

First Semester B.E./B.Tech. Degree Examination, Dec.2025/Jan.2026
Calculus and Linear Algebra : CSE Stream

Time: 3 hrs.

Max. Marks: 100

Note: 1. Answer any FIVE full questions choosing ONE full question from each module.
 2. M: Marks, L: Bloom's level, C: Course outcomes.
 3. VTU Handbook is permitted.

		Module -1		
Q.1	a.	M	L	C
	Find the total derivative when $u = x^2y^2 + x^2y^3$ where $x = at^2, y = 2at$	6	L2	CO1
	b. If $u = \log(\tan x + \tan y + \tan z)$ then show that $\sin 2x \frac{\partial u}{\partial x} + \sin 2y \frac{\partial u}{\partial y} + \sin 2z \frac{\partial u}{\partial z} = 2$	7	L2	CO1
	c. Expand $e^{x^2 \sin y}$ in the powers of x and y as far as terms of third term using Maclaurin's series.	7	L3	CO1
OR				
Q.2	a.	M	L	C
	If $u = x + y + z, v = x^2 + y^2 + z^2, w = xy + yz + zx$. Evaluate the Jacobian of (u, v, w) with respect to (x, y, z) .	6	L2	CO1
	b. If $u = f\left(\frac{x}{y}, \frac{y}{z}, \frac{z}{x}\right)$ then prove that $x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} + z \frac{\partial u}{\partial z} = 0$	7	L2	CO1
	c. Examine the function for the extreme values, given $f(x, y) = x^3 + 3xy^2 - 15x^2 - 15y^2 + 72x$	7	L3	CO1
Module -2				
Q.3	a.	M	L	C
	Find the directional derivative of $\phi = x^2yz + 4xz^2$ at the point $(1, -2, -1)$ in the direction $2i - j - 2k$.	6	L2	CO1
	b. Show that $\vec{F} = (y+z)\hat{i} + (z+x)\hat{j} + (x+y)\hat{k}$ is irrotational and find the scalar potential.	7	L2	CO1
	c. With usual notation, Prove that cylindrical polar coordinate system is orthogonal.	7	L3	CO1
OR				
Q.4	a.	M	L	C
	Given $\vec{F} = \nabla(xy^3z^2)$, Find $\text{div}(\vec{F})$ and $\text{curl}(\vec{F})$ at $(1, -1, 1)$.	6	L2	CO1
	b. Show that $\vec{F} = \frac{x\hat{i} + y\hat{j}}{x^2 + y^2}$ is both solenoidal and irrotational.	7	L2	CO1
	c. Express $2y\hat{i} - z\hat{j} + 3x\hat{k}$ in terms of spherical polar coordinates.	7	L3	CO1

		Module -3		
Q.5	a.	M	L	C
	Find the rank of the matrix $A = \begin{bmatrix} 2 & 1 & -1 & 3 \\ 1 & 2 & 4 & 3 \\ 3 & 6 & 12 & 9 \\ 3 & 3 & 3 & 6 \end{bmatrix}$	6	L2	CO2
	b. Using Gauss Jordan method, solve the system of equations $x + y + z = 9, x - 2y + 3z = 8, 2x + y - z = 3$.	7	L2	CO2
	c. Diagonalize the matrix $\begin{bmatrix} -1 & 3 \\ -2 & 4 \end{bmatrix}$.	7	L3	CO2
OR				
Q.6	a.	M	L	C
	Investigate the value of μ and λ such that the equations, $x + y + z = 6, x + 2y + 3z = 10, x + 2y + \lambda z = \mu$, may have (i) unique solution (ii) infinite solution (iii) no solution	6	L2	CO2
	b. Using Gauss Elimination method, solve the system of equations $x + 2y + z = 3, 2x + 3y + 3z = 10, 3x - y + 2z = 13$	7	L2	CO2
	c. Find the eigen value and eigen vectors of the matrix $A = \begin{bmatrix} 1 & 1 & 3 \\ 1 & 5 & 1 \\ 3 & 1 & 1 \end{bmatrix}$	7	L3	CO2
Module -4				
Q.7	a.	M	L	C
	Determine whether the vectors $(8,0,5)$ is a linear combination of the vectors $(1,2,3), (0,1,4), (2,-1,1)$	6	L2	CO3
	b. Find the basis and dimension of the subspace spanned by the vectors $(2,4,2), (1,-1,0), (1,2,1), (0,3,1)$ in $V_3(R)$.	7	L2	CO3
	c. Find the basis and dimension of the row space, column space and null space of the matrix $\begin{bmatrix} 1 & -1 & 1 & 3 & 2 \\ 2 & -1 & 1 & 5 & 1 \\ 0 & 1 & -1 & -1 & -3 \end{bmatrix}$	7	L3	CO3
OR				
Q.8	a.	M	L	C
	Find the coordinates of the vector $v = (0,1,3)$ with respect to the basis $B = \{(1,1,0), (0,1,1), (1,0,1)\}$.	6	L2	CO3
	b. Define inner product space. Given $u = (1,2,4), v = (2,-3,5), w = (4,2,-3)$ in R^3 . Find (i) $\langle u, v \rangle$ (ii) $\langle v, w \rangle$ (iii) $\langle u, w \rangle$ (iv) $\ u\ $ (v) $\ v\ $	7	L2	CO3
	c. What is a subspace? Prove that the subset $W = \{(x, y, z) / x - 3y + 4z = 0\}$ of the vector space R^3 is a subspace.	7	L3	CO3
Module -5				
Q.9	a.	M	L	C
	Show that the transformation $T: R^2 \rightarrow R^3$ defined by $T(x, y) = (x + y, x - y, y)$ is a linear transformation.	6	L2	CO3

$$-1 \quad a. \quad u = x^3 y^2 + x^2 y^3 \quad x = at^2 \quad y = 2at$$

$$\frac{du}{dt} = \frac{\partial u}{\partial x} \frac{dx}{dt} + \frac{\partial u}{\partial y} \frac{dy}{dt}$$

$$u = x^3 y^2 + x^2 y^3$$

$$\frac{\partial u}{\partial x} = 3x^2 y^2 + 2xy^3 \quad \frac{\partial u}{\partial y} = 2x^3 y + 3x^2 y^2$$

$$x = at^2$$

$$y = 2at$$

$$\frac{dx}{dt} = 2at$$

$$\frac{dy}{dt} = 2a$$

$$\frac{du}{dt} = (3x^2 y^2 + 2xy^3) 2at + (2x^3 y + 3x^2 y^2) 2a$$

$$\begin{aligned} \frac{du}{dt} &= [3(a^2 t^4)(4a^2 t^2) + 2(at^2) 8a^3 t^3] 2at \\ &+ [2(a^3 t^6)(2at) + 3(a^2 t^4)(4a^2 t^2)] 2a \\ &= [12a^4 t^6 + 16a^4 t^5] 2at + [4a^4 t^7 + 12a^4 t^6] 2a \end{aligned}$$

$$= 24a^5 t^7 + 32a^5 t^6 + 8a^5 t^7 + 24a^5 t^6$$

$$\frac{du}{dt} = 32a^5 t^7 + 56a^5 t^6 //$$

$$\sec \theta = \frac{1}{\cos \theta}$$

$$\sin 2\theta = 2 \sin \theta \cos \theta$$

$$u = \log (\tan x + \tan y + \tan z) \therefore \text{ST}$$

$$\sin 2x \frac{\partial u}{\partial x} + \sin y \frac{\partial u}{\partial y} + \sin 2z \frac{\partial u}{\partial z} = 2$$

Partial differentiation w.r.t x

$$\frac{\partial u}{\partial x} = \frac{1}{\tan x + \tan y + \tan z} \times \sec^2 x$$

Partial diff w.r.t y

$$\frac{\partial u}{\partial y} = \frac{1}{\tan x + \tan y + \tan z} \times \sec^2 y$$

