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Internal Assessment Test 2 – Sept. 2018

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Sub:	IOT &WSN					Sub Code:	15EC752	Branch:	TCE	,	
Date:	17-10-18	Duration:	90 min's	Max Marks:	50	Sem / Sec:	/			OBE	
			Answer all	FIVE Question	<u>1S</u>						
1 (a) Explain in detail the features of Nimbits.  OR							[	10]	CO2	L2	
	(b) Explain in brief about the energy consumption in transceiver (transmitter and receiver) section in sensor node.						[:	10]	CO4	L2	
2 (a) What is Wireless sensor network. Explain the challenges for WSN.  OR						[:	10]	CO4	L2		
` ,	Differentiate be mobility.	tween single	e hop and m	ultiple hop netv	works	and explain	the types of t	node [	10]	CO4	L2
	Write a short no paradigms.	ote on embed	lded operatir	ng system and e	explai	n about diffe	erent programi	ming [	10]	CO4	L2
(b)	Write a explana	tory note on	TinyOS and	I nesC.				[:	10]	CO4	L2

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	Differentiate bei mobility.	tween single	hop and m	ultiple hop netv	works	and explain	the types of	node [	10]	CO4	L2
3 (a) Write a short note on embedded operating system and explain about different programming paradigms.  OR						ming [	10]	CO4	L2		
(b) '	Write a explanat		TinyOS and	l nesC.				[	10]	CO4	L2

4 (a)	Explain the single node architecture with necessary hardware components  OR	[10]	CO4	L2
(b)	Write a short note on design principles of WSN	[10]	CO4	L2
5 (a)	Write a short note on Optimization goals and figure of merit.	[6]	CO4	L2
(b)	Write a short note on network gateway  OR	[4]	CO4	L2
(c)	Write a short note on energy scavenging	[4]	CO4	L2
	Write short node on operational state of sensor node with different power consumption.	[6]	CO4	L2

4 (a)	Explain the single node architecture with necessary hardware components . OR	[10]	CO4	L2
(b)	Write a short note on design principles of WSN	[10]	CO4	L2
5 (a)	Write a short note on Optimization goals and figure of merit.	[6]	CO4	L2
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(c)	Write a short note on energy scavenging	[4]	CO4	L2
(d)	Write short node on operational state of sensor node with different power consumption.	[6]	CO4	L2

such controller12345.

## 6.4.2 IoT Cloud-based Data Collection, Storage and Computing Services Using Nimbits

Nimbits enables IoT on an open source distributed cloud. Nimbits cloud PaaS deploy an instance of Nimbits Server at the device nodes. Nimbits functions as an M2M system data store, data collector and logger with access to historical data. Nimbits architectures a cloud-based Google App Engine. Nimbits server is a class hierarchy com.nimbits.server system.ServerInfo of java.lang.Object. Nimbits PaaS services offer the following features.

- Edge computing locally on embedded systems, built up of local applications. It must the rules and pushes important data up to the cloud running when connected over Internet and an instance of Nimbits Server hosts at the device nodes which is then enabled.
- It supports multiple programming languages, including Arduino, new Arduiro library, push functions from Arduino cloud, JavaScript, HTML or the Nimbits in Java library.
- Nimbits server functions as a backend platform. Nimbits data point can relay data between the software systems; or hardware devices such as Arduino, using the cloud as a backend.
- An open source Java library called nimbits io enables easy development of JAVA, web
  and Android solutions (Nimbits data, alerts, messages on mobile).
- It provides a rule engine for connecting sensors, persons and software to the cloud and one another. Rules can be for calculations, statistics, email alerts, xmpp message (Section 3.3.3), push notifications and more.

- It provides a data logging service and access, and stores the historical data points and data objects.
- Storage in any format that can be serialised into a string, such as JSON or XML.
- It filters the noise and important changes sent to another larger central instance.
- It processes a specific type of data and can store it.
- · Time- or geo-stamping of the data.
- Nimbits clients provide over Internet, data collection in real time, charts, chart and graphical plots of collected data and data entry.
- Data visualisation for data of connected sensors to IoT devices.
- Supports the alerts subscription, generation and sending in real time over the Internet.
- It creates streams of data objects and stores them in a data point series.
- Data accessibility and monitoring from anywhere, and is used to shape the behaviour of connected devices and software.
- It supports the mBed<sup>TM</sup>, Arduino, Raspberry Pi based and other hardware platform based IoT devices.
- . Web service APIs are easy to implement on device hardware acting as clients to Nimbits web services, and connect to the web service and send data.
- It deplays software on Google App Engine, any J2EE server on Amazon EC2 or on a Raspberry Pi.

