

USN

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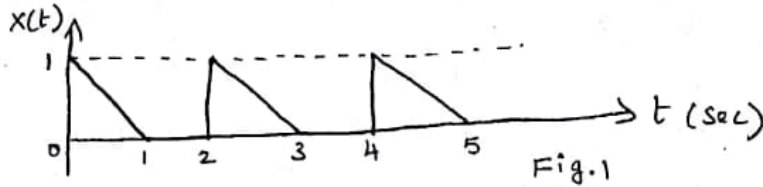
Internal Assessment Test III - NOV 2018

Sub:	Network Analysis	Sub Code:	17EC35	Branch:	ECE
Date:	19/11/2018	Duration:	90 min's	Max Marks:	50
				Sem / Sec:	3A/3B/3C

Answer any FIVE FULL Questions

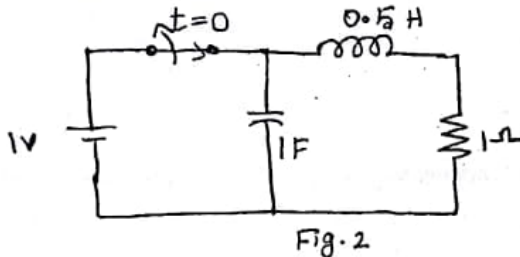
- 1 Obtain the laplace transform for the periodic signal given in Fig.1

MARKS [10] CO RBT
CO4 L3



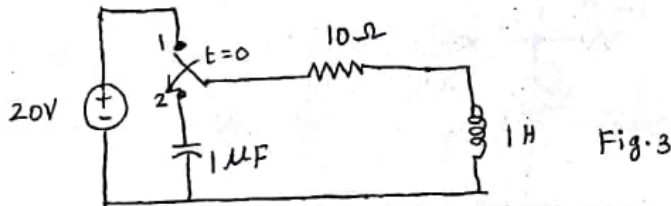
- 2 The network shown in Fig.2 was in steady state before $t=0$. The switch is opened at $t=0$. Find $i(t)$ for $t>0$ using laplace transform.

[10] CO4 L3



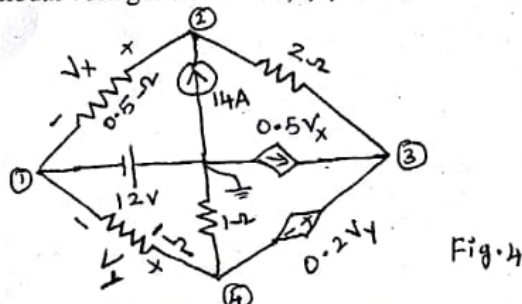
- 3 In the circuit shown in Fig.3 switch K is changed from position 1 to 2 at $t=0$, steady state having been attained in position 1. Find the values of I , first derivative and second derivative of I at $t=0^+$

[10] CO3 L3



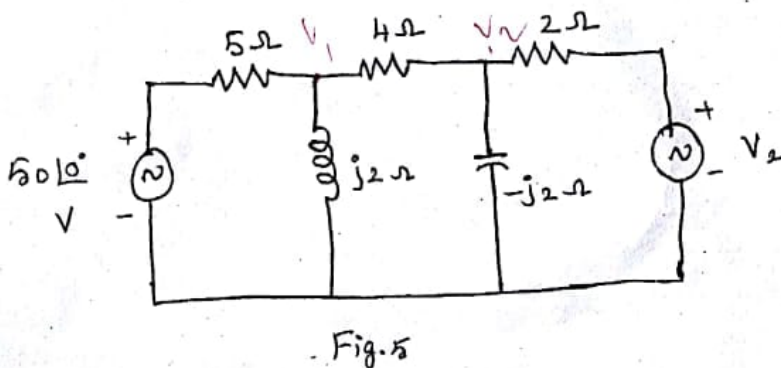
- 4 Find the nodal voltages at nodes 1,2,3,4 for the network shown in Fig.4

[10] CO1 L3



- 5 In the circuit shown in Fig.5 determine V_2 , which results in zero current through the 4Ω resistor. Use mesh analysis.