Partial diff w.r.t z

$$\frac{\partial u}{\partial z} = \frac{1}{\tan x + \tan y + \tan z} \times \sec^2 z$$

$$\text{LHS} \Rightarrow \sin 2x \left[\frac{\sec^2 x}{\tan x + \tan y + \tan z} \right] + \sin y \left[\frac{\sec^2 y}{\tan x + \tan y + \tan z} \right]$$

$$+ \sin 2z \left[\frac{\sec^2 z}{\tan x + \tan y + \tan z} \right]$$

$$a^3 + b^3 + c^3 - 3abc = (a+b+c)(a^2 + b^2 + c^2 - ab - bc - ca)$$

graphikan

$$\frac{\sin x}{\tan x + \tan y + \tan z} = \sin x \sec^2 x + \sin y \sec^2 y + \sin z \sec^2 z$$

$$\frac{\sin x \cos x \times 1}{\cos^2 x} + \frac{\sin y \cos y \times 1}{\cos^2 y} + \frac{\sin z \cos z \times 1}{\cos^2 z}$$

$$\frac{2 \sin x + 2 \sin y + 2 \sin z}{\cos x \cos y \cos z}$$

$$\frac{2 \tan x + 2 \tan y + 2 \tan z}{2}$$

$$\tan x + \tan y + \tan z = \text{RHS}$$

Hence showed

$$x^3 + y^3 + z^3 - 3xyz = (x+y+z)(x^2 + y^2 + z^2 - xy - yz - zx)$$

$$f(x, y) = e^x \sin y$$

$$f(x, y) = f(0, 0) + x f_x(0, 0) + y f_y(0, 0) + \frac{1}{2!} [x^2 f_{xx}(0, 0) + 2xy f_{xy}(0, 0) + y^2 f_{yy}(0, 0)] + \frac{1}{3!} [x^3 f_{xxx}(0, 0) + 3x^2 y f_{xxy}(0, 0) + 3xy^2 f_{xyy}(0, 0) + y^3 f_{yyy}(0, 0)]$$

$$f(x, y) = e^x \sin y \Rightarrow f(0, 0) = 0$$

$$f_x = e^x \sin y \Rightarrow f(0, 0) = 0$$

$$f_y = e^x \cos y \Rightarrow f(0, 0) = 1$$

$$f_{xx} = e^x \sin y \Rightarrow f(0, 0) = 0$$

$$f_{yy} = -e^x \sin y \Rightarrow f(0, 0) = 0$$

$$f_{xy} = e^x \cos y \Rightarrow f(0, 0) = 1$$

$$f_{xxx} = e^x \sin y \Rightarrow f(0, 0) = 0$$

$$f_{yyy} = -e^x \sin y \Rightarrow f(0, 0) = 0$$

$$f_{yyy} = -e^x \cos y \Rightarrow f(0, 0) = -1$$

$$f_{xxy} = e^x \cos y \Rightarrow f(0, 0) = 1$$

$$\therefore f(x, y) = y + \frac{1}{2!} [2xy(1)] + \frac{1}{3!} [3x^2y - y^3]$$

$$f(x, y) = y + xy + \frac{1}{6} [3x^2y - y^3]$$

① $u = x^2 - 2y^2$, $v = 2x^2 - y^2$, find $\frac{\partial(u,v)}{\partial(x,y)}$?

② $J = \frac{\partial(x,y,z)}{\partial(\rho,\phi,z)}$, $x = \rho \cos \phi$, $y = \rho \sin \phi$, $z = z$?

$$J = \begin{vmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{vmatrix}$$

$$J = 1 //$$

Find $\frac{\partial(u,v,w)}{\partial(x,y,z)}$ where $x^2 + y^2 + z^2 = u$, $v = xy + yz + xz$, $w = x + y + z$?

$\frac{\partial(u,v,w)}{\partial(x,y,z)}$	$\frac{\partial u}{\partial x}$	$\frac{\partial u}{\partial y}$	$\frac{\partial u}{\partial z}$
	$\frac{\partial v}{\partial x}$	$\frac{\partial v}{\partial y}$	$\frac{\partial v}{\partial z}$
	$\frac{\partial w}{\partial x}$	$\frac{\partial w}{\partial y}$	$\frac{\partial w}{\partial z}$

$$u = x^2 + y^2 + z^2$$

$$\frac{\partial u}{\partial x} = 2x + 0 + 0 = 2x, \quad \frac{\partial u}{\partial y} = 0 + 2y + 0 = 2y, \quad \frac{\partial u}{\partial z} = 0 + 0 + 2z$$

$$v = xy + yz + xz$$

$$\frac{\partial v}{\partial x} = y + 0 + z = y + z, \quad \frac{\partial v}{\partial y} = x + z + 0 = x + z, \quad \frac{\partial v}{\partial z} = 0 + y + x = x + y$$

$$w = x + y + z$$

$$\frac{\partial w}{\partial x} = 1 + 0 + 0 = 1, \quad \frac{\partial w}{\partial y} = 0 + 1 + 0 = 1, \quad \frac{\partial w}{\partial z} = 0 + 0 + 1 = 1$$

$$J = \frac{\partial(u,v,w)}{\partial(x,y,z)} = \begin{vmatrix} 2x & 2y & 2z \\ y+z & x+z & x+y \\ 1 & 1 & 1 \end{vmatrix}$$

$$J = 2x [(x+z) - (x+y)] - 2y [(y+z) - (x+y)] + 2z [(y+z) - (x+z)]$$

$$J = 2x [x+z - x - y] - 2y [y+z - x - y] + 2z [y+z - x - z]$$

$$\neq 2xz - 2xy - 2yz + 2xy + 2zy - 2xz$$

$$J = 0 //$$

Hence, proved

Type 2

A. If $V = f(x, y, z)$ if $r = \frac{x}{y}$, $s = \frac{y}{z}$, $t = \frac{z}{x}$. ST

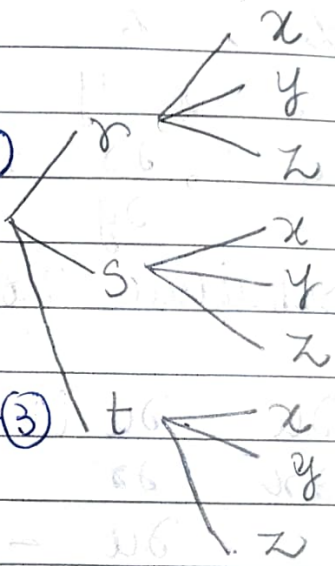
$$x \frac{\partial V}{\partial x} + y \frac{\partial V}{\partial y} + z \frac{\partial V}{\partial z} = 0$$

Ans:

$$\frac{\partial V}{\partial x} = \frac{\partial V}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial V}{\partial s} \frac{\partial s}{\partial x} + \frac{\partial V}{\partial t} \frac{\partial t}{\partial x} \quad \text{--- (1)}$$

$$\frac{\partial V}{\partial y} = \frac{\partial V}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial V}{\partial s} \frac{\partial s}{\partial y} + \frac{\partial V}{\partial t} \frac{\partial t}{\partial y} \quad \text{--- (2)}$$

$$\frac{\partial V}{\partial z} = \frac{\partial V}{\partial r} \frac{\partial r}{\partial z} + \frac{\partial V}{\partial s} \frac{\partial s}{\partial z} + \frac{\partial V}{\partial t} \frac{\partial t}{\partial z} \quad \text{--- (3)}$$



$$r = \frac{x}{y}$$

$$\frac{\partial r}{\partial x} = \frac{1}{y}, \quad \frac{\partial r}{\partial y} = -\frac{x}{y^2}, \quad \frac{\partial r}{\partial z} = 0$$

$$s = \frac{y}{z}$$

$$\frac{\partial s}{\partial x} = 0, \quad \frac{\partial s}{\partial y} = \frac{1}{z}, \quad \frac{\partial s}{\partial z} = -\frac{y}{z^2}$$

$$t = \frac{z}{x}$$

$$\frac{\partial t}{\partial x} = -\frac{z}{x^2}, \quad \frac{\partial t}{\partial y} = 0, \quad \frac{\partial t}{\partial z} = \frac{1}{x}$$

substitute all values in eq ①, ②, ③

$$\begin{aligned} \frac{\partial v}{\partial x} &= \frac{\partial v}{\partial r} \left(\frac{1}{y} \right) + \frac{\partial v}{\partial s} (0) + \frac{\partial v}{\partial t} \left(-\frac{z}{x^2} \right) \\ &= \frac{1}{y} \frac{\partial v}{\partial r} - \frac{z}{x^2} \frac{\partial v}{\partial t} \end{aligned}$$

$$\begin{aligned} \frac{\partial v}{\partial y} &= \frac{\partial v}{\partial r} \left(-\frac{x}{y^2} \right) + \frac{\partial v}{\partial s} \left(\frac{1}{z} \right) + \frac{\partial v}{\partial t} (0) \\ &= -\frac{x}{y^2} \frac{\partial v}{\partial r} + \frac{\partial v}{\partial s} \end{aligned}$$

$$\begin{aligned} \frac{\partial v}{\partial z} &= \frac{\partial v}{\partial r} (0) + \frac{\partial v}{\partial s} \left(-\frac{y}{z} \right) + \frac{\partial v}{\partial t} \left(\frac{1}{x} \right) \\ &= -\frac{y}{z} \frac{\partial v}{\partial s} + \frac{\partial v}{\partial t} \end{aligned}$$