Figure 6.3 shows connected devices, sensor nodes, network data points. Nimbits server, aployment at the device network nodes, and networked with the Nimbits Server (PaaS, Sand laaS services) at cloud for applications and services.

Architecture shown in Figure 6.3 shows a NimbitsServerL which deploys at each device ode and is an instance of the NimbitsSeverS at the cloud. Each NimbitsServerL of the byte node generates the calculation objects for device nodes.

Each node also hosts an XMPPServerL, an instance of the XMPPSeverC at the cloud.

XMPPServerL deploys at each device node and generates the data feed channels for the MPP messages and alerts. Each XMPPServerI, sends feeds to XMPPSeverC.

## Data Points

data point means a collected value of a sensor in a group of sensors. Data points organise data in a number of ways. For example, points can have child points (child points an subpoints; for example, if light level is a data point then light on or off is a child

and light level above or below the threshold can be another child point.)

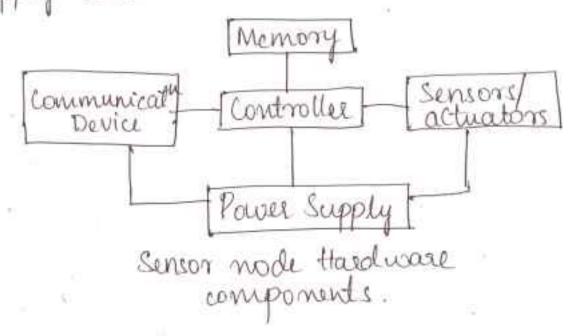
as can be in the folders. The folders can go as deep as like in a tree (Tree means the having several subfolders, a subfolder having several subfolders, till the leaf

type of document can upload and organise them with the points. Files can be publicly or with the connections.

semption data feed is a special point for each user that logs system messages, dens from other points which are subscribed by a service and more.

Q2	(a) notwork? Explain the	
1)	what is wireless series.	cmuists
->	wireless Senson networks are networks that of sensons which are distributed in an omanner.	ad hoc
	Mallowan for WSN's:	
	· charactoristic requirements	8
	· Required mechanisms	
	Characteristic requirements:	
$\rightarrow$	Trype of service	
$\rightarrow$	Quality of server	
<b>-</b> ->	Fault tolerance	
$\rightarrow$	Léfetime	
->	Scalability	
$\rightarrow$	wide range of densities	
→ →	Maintainabilly	
->	Programmability	

- · Required Mechanisms.
- -> Multihop voiveless communication
- > Energy-efficient operation
- > Auto configuration
- -> Collaboration and in-notwork processing
- → Data centric
- -> Locality
- > Exploit trade-offs.
- 2) Explain the single node architecture with necessary hardware components.
- → A basic sensor node contains 5 main components such as controller, memory, sensors and actuators, communication devices and paver supply unit.



- The controller is the core of a wireless sensor node, it process all the relevant data, capable of executing arbitrary code.

  It collects data from someon processes this data
  - It collects data from sensors, processes this data decides when and where to send it, similarly receives data from other sensor nodes and decides on the actuator's behaviour.
- Memory: Memory is required to stone programs and intermediate data; usually, different types of memory are used for programs and data. In wan there is a need for RAM to stone intermediate censor readings, packeds from other modes & some RAM is fast, but loses content if power supply is indesuppted. Hence we use RAM or EEPROM
- They are the actual inderface to the physical world, They are the actual inderface to the physical world, they observe or control physical parameters of the environment.

  Sensors can be categorized as active, passive sensor omni directional, and passive narrow beam sensor.

  Actuators are just about as diverse as sensors, yet for It is used for converting electrical signals into physical phenomenon.

iv) Communication Device:
To turn modus into a n/w, a device is required for sending & receiving info over a wireless channel. The communication device is used to each ange data blue individual modes. Rf based communication is by fax the most relevant one as it fits all requirements of most were applications for communication, both transmitter & receiver are required in a sensor node to convert a bit stream from a controller & convert them to & from radio waves. For 2 tasks a combined device called

Radio fronthad Law noise amplifier & baseband processing

Antenna Indespace

Rower amplifier & Frequency

Frequency

Conversion

No tied power supply is avoidable, hence some form of batteries are necessary to provide energy.

There are success essentially 2 features:

) Storing energy 2) Energy Scavenging.

