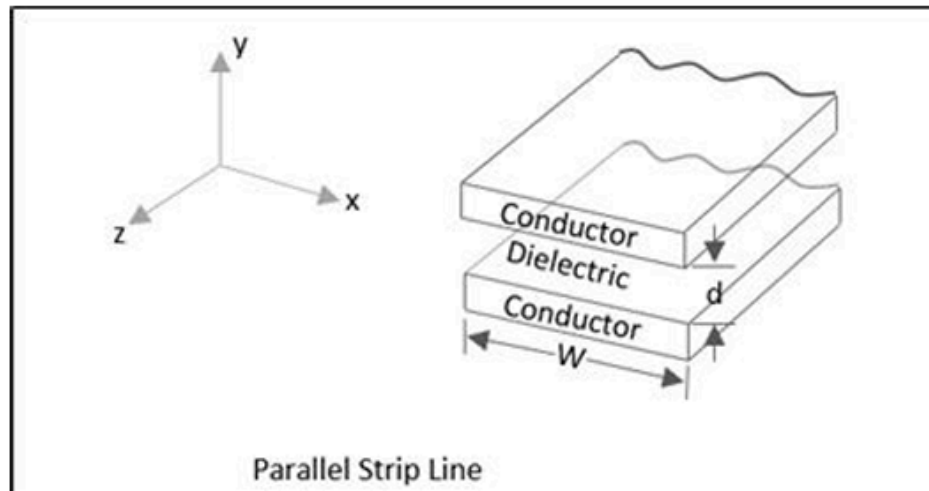
Where

λ_0 = Free – space wavelength

$F(\epsilon_{re})$ = radiation factor given by

$$F(\epsilon_{re}) = \frac{\epsilon_{re} + 1}{\epsilon_{re}} - \frac{\epsilon_{re} - 1}{2(\epsilon_{re})^{3/2}} \ln \frac{\sqrt{\epsilon_r} + 1}{\sqrt{\epsilon_r} - 1}$$

Parallel Strip Lines



If $w \gg d$, then the fringing capacitance becomes negligibly small.

The inductance along the two conducting strips is given by

$$L = \frac{\mu_c d}{w} \text{ henry/m}$$

Where μ_c = permeability of the conductor

The capacitance between the two parallel conducting strips is given by

$$C = \frac{\epsilon_d w}{d} \text{ farad/m}$$

The series resistance of both strips is given by

$$R = \frac{2R_s}{w} = \frac{2}{w} \sqrt{\frac{\pi f \mu_c}{\sigma_c}} \frac{\Omega}{\text{m}}$$

Where R_s = surface resistance

σ_c = conductivity of the strips in mhos/m

The shunt conductance of the parallel strip line is

$$G = \frac{\sigma_c w}{d} \quad \text{mhos/m}$$

Where σ_c is conductivity of the dielectric material between the two strips

Characteristic Impedance Z_0

$$Z_0 = \frac{377}{\sqrt{\epsilon_{rd}}} \left(\frac{d}{w} \right) \quad \Omega$$

The phase velocity of the TEM wave propagating through the parallel strip line is given by

$$v_p = \frac{c}{\sqrt{\epsilon_{rd}}} \quad \text{m/s}$$