LHS [sub $\frac{\partial v}{\partial x}$, $\frac{\partial v}{\partial y}$, $\frac{\partial v}{\partial z}$ in RHS]

$$x \frac{\partial v}{\partial x} + y \frac{\partial v}{\partial y} + z \frac{\partial v}{\partial z}$$

$$x \left[\frac{1}{y} \frac{\partial v}{\partial r} - \frac{z}{x^2} \frac{\partial v}{\partial t} \right] + y \left[-\frac{x}{y^2} \frac{\partial v}{\partial r} + \frac{\partial v}{\partial s} \right] + z \left[-\frac{y}{z} \frac{\partial v}{\partial s} + \frac{\partial v}{\partial t} \right]$$

$$\frac{x}{y} \frac{\partial v}{\partial r} - \frac{z}{x} \frac{\partial v}{\partial t} - \frac{x}{y} \frac{\partial v}{\partial r} + y \frac{\partial v}{\partial s} - y \frac{\partial v}{\partial s} + z \frac{\partial v}{\partial t}$$

// 0

Minimum value of $f(x, y)$ is $f(1, 2) = 1 + 8 - 3 - 24 + 20 = 2$

Thus, **Maximum value is 38 and Minimum value is 2.**

[50] Find the maximum and minimum values of the function

$$x^3 + 3xy^2 - 15x^2 - 15y^2 + 72x$$

[Sep 20, Apr 23]

For the given function $f(x, y)$ we have,

$$f_x = 3x^2 + 3y^2 - 30x + 72, \quad f_y = 6xy - 30y$$

We shall find points (x, y) such that $f_x = 0$ and $f_y = 0$.

$$3x^2 + 3y^2 - 30x + 72 = 0 \quad \text{or} \quad x^2 + y^2 - 10x + 24 = 0 \quad \dots (1)$$

$$6xy - 30y = 0 \quad \text{or} \quad y(x - 5) = 0 \quad \dots (2)$$

(2) gives us $y = 0$ and $x = 5$.

Putting $y = 0$ in (1) we get $x^2 - 10x + 24 = 0$ or

$$(x - 4)(x - 6) = 0 \quad \text{or} \quad x = 4, 6$$

$\therefore (4, 0), (6, 0)$ are stationary points

Putting $x = 5$ in (1), we get $y^2 - 1 = 0$ or $y = \pm 1$

$\therefore (5, 1), (5, -1)$ are also stationary points.

Let us examine these points for maxima and minima.

Let $A = f_{xx}$, $B = f_{xy}$, $C = f_{yy}$

	$(4, 0)$	$(6, 0)$	$(5, 1)$	$(5, -1)$
$A = 6x - 30$	$-6 < 0$	$6 > 0$	0	0
$B = 6y$	0	0	6	-6
$C = 6x - 30$	-6	6	0	0
$AC - B^2$	$36 > 0$	$36 > 0$	$-36 < 0$	$-36 < 0$
Conclusion	Max. pt.	Min. pt.	Saddle pt.	Saddle pt.

Maximum value of $f(x, y)$ is $f(4, 0) = 64 - 240 + 288 = 112$

Minimum value of $f(x, y)$ is $f(6, 0) = 216 - 540 + 432 = 108$

Thus,

Maximum value is 112 and minimum value is 108.

[51] Examine the function $xy (a - x - y)$

Module-2

3^o Given $\phi = xyz + 4xz^2$ at $(1, -2, -1)$

and direction $2\hat{i} - \hat{j} + 6\hat{k}$

$$\text{so } \nabla\phi = \frac{\partial\phi}{\partial x}\hat{i} + \frac{\partial\phi}{\partial y}\hat{j} + \frac{\partial\phi}{\partial z}\hat{k}$$

$$\text{i.e., } \nabla\phi = (2xyz + 4z^2)\hat{i} + (xz^2)\hat{j} + (xy + 8xz)\hat{k}$$

$$[\nabla\phi]_{(1, -2, -1)} = 8\hat{i} - \hat{j} - 10\hat{k}$$

The unit vector in the direction of $2\hat{i} - \hat{j} - 2\hat{k}$ is

$$\hat{n} = \frac{2\hat{i} - \hat{j} - 2\hat{k}}{\sqrt{4+1+4}} = \frac{2\hat{i} - \hat{j} - 2\hat{k}}{3}; \text{ The required}$$

directional derivative is

$$\nabla\phi \cdot \hat{n} = \frac{(8\hat{i} - \hat{j} - 10\hat{k}) \cdot (2\hat{i} - \hat{j} - 2\hat{k})}{3}$$

$$\text{Thus } \nabla\phi \cdot \hat{n} = \frac{(8)(2) + (-1)(-1) + (-10)(-2)}{3} = \frac{37}{3}$$

$$\boxed{\nabla\phi \cdot \hat{n} = \frac{37}{3}}$$

(8b)

Given $\vec{F} = (y+z)\mathbf{i} + (z+x)\mathbf{j} + (x+y)\mathbf{k}$

Now

$$\nabla \times \vec{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y+z & z+x & x+y \end{vmatrix}$$

$$= \mathbf{i} \left(\frac{\partial}{\partial y} (x+y) - \frac{\partial}{\partial z} (z+x) \right) - \mathbf{j} \left(\frac{\partial}{\partial x} (x+y) - \frac{\partial}{\partial z} (y+z) \right)$$

$$+ \mathbf{k} \left(\frac{\partial}{\partial x} (z+x) - \frac{\partial}{\partial y} (y+z) \right)$$

$$= \mathbf{i} (1-1) - \mathbf{j} (1-1) + \mathbf{k} (1-1) = \vec{0}$$

$\therefore \boxed{\nabla \times \vec{F} = \vec{0}}$ \rightarrow Given vector \vec{F} is irrotational.

For scalar potential (ϕ) we have $\nabla \phi = \vec{F}$

$$\frac{\partial \phi}{\partial x} \mathbf{i} + \frac{\partial \phi}{\partial y} \mathbf{j} + \frac{\partial \phi}{\partial z} \mathbf{k} = (y+z)\mathbf{i} + (z+x)\mathbf{j} + (x+y)\mathbf{k}$$

$$\begin{aligned} \Rightarrow \frac{\partial \phi}{\partial x} &= y+z & \Rightarrow \phi &= xy + xz + f(y,z) & \text{--- (1)} \\ \frac{\partial \phi}{\partial y} &= z+x & \Rightarrow \phi &= zy + xy + f(x,z) & \text{--- (2)} \\ \frac{\partial \phi}{\partial z} &= x+y & \Rightarrow \phi &= xz + yz + f(x,y) & \text{--- (3)} \end{aligned}$$

By ① & ② & ③

$$\phi = xy + yz + zx$$

we have for the cylindrical system

$$\vec{r} = \rho \cos \phi \hat{i} + \rho \sin \phi \hat{j} + z \hat{k}$$

Let $\hat{e}_\rho, \hat{e}_\phi, \hat{e}_z$ be the basic unit vectors of this system.

Further we have, $h_1 = 1, h_2 = \rho, h_3 = 1$ for the cylindrical system.