Q5(c) Write a short note on energy scavenging. 4)

Depending on application, high capacity batteries that lost for long times with nigligible selfdischarge rate and that can efficiently provide small amounts of werent for this energy scavenging is used, which is the process of recharging battery with gathered from the environment for example,

Temperature gradient difference in temperature Phobo voltatics: solar cells

converted to districal energy

Vibrations muchanical energy

How of air/liquid: Windmills & turbines.

Operational state of sensor with diff power consumpth

Micro controller energy consumpts: For a controller, typical states are active, idle & sleep. The energy saving in micro controller is denoted given by

Esaved = (tevent - ta) Pacline ( Gown Clark + Peley)/2 + (tevent -

t, - Tdown) Psleep) The energy oberhead is denoted by Eoverhead Tup (Padine + Psleep)/2

tx Intel Strong ARM:

·) In normal mode, the power consumption is up to

In the despet steep mode (seem) today consumer county.

In take skeep mode, power consumpth is up to 50 mill.

At med At maga:
In almed At maga, power consumpth varies b/w or mill g.

In almed At maga, power consumpth varies b/w or mill g.

In power down modes.

5) Enugy consumption in transcelver

A radio transcriva has essentially a tacks as transmitty & receiving data between a pair of modes. To maintain low energy consumption, he transcrives should be turned off most of the time and only be activated when necessary.

The energy consumed by a transmitter is due to RF signal generation of due to electronic components. necessary for frequency synthesis, feonversion, filters and so on.

-> Similar to the transmitter, the receiver can be either turned off or turned on.

6) Write a short note or embedded OS. georplain

An operating system (OS) is system software that manages computer hardware & software resources, is acts as an intermedicity between programs & computer hardware. An embedded system is some combinate on of hardware or software, that is specifically designed for a particular function.

→ tombedded operating system (tos) are duigned to be used in embedded computer systems. Eosare able to operate with a limited no of resources. They are compact ejefficient.

1) Note on Tiny Os

This an opensouse, flixible & application specific Us for wineless einsor now. WSN consists of a large no of tiny & low-power nodes, each of which executes simultaneous & reactive programs that must work with aneous & reactive programs that must work with strict memory & power consumpt. TinyOs meets these challenges.

## features:

· Event based concurring model.

component-based architecture.

Tinyos's component library includes network proto cold, distributed services, sensor drivers, de

Timyos's event-driven execution model.

8) Difference b/w single hop & multiple hop network & explain the types of node mobility.

> In wineless sensor, n/w mobility can appear in 3 maintrames:

· Node Mobility - The wireless sensor makes themselves can be mobile. The meaning of such mobility is

Sink mobility. The information sinks can be mobile wohlle this can be a special case of mode mobility the important aspect is the mobility of an info sink that is not part of the sensor n/w.

ond in particular tracking applications the caue the events or the objects to be tracked can be mobile.

Single vs multi thop

From the basics of radio communicates the inhuentle power limitation of radio comm follows a limitate on the feasible distance blue a sender & receiver. On the feasible distance blue a sender & receiver. Because of this limited distance, the simple, direct because of this limited distance, the simple of distance communicates blue source & sinck is not always possible communicates blue source & sinck is not always possible to cover a specifically in EUSNs, which are intended to cover a specifically in EUSNs, which are intended to cover a lost of ground or that operate in difficult radio environments with strong attenuation.

To overcome such limited distances, an obvious to overcome such limited distances, an obvious to overcome such limited distances, an obvious

To overcome such limited aistances, an data packets way out is to use selay stath, with data packets having multi hops from the source to the stink. This concept of multihop n/10 is particularly. This concept of multihop n/10 is particularly all ractive for wells at the sensor males themselves all ractive for wells at the sensor males themselves can act as such relay nodes, for egoing the can act as such relay nodes, for egoing the need for additional equipment.

10) Short note on design principles of wish. Short note on optimizatingouls & figure of merit. (\$5(a) for all WSN scenanions & application types have to face the challenges euch as: How to optimize a network, compare soluting? How to decide the approach How to twon inaccurate optimizate goals into oncasurable figures General answers for the above questions: \* Scalabilility quality of service \* Robustness Energy officiency Quality of service: WSNs differ from other conventional 11 now in the type of service they offer. These now essentially only move to its from one place to another Generic possibilities are: Event detection/ reporting probability Event classification essor. Event detection delay Missing reports Approx accuracy Tracking accuracy.

voireless sensor mos should also ealibit an appropriate iii Robustness: nobustness. They should not fail just because a limited no of nodes run out of energy or bez their environment changes. If possible, these failures have to be compensated by finding others routes.