Using the definition of the unit vectors,

$$\hat{e}_\rho = \frac{1}{h_1} \frac{\partial \vec{r}}{\partial \rho} = \cos \phi \hat{i} + \sin \phi \hat{j} + 0 \hat{k}$$

$$\hat{e}_\phi = \frac{1}{h_2} \frac{\partial \vec{r}}{\partial \phi} = \frac{1}{\rho} (-\rho \sin \phi \hat{i} + \rho \cos \phi \hat{j} + 0 \hat{k}) = -\sin \phi \hat{i} + \cos \phi \hat{j} + 0 \hat{k}$$

$$\hat{e}_z = \frac{1}{h_3} \frac{\partial \vec{r}}{\partial z} = \frac{1}{1} (0 \hat{i} + 0 \hat{j} + 1 \hat{k}) = 0 \hat{i} + 0 \hat{j} + 1 \hat{k}$$

Now, $\hat{e}_\rho \cdot \hat{e}_\phi = -\cos \phi \sin \phi + \sin \phi \cos \phi = 0, \hat{e}_\phi \cdot \hat{e}_z = 0$

$\hat{e}_z \cdot \hat{e}_\rho = 0$, Thus the cylindrical system is orthogonal.

(4a) Given $\vec{F} = \nabla(xy^3z^2)$. To Find $\text{div}(\vec{F})$ and $\text{curl}(\vec{F})$ at $(1, -1, 1)$

we have

$$\vec{F} = \frac{\partial}{\partial x}(xy^3z^2)\mathbf{i} + \frac{\partial}{\partial y}(xy^3z^2)\mathbf{j} + \frac{\partial}{\partial z}(xy^3z^2)\mathbf{k}$$

$$\vec{F} = y^3z^2\mathbf{i} + 3xy^2z^2\mathbf{j} + 2xy^3z\mathbf{k}$$

Now

$$\text{div}(\vec{F}) = \nabla \cdot \vec{F} = \left(\frac{\partial}{\partial x}\mathbf{i} + \frac{\partial}{\partial y}\mathbf{j} + \frac{\partial}{\partial z}\mathbf{k} \right) (y^3z^2\mathbf{i} + 3xy^2z^2\mathbf{j} + 2xy^3z\mathbf{k})$$

$$\nabla \cdot \vec{F} = 0 + 6xyz^2 + 2xy^3$$

$$\text{at } (1, -1, 1) \quad [\nabla \cdot \vec{F}]_{(1, -1, 1)} = 6 \times 1 \times (-1) \times 1 + 2 \times 1 \times (-1)^3$$

$$= -6 - 2 = -8$$

and

$$\text{curl}(\vec{F}) = \nabla \times \vec{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y^3z^2 & 3xy^2z^2 & 2xy^3z \end{vmatrix}$$

$$= \mathbf{i} [6xy^2z - 6xy^2z] - \mathbf{j} [2y^3z - 2y^3z] + \mathbf{k} [3y^2z^2 - 3y^2z^2]$$

$$= 0\mathbf{i} + 0\mathbf{j} + 0\mathbf{k} = \vec{0}$$

(4b) Given $\vec{F} = \frac{x\vec{i} + y\vec{j}}{x^2 + y^2} = \frac{x}{x^2 + y^2}\vec{i} + \frac{y}{x^2 + y^2}\vec{j}$

Now $\text{div } \vec{F} = \nabla \cdot \vec{F} = \frac{\partial}{\partial x} \frac{x}{x^2 + y^2} + \frac{\partial}{\partial y} \frac{y}{x^2 + y^2}$

$$= \frac{(x^2 + y^2) \cdot 1 - x(2x)}{(x^2 + y^2)^2} + \frac{(x^2 + y^2) \cdot 1 - y(2y)}{(x^2 + y^2)^2}$$

$$= \frac{x^2 + y^2 - 2x^2 + x^2 + y^2 - 2y^2}{(x^2 + y^2)^2} = 0$$

i.e. $\text{div } \vec{F} = \nabla \cdot \vec{F} = 0 \rightarrow$ Vector is solenoidal.

Now $\text{curl } \vec{F} = \nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{x}{x^2 + y^2} & \frac{y}{x^2 + y^2} & 0 \end{vmatrix}$

$$= \vec{i} [0 - 0] - \vec{j} [0 - 0] + \vec{k} \left[\frac{y(2x)}{(x^2 + y^2)^2} - \frac{x(2y)}{(x^2 + y^2)^2} \right]$$

$$= 0\vec{i} + 0\vec{j} + 0\vec{k} = \vec{0}$$

i.e. $\text{curl } \vec{F} = \nabla \times \vec{F} = \vec{0} \rightarrow$

So Given vector \vec{F} is solenoidal and irrotational both.

(4c) Given $\vec{F} = 2y\hat{i} - z\hat{j} + 3x\hat{k}$

$\Rightarrow \vec{F} = F_r \hat{e}_r + F_\theta \hat{e}_\theta + F_\phi \hat{e}_\phi$ — (1)

where F_r, F_θ, F_ϕ are to be determined.

$\therefore \vec{F} \cdot \hat{e}_r = F_r, \vec{F} \cdot \hat{e}_\theta = F_\theta, \vec{F} \cdot \hat{e}_\phi = F_\phi$

In terms of spherical polar coordinates, the given function. — (2)

$\vec{F} = 2(r \sin \theta \sin \phi)\hat{i} + (r \cos \theta)\hat{j} + 3(r \sin \theta \cos \phi)\hat{k}$ — (3)

Also we have, $\hat{e}_r = \frac{1}{h_1} \frac{\partial \vec{r}}{\partial r}; \hat{e}_\theta = \frac{1}{h_2} \frac{\partial \vec{r}}{\partial \theta};$

$\hat{e}_\phi = \frac{1}{h_3} \frac{\partial \vec{r}}{\partial \phi}$

where $\vec{r} = (r \sin \theta \cos \phi)\hat{i} + (r \sin \theta \sin \phi)\hat{j}$

and $h_1 = 1, h_2 = r, h_3 = r \sin \theta + r \cos \theta \hat{k}$

$$\hat{e}_r = \sin\theta \cos\phi \hat{i} + \sin\theta \sin\phi \hat{j} + \cos\theta \hat{k}$$

$$\hat{e}_\theta = \cos\theta \cos\phi \hat{i} + \cos\theta \sin\phi \hat{j} - \sin\theta \hat{k}$$

$$\hat{e}_\phi = -\sin\phi \hat{i} + \cos\phi \hat{j}$$

Thus we have from (2), the required

F_r, F_θ, F_ϕ is as follows.

$$F_r = 2r \sin^2\theta \sin\phi \cos\phi + r \cos\theta \sin\theta \sin\phi + 3r \sin\theta \cos\theta \cos\phi$$

$$F_\theta = 2r \sin\theta \cos\theta \sin\phi \cos\phi - r \cos^2\theta \sin\phi - 3r \sin^2\theta \cos\phi$$

$$F_\phi = -2r \sin\theta \sin^2\phi - r \cos\theta \cos\phi$$

Q5
a)Find the rank of the matrix $A = \begin{bmatrix} 2 & 1 & -1 & 3 \\ 1 & 2 & 4 & 3 \\ 3 & 6 & 12 & 9 \\ 3 & 3 & 3 & 6 \end{bmatrix}$.Solⁿ:

$$A = \begin{bmatrix} 2 & 1 & -1 & 3 \\ 1 & 2 & 4 & 3 \\ 3 & 6 & 12 & 9 \\ 3 & 3 & 3 & 6 \end{bmatrix}$$

$$R_3 \rightarrow \frac{1}{3} \times R_3, \quad R_4 \rightarrow \frac{1}{4} \times R_4, \quad R_1 \leftrightarrow R_2$$

~~$$\approx \begin{bmatrix} 2 & 1 & -1 & 3 \\ 1 & 2 & 4 & 3 \\ 3 & 6 & 12 & 9 \\ 3 & 3 & 3 & 6 \end{bmatrix}$$~~

$$\approx \begin{bmatrix} 1 & 2 & 4 & 3 \\ 2 & 1 & -1 & 3 \\ 1 & 2 & 4 & 3 \\ 1 & 1 & 1 & 3 \end{bmatrix}$$

$$R_2 \rightarrow R_2 - 2R_1, \quad R_3 \rightarrow R_3 - R_1, \quad R_4 \rightarrow R_4 - R_1$$

$$\approx \begin{bmatrix} 1 & 2 & 4 & 3 \\ 0 & -3 & -9 & -3 \\ 0 & 0 & 0 & 0 \\ 0 & -1 & -3 & -1 \end{bmatrix}$$

$$R_4 \rightarrow 3R_4 - R_2$$

$$\approx \begin{bmatrix} 1 & 2 & 4 & 3 \\ 0 & -3 & -9 & -3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$R_2 \rightarrow \frac{1}{3} \times R_2$$

$$A \approx \begin{bmatrix} 1 & 2 & 4 & 3 \\ 0 & 1 & 3 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Therefore, $\text{rank}(A) = 2$.

b) Using Gauss Jordan method, solve the system of equations

$$x + y + z = 9, \quad x - 2y + 3z = 8, \quad -2x + y - z = 3$$

Solⁿ

$$[A:b] = \begin{bmatrix} 1 & 1 & 1 & : & 9 \\ 1 & -2 & 3 & : & 8 \\ 2 & 1 & -1 & : & 3 \end{bmatrix}$$

$$R_2 \rightarrow R_2 - R_1, \quad R_3 \rightarrow R_3 - 2R_1$$

$$\approx \begin{bmatrix} 1 & 1 & 1 & : & 9 \\ 0 & -3 & 2 & : & -1 \\ 0 & -1 & -3 & : & -15 \end{bmatrix}$$

$$R_1 \rightarrow 3R_1 + R_2, \quad R_3 \rightarrow 3R_3 - R_2$$

$$\approx \begin{bmatrix} 3 & 0 & 5 & : & 26 \\ 0 & -3 & 2 & : & -1 \\ 0 & 0 & -11 & : & -44 \end{bmatrix}$$

$$R_3 \rightarrow \frac{-1}{11} \times R_3$$

$$12 \quad \left[\begin{array}{ccc|c} 3 & 0 & 5 & 26 \\ 0 & -3 & 2 & -1 \\ 0 & 0 & 1 & 4 \end{array} \right]$$

$$0 = 3 + 5 - 26 - 26 \leftarrow$$

$$0 = (3-5)1 - (3-5)4 \leftarrow$$

$$R_1 \rightarrow R_1 - 5R_3, \quad R_2 \rightarrow R_2 - 2R_3$$

$$13 \quad \left[\begin{array}{ccc|c} 3 & 0 & 0 & 6 \\ 0 & -3 & 0 & -9 \\ 0 & 0 & 1 & 4 \end{array} \right]$$

and A is under mod 11
 $3 = 3 \pmod{11}$
 $2 = 2 \pmod{11}$

$$\Rightarrow 3x = 6, \quad -3y = -9, \quad z = 4 \pmod{11}$$

Hence the solⁿ of the given system of eq^s is

$$x = 2, \quad y = 3, \quad z = 4$$

c) Diagonalize the matrix $\begin{bmatrix} -1 & 3 \\ -2 & 4 \end{bmatrix}$

solⁿ

$$\text{let } A = \begin{bmatrix} -1 & 3 \\ -2 & 4 \end{bmatrix}$$

The characteristic eqⁿ is

$$|A - \lambda I| = 0$$

$$\Rightarrow \begin{vmatrix} -1-\lambda & 3 \\ -2 & 4-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (-1-\lambda)(4-\lambda) + 6 = 0$$

$$\Rightarrow -4 + \lambda - 4\lambda + \lambda^2 + 6 = 0$$

$$\Rightarrow \lambda^2 - 3\lambda + 2 = 0$$

$$\Rightarrow \lambda^2 - 2\lambda - \lambda + 2 = 0$$

$$\Rightarrow \lambda(\lambda - 2) - 1(\lambda - 2) = 0$$

$$\Rightarrow (\lambda - 2)(\lambda - 1) = 0$$

$$\Rightarrow \lambda = 1, 2.$$

The eigen values of A are 1, 2

If $\lambda = 1,$

$$(A - \lambda I)X = 0$$

$$\Rightarrow \left(\begin{bmatrix} -1 & 3 \\ -2 & 4 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$$

$$\Rightarrow \left(\begin{bmatrix} -1 & 3 \\ -2 & 4 \end{bmatrix} - \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$$

$$\Rightarrow \begin{pmatrix} -2 & 3 \\ -2 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$$

$$R_2 \rightarrow R_2 - R_1$$

$$\Rightarrow \begin{pmatrix} -2 & 3 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$$

$$\Rightarrow -2x_1 + 3x_2 = 0$$

$$\Rightarrow 2x_1 = 3x_2$$

$$\Rightarrow x_1 = \frac{3}{2} x_2$$

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} \frac{3}{2} x_2 \\ x_2 \end{pmatrix} = x_2 \begin{pmatrix} 3/2 \\ 1 \end{pmatrix}$$

For $\lambda=1$, eigen vector is $\begin{pmatrix} 3/2 \\ 1 \end{pmatrix}$

For $\lambda=2$

$$(A - \lambda I) x = 0$$

$$\Rightarrow \left(\begin{pmatrix} -1 & 3 \\ -2 & 4 \end{pmatrix} - \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} \right) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$$

$$\Rightarrow \begin{pmatrix} -3 & 3 \\ -2 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$$

$$R_2 \rightarrow 3R_2 - 2R_1$$

$$\Rightarrow \begin{pmatrix} -3 & 3 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$$

$$-3x_1 + 3x_2 = 0$$

$$\Rightarrow x_1 = x_2$$

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_1 \end{pmatrix} = x_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

For $\lambda = 2$, eigen vector = $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$

The modal matrix is $P = \begin{pmatrix} 3/2 & 1 \\ 1 & 1 \end{pmatrix}$

$$|P| = \begin{vmatrix} 3/2 & 1 \\ 1 & 1 \end{vmatrix} = \left(\frac{3}{2} \times 1\right) - (1 \times 1) = \frac{3}{2} - 1 = \frac{1}{2}$$

$$P^{-1} = \frac{1}{|P|} \begin{pmatrix} 1 & -1 \\ -1 & 3/2 \end{pmatrix} = \frac{1}{1/2} \begin{pmatrix} 1 & -1 \\ -1 & 3/2 \end{pmatrix} = \begin{pmatrix} 2 & -2 \\ -2 & 3 \end{pmatrix}$$

$$P^{-1} = \frac{1}{2} \begin{pmatrix} 1 & -1 \\ -1 & 3/2 \end{pmatrix} = \begin{pmatrix} 2 & -2 \\ -2 & 3 \end{pmatrix}$$

$$D = P^{-1} A P = \begin{pmatrix} 2 & -2 \\ -2 & 3 \end{pmatrix} \begin{pmatrix} -1 & 3 \\ -2 & 4 \end{pmatrix} \begin{pmatrix} 3/2 & 1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}$$

The diagonal matrix is $\begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}$.

Q.6

a) Investigate the values of μ & λ such that the equations $x+y+z=6$, $x+2y+3z=10$, $x+2y+\lambda z=\mu$, may have
 (i) unique solⁿ, (ii) infinite solⁿ, (iii) no solⁿ.

Solⁿ

$$[A:b] = \begin{bmatrix} 1 & 1 & 1 & : & 6 \\ 1 & 2 & 3 & : & 10 \\ 1 & 2 & \lambda & : & \mu \end{bmatrix}$$

$$R_2 \rightarrow R_2 - R_1, \quad R_3 \rightarrow R_3 - R_1$$

$$\approx \begin{bmatrix} 1 & 1 & 1 & : & 6 \\ 0 & 1 & 2 & : & 4 \\ 0 & 1 & \lambda-1 & : & \mu-6 \end{bmatrix}$$

$$R_3 \rightarrow R_3 - R_2$$

$$\approx \begin{bmatrix} 1 & 1 & 1 & : & 6 \\ 0 & 1 & 2 & : & 4 \\ 0 & 0 & \lambda-3 & : & \mu-10 \end{bmatrix}$$

(i) unique solⁿ:- $\lambda \neq 3$.

(ii) infinite solⁿ:- $\lambda = 3, \mu = 10$.

(iii) no solⁿ:- $\lambda = 3, \mu \neq 10$.

b) Using Gauss elimination method, solve the system of equations: $x + 2y + z = 3$, $2x + 3y + 3z = 10$, $3x - y + 2z = 13$.