Q4(b) 10) Design principles of WSN:

Distributed organizat.

Distributed means every part of organizat" is acting separately as an autonomous unit; there is no central controller who interference ->

If WSN used and valized at architecture, then if the central mode fails, then the entire you

will collapse.

Hence a distributed control is to increase reliability

It is called in-network processing as processing is done inside the sensor network close to the source. It is divided into 2 categories:

Aggregath based techniques:

Let modes periodically measure data, but it is not trata with large necessary to send all the collected data. Average of charge in average value, or a huge difference can be suit.

In average value, or a huge difference can be suit.

Hence aggregath condenses gremones redundant info by reducing the most of birts.

\* Approx techniques: If focuses on reducing amount of data packets to be transmitted in-network when the accusacy of data collection is important. It defines accusacy of data collection is important it defines what is the armage frax absolute or relative essention with the actual function.

Distrubuted source cooling & collaborative signal

processing:
Where networking is distributed, each mode has
where networking is distributed, each mode has
separate processors working independently CSP
separate

Geographic Adaptive fidelity (GAF): It is one of the Geographic Adaptive fidelity (GAF): It is one of the It was the modes location info to transfer the data. Was the modes location info to transfer the data. It reduces the use of energy consumption of modes and increase the new lifetime.

· Data centric networking.

It defines that data is the center of attention, not the identity of modes, called the data centric approval.

· avalay now & distributed hash tables (DHT):

If the data is retrieved from an unknown source, like in peer-to-peer now then use DHT. The during data is identified by a key (hash) and then DHT provides one source for the data associated with

Publish/subscribe: Modes can publish data, can subscribe to any particular kind of data. Once data of a certain type has been published, it is delivered

Databases: USN can be considered as dynamic

data base (SQL). The sensors are considered as virtual tables to which some relational operators can be applied.

Exploit location gorianinjo: for some applications tocation info of sensor coucial info.

Exploit activity patterns: Once an event has tappened, it can be detected by a no. of sensors, breaking into frenzy activity called as event shower effect.

taploit heaterogeneity.

- (35(b) write a short note on n/w gateway.
- The new housto be able to interact with other info devices for ex to read the temperature sensors in -> one's home while travelling & accessing the internet via a wireless
- Gotteway allows the WSN to exchange the data with other devices like mobile phones.
- Gate way node bridges a gap b/w wsN and other -> communication devices.
- Gateway is equipped with a radio transceiver or some standard coincless communicate technique like IEEE 802.11.
- Challenges in WSN to interpret comm.
  Let sensor mode 'ALICE' was deliver an alasm msg to an interest host.
- But some issues occus like: ->
  - · Chase best gateway. I which it should be sent. · Finding host 17 address to which it should be sent.
- Let interest based entry try to access the services of If requesting terminal can directly communicate
- like mobile then no particular treatment is neccessary, but if this is not the case tomplexity IMC 2002 67.



- 3a) Embedide Operating Systems and different programming paradigms.
- An operating system is a syntem which industraces both the hardware and software components of a computer system.
- They act as a backbone, making it easier for the user to access the hardware and software components.
- -> An Embedded Operating system (EDS) is the operating system that interface the hardware components of the embedded system with its software components.
- one of the most common tos is Tiny Os.

  It satisfies all the requirements an enbedded operating system needs for the its functioning.
- -> EOS has different programining pasadigme. They are:



Considerent programming paradigm:
In concurrent programming, multiple
functions / programs are carried out
functions / programs are carried out
simultaneously, northout lower the speed or
affecting the quality concurrent programming
affecting the function as multiple
reduces the time consumption as multiple
programs are running at the same time

Parallel concurrency is extremely useful as it Parallel concurrency is extremely useful as it speeds up the process the main advantage speeds up the process the main advantage of this over threads is that if the tarreads of this over threads is that if the tarreads of this over threads is that if the tarreads of this over threads is that if the tarreads of the regained back are lost once, they cannot be regained back are lost once, they cannot be regained back nohere as here, use can veg recover our nohere as here, use can veg recover our program by simply turning off and turning program by simply turning off and turning on the system again.

Event-based:

Event-based poraa works on the basis of

the wesent event that has occured for examp

click of a mouse.

The next action is based on the output of

the recently occured event.



Interface paradigmis GUI- Graphic ween interface is the most It gives control of events to the user. This interface has graphic icons, which each of which have their own functionality.