Solⁿ

$$[A : b] = \begin{bmatrix} 1 & 2 & 1 & : & 3 \\ 2 & 3 & 3 & : & 10 \\ 3 & -1 & 2 & : & 13 \end{bmatrix}$$

$$R_2 \rightarrow R_2 - 2R_1, \quad R_3 \rightarrow R_3 - 3R_1$$

$$\approx \begin{bmatrix} 1 & 2 & 1 & : & 3 \\ 0 & -1 & 1 & : & 4 \\ 0 & -7 & -1 & : & 4 \end{bmatrix}$$

$$R_3 \rightarrow \cancel{R_3 + 7R_1}, \quad R_3 - 7R_2$$

$$\approx \begin{bmatrix} 1 & 2 & 1 & : & 3 \\ 0 & -1 & 1 & : & 4 \\ 0 & 0 & -8 & : & -24 \end{bmatrix}$$

By backward substitution,

$$-8z = -24 \Rightarrow z = 3$$

$$-y + z = 4$$

$$\Rightarrow -y = 4 - 3 = 1$$

$$\Rightarrow y = -1$$

$$x + 2y + z = 3$$

$$x = 3 - 2(-1) - 3$$

$$\Rightarrow x = 2$$

Hence, the solⁿ is $x=2, y=-1, z=3$.

c) Find the eigen value & eigen vectors of the matrix

$$A = \begin{pmatrix} 1 & 1 & 3 \\ 1 & 5 & 1 \\ 3 & 1 & 1 \end{pmatrix}$$

$$0 = (x)(2A - A)$$

Solⁿ

The characteristic eqⁿ is,

$$|A - \lambda I| = 0$$

$$\Rightarrow \begin{vmatrix} 1-\lambda & 1 & 3 \\ 1 & 5-\lambda & 1 \\ 3 & 1 & 1-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (1-\lambda) [(5-\lambda)(1-\lambda)-1] - 1 [1(1-\lambda)-3] + 3 [1-3(5-\lambda)] = 0$$

$$\Rightarrow (1-\lambda) (5 - 5\lambda - \lambda + \lambda^2 - 1) - (1-\lambda-3) + 3(1-15+3\lambda) = 0$$

$$\Rightarrow (1-\lambda) (\lambda^2 - 6\lambda + 4) - (-\lambda - 2) + 3(3\lambda - 14) = 0$$

$$\Rightarrow \lambda^2 - 6\lambda + 4 - \lambda^3 + 6\lambda^2 - 4\lambda + \lambda + 2 + 9\lambda - 42 = 0$$

$$\Rightarrow -\lambda^3 + 7\lambda^2 - 36 = 0$$

$$\Rightarrow (\lambda-3) (\lambda^2 - 4\lambda - 12) = 0$$

Eigen values are $\lambda = 3, 6, -2$

For $\lambda = 3$, $(A - \lambda I)(x) = 0$

$$(A - \lambda I)(x) = 0 \quad \cdot \begin{pmatrix} 3 & 1 & 3 \\ 1 & 2 & 1 \\ 3 & 1 & -2 \end{pmatrix} = 0$$

$$\Rightarrow \begin{pmatrix} 1-3 & 1 & 3 \\ 1 & 5-3 & 1 \\ 3 & 1 & 1-3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0$$

$$\Rightarrow \begin{pmatrix} -2 & 1 & 3 \\ 1 & 2 & 1 \\ 3 & 1 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0$$

$$R_2 \rightarrow 2R_2 + R_1, R_3 \rightarrow 2R_3 + 3R_1$$

$$\Rightarrow \begin{pmatrix} -2 & 1 & 3 \\ 0 & 5 & 5 \\ 0 & 5 & 5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0$$

$$(3-3-1) - (1-3+3-3-3) = 0$$

$$\Rightarrow \begin{pmatrix} -2 & 1 & 3 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0$$

$$x_2 + x_3 = 0$$

$$\Rightarrow \boxed{x_2 = -x_3}$$

$$-2x_1 + 2x_3 + 3x_3 = 0$$

$$\Rightarrow -2x_1 + 2x_3 = 0 \Rightarrow \boxed{x_1 = x_3}$$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} x_3 \\ -x_3 \\ x_3 \end{pmatrix} = x_3 \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

for $\lambda = 3$, eigen vector is $\begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} = x$

For $\lambda = 6$:

$$\Rightarrow \begin{pmatrix} 1-6 & 1 & 3 \\ 1 & 5-6 & 1 \\ 3 & 1 & 1-6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0$$

$$\Rightarrow \begin{pmatrix} -5 & 1 & 3 \\ 1 & -1 & 1 \\ 3 & 1 & -5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0$$

$$R_2 \rightarrow 5R_2 + R_1, R_3 \rightarrow 5R_3 + 3R_1$$

$$\Rightarrow \begin{pmatrix} -5 & 1 & 3 \\ 0 & -4 & 8 \\ 0 & 8 & -16 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0$$

$$\Rightarrow \begin{pmatrix} -5 & 1 & 3 \\ 0 & -4 & 8 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0$$

$$-5x_1 + x_2 + 3x_3 = 0$$

$$-4x_2 + 8x_3 = 0$$

$$\boxed{x_2 = 2x_3}$$

$$-5x_1 + 2x_3 + 3x_3 = 0$$

$$\Rightarrow \boxed{x_1 = x_3}$$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} x_3 \\ 2x_3 \\ x_3 \end{pmatrix} = x_3 \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$$

For $\lambda = 6$, eigen vector =

$$\begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$$

For $\lambda = -2$,

$$\begin{pmatrix} 1+2 & 1 & 0 & 3 \\ 1 & 5+2 & 1 & \\ 3 & 18+1+2 & & \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0$$

$$\Rightarrow \begin{pmatrix} 3 & 1 & 3 \\ 1 & 7 & 1 \\ 3 & 1 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0$$

$$R_2 \rightarrow 3R_2 - R_1$$

$$R_3 \rightarrow R_3 - R_1$$

$$\Rightarrow \begin{pmatrix} 3 & 1 & 3 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$3x_1 + x_2 + 3x_3 = 0$$

$$(1, 1, 3)x_1 + 2x_2 = 0 \Rightarrow (1, 1, 3)x_1 + (0, 2, 0)x_2 = (0, 0, 0)$$

$$\Rightarrow \boxed{x_2 = 0}$$

$$3x_1 + 0 + 3x_3 = 0$$

$$\Rightarrow \boxed{x_1 = -x_3}$$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} -x_3 \\ 0 \\ x_3 \end{pmatrix} = x_3 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

Hence, the eigen values are $3, 6, -2$ corresponding eigen vectors are

$$\begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

$$\begin{bmatrix} 8 & 0 & 0 & 1 \\ 2 & 2 & -1 & 0 \\ 2 & 2 & -1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 8 & 0 & 0 & 1 \\ 2 & 2 & -1 & 0 \\ 2 & 2 & -1 & 0 \end{bmatrix}$$

Module - 4

Q-7

a) Determine whether the vectors $(8, 0, 5)$ is a linear combination of the vectors $(1, 2, 3)$, $(0, 1, 4)$, $(2, -1, 1)$.

Solⁿ

let α, β, γ be any scalars such that

$$(8, 0, 5) = \alpha(1, 2, 3) + \beta(0, 1, 4) + \gamma(2, -1, 1)$$

$$0 = \alpha\beta$$

$$\alpha + 0 \cdot \beta + 2\gamma = 8$$

$$2\alpha + \beta - \gamma = 0$$

$$3\alpha + 4\beta + \gamma = 5$$

$$0 = \alpha\beta + 0 + \gamma$$

$$\alpha\beta = -\gamma$$

$$\begin{bmatrix} 1 & 0 & 2 & : & 8 \\ 2 & 1 & -1 & : & 0 \\ 3 & 4 & 1 & : & 5 \end{bmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \xrightarrow{R_2 - 2R_1} \begin{pmatrix} \alpha\beta \\ 0 \\ \alpha\beta \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ \alpha\beta \end{pmatrix}$$

$R_2 \rightarrow R_2 - 2R_1$
 $R_3 \rightarrow R_3 - 3R_1$

no scalar multiple with zero
 no scalar multiple with zero

$$\approx \begin{bmatrix} 1 & 0 & 2 & : & 8 \\ 0 & 1 & -5 & : & -16 \\ 0 & 4 & -5 & : & -19 \end{bmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$R_3 \rightarrow R_3 - 4R_2$$

$$\approx \begin{bmatrix} 1 & 0 & 2 & : & 8 \\ 0 & 1 & -5 & : & -16 \\ 0 & 0 & 15 & : & 45 \end{bmatrix}$$

By backward substitution,

$$15r = 45$$

$$\Rightarrow \boxed{r = 3}$$

$$\beta - 5r = -16$$

$$\beta - 5(3) = -16$$

$$\boxed{\beta = -1}$$

$$\alpha + 0\beta + 2r = 8$$

$$\Rightarrow \alpha = 8 - 2(3)$$

$$\Rightarrow \boxed{\alpha = 2}$$

Hence, the given vectors $(1, 2, 3), (0, 1, 4), (2, -1, 1)$ is a linear combination of $(8, 0, 5)$.

$$(8, 0, 5) = 2(1, 2, 3) - 1(0, 1, 4) + 3(2, -1, 1).$$

b) Find the basis & dimension of the subspace spanned by the vectors $(2, 4, 2), (1, -1, 0), (1, 2, 1), (0, 3, 1)$ in $V_3(\mathbb{R})$.

$$\begin{bmatrix} 2 & 4 & 2 \\ 1 & -1 & 0 \\ 1 & 2 & 1 \end{bmatrix} = A$$

$$\begin{bmatrix} 2 & 4 & 2 \\ 2 & 2 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} =$$

$$\begin{bmatrix} 2 & 4 & 2 \\ 2 & 2 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} =$$

Solⁿ

$$A = \begin{bmatrix} 2 & 4 & 2 \\ 1 & -1 & 0 \\ 1 & 2 & 1 \\ 0 & 3 & 1 \end{bmatrix}$$

$$R_2 \rightarrow 2R_2 - R_1, \quad R_3 \rightarrow 3R_3 - R_1$$

$$\Rightarrow \begin{bmatrix} 2 & 4 & 2 \\ 0 & -6 & -2 \\ 0 & 0 & 0 \\ 0 & 3 & 1 \end{bmatrix}$$

$$R_4 \rightarrow 2R_4 + R_2$$

$$\Rightarrow \begin{bmatrix} 2 & 4 & 2 \\ 0 & -6 & -2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$8 = r_1 s + 4r_2 + 0 + \lambda$$

$$(8) 8 - 8 = \lambda \Rightarrow$$

$$\boxed{8 = \lambda} \Rightarrow$$

Therefore the basis for the subspace of $V_3(\mathbb{R})$ is

$$\left\{ (2, 4, 2), (0, -6, -2) \right\} \cup \{ (0, 0, 0) \} \Rightarrow \left\{ (2, 4, 2), (1, -1, 0) \right\}$$

c) Find the basis & dimension of the row space, column space & null space of the matrix

$$\begin{bmatrix} 1 & -1 & 1 & 3 & 2 \\ 2 & -1 & 1 & 5 & 1 \\ 0 & 1 & -1 & -1 & -3 \end{bmatrix}$$

Solⁿ

Let $A = \begin{bmatrix} 1 & -1 & 1 & 3 & 2 \\ 2 & -1 & 1 & 5 & 1 \\ 0 & 0 & -1 & -1 & -3 \end{bmatrix}$

$$\begin{bmatrix} 1 & -1 & 1 & 3 & 2 \\ 0 & 1 & -1 & -1 & -3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$R_2 \rightarrow R_2 - 2R_1$

$$\Rightarrow \begin{bmatrix} 1 & -1 & 1 & 3 & 2 \\ 0 & 1 & -1 & -1 & -3 \\ 0 & 0 & -1 & -1 & -3 \end{bmatrix}$$

$R_3 \rightarrow R_3 - R_2$

$$\Rightarrow \begin{bmatrix} 1 & -1 & 1 & 3 & 2 \\ 0 & 1 & -1 & -1 & -3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Basis of the row space is $\{(1, -1, 1, 3, 2), (0, 1, -1, -1, -3)\}$

$\{(1, -1, 1, 3, 2), (2, -1, 1, 5, 1)\}$

dim of the row space is 2.

Basis of the column space is $\left\{ \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix} \right\}$

dim of the column space is 2.

For null space :-

$$\begin{bmatrix} 1 & -1 & 1 & 3 & 2 \\ 0 & 1 & -1 & -1 & -3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} = 0$$



$$x_1 - x_2 + x_3 + 3x_4 + 2x_5 = 0$$

$$x_2 - x_3 - x_4 - 3x_5 = 0$$

$$x_2 = x_3 + x_4 + 3x_5$$

$$x_1 = x_2 - x_3 - 3x_4 - 2x_5$$

$$= x_3 + x_4 + 3x_5 - x_3 - 3x_4 - 2x_5$$

$$x_1 = -2x_4 + x_5$$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} = \begin{pmatrix} -2x_4 + x_5 \\ x_3 + x_4 + 3x_5 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} = \begin{pmatrix} 0 \\ x_3 \\ x_3 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} -2x_4 \\ x_4 \\ 0 \\ x_4 \\ 0 \end{pmatrix} + \begin{pmatrix} x_5 \\ 3x_5 \\ 0 \\ 0 \\ x_5 \end{pmatrix}$$

$$= x_3 \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} -2 \\ 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} + x_5 \begin{pmatrix} 1 \\ 3 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

Hence the basis of null space is

$$\left\{ \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -2 \\ 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 3 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\}$$

Dim of the null space = 3

Q. 8

a) Find the coordinates of the vector $v = (0, 1, 3)$ w.r.t the basis $B = \{(1, 1, 0), (0, 1, 1), (1, 0, 1)\}$.

Sol: Let (α, β, γ) be the coordinates of the vector v w.r.t B . $\Rightarrow 0 = \alpha(1, 1, 0) + \beta(0, 1, 1) + \gamma(1, 0, 1)$ (i)

$$(0, 1, 3) = \alpha(1, 1, 0) + \beta(0, 1, 1) + \gamma(0, 0, 1)$$

$$\alpha + \gamma = 0 \Rightarrow \alpha = -\gamma$$

$$\alpha + \beta = 1 \Rightarrow -\gamma + \beta = 1$$

$$\beta + \gamma = 3 \Rightarrow \gamma + \beta = 3$$

$$2\beta = 4 \Rightarrow \beta = 2$$

$$\gamma = 3 - \beta$$

$$\gamma = 3 - 2$$

$$\boxed{\gamma = 1} \Rightarrow \boxed{\alpha = -1}$$

Hence, the coordinates are $(-1, 2, 1)'$.

b) Define inner product space. Given $u = (1, 2, 4)$, $v = (2, -3, 5)$, $w = (4, 2, -3)$ in \mathbb{R}^3 . Find

- (i) $\langle u, u \rangle$, (ii) $\langle v, w \rangle$, (iii) $\langle u, w \rangle$, (iv) $\|u\|$ and $\|v\|$

Solⁿ Defⁿ An inner product space is a vector space V over \mathbb{R} ,

$\langle \cdot, \cdot \rangle: V \times V \rightarrow \mathbb{R}$, satisfying the following

- properties:
- (i) $\langle x, x \rangle \geq 0$ & $\langle x, x \rangle = 0 \Leftrightarrow x = 0$.

(ii) $\langle \alpha x + \beta y | z \rangle = \alpha \langle x, z \rangle + \beta \langle y, z \rangle$ (property of dot product)

Ex (iii) $\langle x, y \rangle = \langle y, x \rangle$. $\{0 = x + y + z - x \mid (x, y, z)\} = w$

~~(i) $\langle u, u \rangle = \langle (2, -3, 5) | (2, -3, 5) \rangle$~~ (property of dot product)

(i) $\langle u, u \rangle = 2 \times 2 + 2 \times (-3) + 4 \times 5 = 2 - 6 + 20 = 16$

(ii) $\langle u, w \rangle = 2 \times 4 + (-3) \times 2 + 5 \times (-3) = 8 - 6 - 15 = -13$

(iii) $\langle u, w \rangle = 4 + 4 - 12 = -4$

(iv) $\|u\|^2 = \langle u, u \rangle = 1 + 4 + 16 = 21 \neq 0$ (i)

$\|u\| = \sqrt{21}$ $w \in \beta, x \parallel, w \in \beta + x$ (ii)

(v) $\|u\|^2 = \langle u, u \rangle = 4 + 9 + 25 = 38$

$\|u\| = \sqrt{38}$. $\{0 = x + y + z - x \mid (x, y, z)\} = w$

Answer part (i)
 $0 = (0) + (0) - 0$

$w \in (0, 0, 0) \Leftarrow$

$4 \in \beta, x$ & $w \in (x, y, z), (x, y, z)$ del (ii)

~~$+ (x, y, z) \times$~~

Q) What is a subspace? Prove that the subset $W = \{(x, y, z) \mid x - 3y + 4z = 0\}$ of the vector space \mathbb{R}^3 is a subspace.

Soln
Defn - Let $V(F)$ be a vector space over the field F .

A subset W of $V(F)$ is said to be a subspace of $V(F)$ if it is closed under vector addition & scalar multiplication,

i.e.,
 (i) $0 \in W$

(ii) $x + y \in W, \forall x, y \in W$

(iii) $\alpha x \in W, \forall x \in W, \alpha \in F$

$W = \{(x, y, z) \mid x - 3y + 4z = 0\}$

(i) Zero element:
 $0 - 3(0) + 4(0) = 0$

$\Rightarrow (0, 0, 0) \in W$

(ii) Let $(x_1, y_1, z_1), (x_2, y_2, z_2) \in W$ & $\alpha, \beta \in F$
 $\alpha(x_1, y_1, z_1) +$

$$(x_1, y_1, z_1) \in W \Rightarrow x_1 - 3y_1 + 4z_1 = 0$$

$$\Rightarrow \alpha(x_1 - 3y_1 + 4z_1) = \alpha \cdot 0$$

$$\Rightarrow \alpha x_1 - 3\alpha y_1 + 4\alpha z_1 = 0 \quad \text{--- (1)}$$

$$(x_2, y_2, z_2) \in W \Rightarrow x_2 - 3y_2 + 4z_2 = 0$$

$$\Rightarrow \beta(x_2 - 3y_2 + 4z_2) = 0$$

$$\Rightarrow \beta x_2 - 3\beta y_2 + 4\beta z_2 = 0 \quad \text{--- (2)}$$

From (1) & (2), we have

$$(\alpha x_1 - 3\alpha y_1 + 4\alpha z_1) + (\beta x_2 - 3\beta y_2 + 4\beta z_2) = 0$$

$$\Rightarrow (\alpha x_1 + \beta x_2) - 3(\alpha y_1 + \beta y_2) + 4(\alpha z_1 + \beta z_2) = 0$$

$$\Rightarrow (\alpha x_1 + \beta x_2, \alpha y_1 + \beta y_2, \alpha z_1 + \beta z_2) \in W$$

$$\Rightarrow \alpha(x_1, y_1, z_1) + \beta(x_2, y_2, z_2) \in W.$$

$$\Rightarrow W \text{ is a subspace of } \mathbb{R}^3.$$

Module-5

(1)

9 a) S-T $T(x, y) = (x+y, x-y, y)$ is a L.T.

Let $a = (x_1, y_1)$ & $b = (x_2, y_2) \in V_2(\mathbb{R}), \mathbb{R}^2$

T.P (1) $T(a+b) = T(a) + T(b)$

(i) $T(ka) = k \cdot T(a)$

(i) $a+b = (x_1+x_2, y_1+y_2)$

$T(a+b) = (x_1+x_2+y_1+y_2, x_1+x_2-y_1-y_2, y_1+y_2)$

(1)

$T(a) + T(b) = (x_1+y_1, x_1-y_1, y_1) + (x_2+y_2, x_2-y_2, y_2)$

$T(a) + T(b) = (x_1+y_1+x_2+y_2, x_1+x_2-y_1-y_2, y_1+y_2)$

from (1) & (2) $T(a+b) = T(a) + T(b)$ (2)

(ii) $T(ka) = T(kx_1, ky_1) = (kx_1+ky_1, kx_1-ky_1, ky_1)$

$= k(x_1+y_1, x_1-y_1, y_1)$

$= k \cdot T(a)$

Hence it is a L.T.

9 (b) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ $T(x, y) = (2x + 4y, x + 2y)$

$e_1 = (1, 0), e_2 = (0, 1)$

$T(e_1) = T(1, 0) = (2, 1)$

$T(e_2) = T(0, 1) = (4, 2)$

\therefore Matrix T is $A = \begin{pmatrix} 2 & 4 \\ 1 & 2 \end{pmatrix}$

$\det(A) = \begin{vmatrix} 2 & 4 \\ 1 & 2 \end{vmatrix} = 4 - 4 = 0$

$\Rightarrow T$ is singular.

To find kernel (T)

(a) set of vectors (x, y) such that $T(x, y) = (0, 0)$

$\begin{pmatrix} 2 & 4 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$\begin{cases} 2x + 4y = 0 \\ x + 2y = 0 \end{cases} \Rightarrow x = -2y$
Take y as arbitrary

$\Rightarrow x = -2k$

$\therefore \text{ker } T = \left\{ (-2k, k) / k \in \mathbb{R} \right\}$

span $(-2, 1)$.

9c) Verify Rank nullity $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$

(3)

$$T(x, y, z) = (x+2y, y-z, x+2z)$$

Soln

$$T(e_1) = T(1, 0, 0) = (1, 0, 1)$$

$$T(e_2) = T(0, 1, 0) = (2, 1, 0)$$

$$T(e_3) = T(0, 0, 1) = (0, -1, 2)$$

$$A = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 2 \end{pmatrix}$$

To Find Rank :

$$R_3 \rightarrow R_3 - R_1 \quad A \sim \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & -1 \\ 0 & -2 & 2 \end{pmatrix}$$

$$R_3 \rightarrow R_3 + 2R_2 \Rightarrow A \sim \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{pmatrix}$$

\therefore Rank is 2.

To find nullity

$$x + 2y = 0$$

$$y - z = 0$$

Take $z = k$ arbitrary $\Rightarrow y = k$

\Rightarrow

$$\& x = -2k.$$

Kernel is spanned by $(-2, 1, 1)$

So dimension of kernel, nullity is 1.

$$\text{rank}(T) + \text{nullity}(T) = 2 + 1 = 3$$

$$\& \dim(\mathbb{R}^3) = 3$$

Hence Rank nullity thm

$$\text{Rank}(T) + \text{nullity of}(T) = \dim(V) \text{ is}$$

verified

— X —

$$(10) \text{ a) } T: \mathbb{R}^3 \rightarrow \mathbb{R}^4 \quad T(x, y, z) = (x+y+z, 2x+2z, 2y-2, 6y)$$

$$T(e_1) = T(1, 0, 0) = (1, 2, 0, 0)$$

$$T(e_2) = T(0, 1, 0) = (1, 0, 2, 6)$$

$$T(e_3) = T(0, 0, 1) = (1, 1, -1, 0)$$

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 0 & 1 \\ 0 & 2 & -1 \\ 0 & 6 & 0 \end{bmatrix}$$

is the required matrix

w) b) $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$

$T(x, y, z) = (x+z, x-z, y)$

S. T T is invertible & find T^{-1}

$T(e_1) = T(1, 0, 0) = (1, 1, 0)$

$T(e_2) = T(0, 1, 0) = (0, 0, 1)$

$T(e_3) = T(0, 0, 1) = (1, -1, 0)$

$A = \begin{pmatrix} 1 & 0 & 1 \\ 1 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}$

T.P Invertible. $\det(A) = 1(1) + 0 + 1(1) = 2 \neq 0$

$\therefore T$ is invertible

To find T^{-1} , $T(x, y, z) = (a, b, c)$

$x+z = a$

$x-z = b$

$y = c$

$x+z = a$

$x-z = b$

$2x = a+b \Rightarrow x = \frac{a+b}{2}$

$z = x - b$

$z = \frac{a+b}{2} - b$

$z = \frac{a-b}{2}$

$T^{-1}(a, b, c) = \left(\frac{a+b}{2}, c, \frac{a-b}{2} \right)$ or $T^{-1}(x, y, z) = \left(\frac{x+y}{2}, z, \frac{x-y}{2} \right)$

(10) c) verify Rank nullity

T: R^3 -> R^2 T(x, y, z) = (x+y, z)

T(e1) = T(1, 0, 0) = (1, 0)

T(e2) = T(0, 1, 0) = (1, 0)

T(e3) = T(0, 0, 1) = (0, 1)

A = [[1, 1, 0], [0, 0, 1]]

Rank(A) = 2

To find nullity.

x+y=0 => x=-y, z=0

let y=k be arbitrary.

=> (x, y, z) = (-k, k, 0) = k(-1, 1, 0)

one basis vector => nullity = 1

rank + nullity = 2 + 1 = dim(R^3) = 3

Hence Rank nullity thm is verified.