[10] CO1 L3



6 For the network shown in Fig.6 find Z-parameters.

[10] CO6 L3

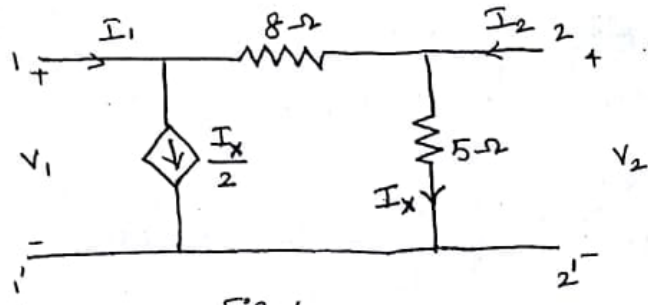


Fig. 6

7 Define 'h' and 'T' parameters. Derive 'h' parameters in terms of 'T' and 'T' parameters in terms of h parameters.

[10] CO6 L3

8 For the circuit shown in Fig.8, find node voltages V_1, V_2, V_3 using node analysis.

[10] CO1 L3

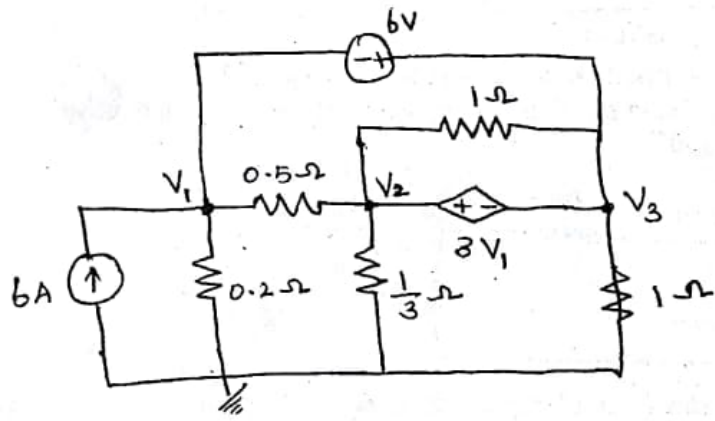
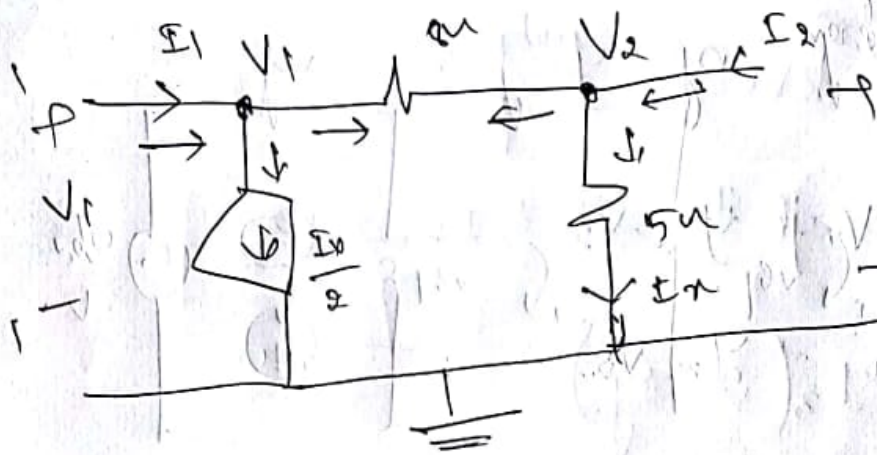


Fig. 8

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Applying nodal analysis

$$I_1 = \frac{V_1 - V_2}{1} + \frac{I_x}{2}$$

But $I_x = \frac{V_2}{5} \rightarrow \frac{I_x}{2} = \frac{V_2}{10}$

$$I_1 = \frac{V_1 - V_2}{1} + \frac{V_2}{10}$$

$$I_1 = 0.125 V_1 - 0.025 V_2$$

$$I_1 = 0.125 V_1 - 0.025 V_2 \quad \text{--- (1)}$$

Also

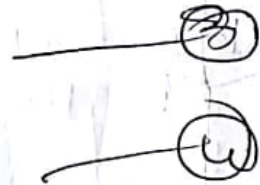
$$I_2 = \frac{V_2 - V_1}{1} + \frac{V_2}{5}$$

$$I_2 = -0.125 V_1 + 0.325 V_2 \quad \text{--- (2)}$$

By definition of y

$$I_1 = y_{11} V_1 + y_{12} V_2$$

$$I_2 = y_{21} V_1 + y_{22} V_2$$



Comparing (1) & (2) (3) & (4)

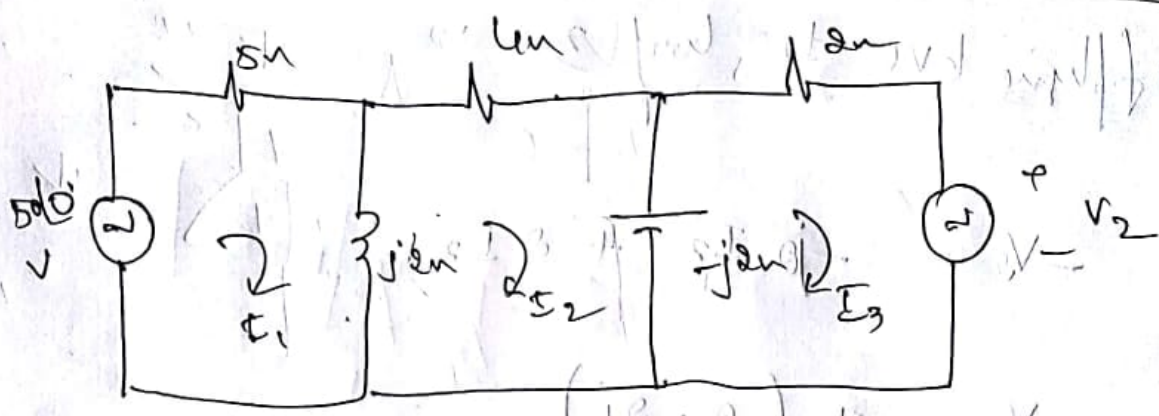
$$y = \begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} = \begin{bmatrix} 0.125 & -0.025 \\ -0.125 & 0.325 \end{bmatrix} \Omega$$

By Relationship b/w z & y

$$z = \begin{bmatrix} z_{11} & z_{12} \\ z_{21} & z_{22} \end{bmatrix} = \begin{bmatrix} \frac{y_{22}}{\Delta y} & -\frac{y_{12}}{\Delta y} \\ -\frac{y_{21}}{\Delta y} & \frac{y_{11}}{\Delta y} \end{bmatrix}$$

where $\Delta y = y_{11} y_{22} - y_{12} y_{21} = 0.0375$

$$z = \begin{bmatrix} z_{11} & z_{12} \\ z_{21} & z_{22} \end{bmatrix} = \begin{bmatrix} 8.67 & 0.67 \\ 3.33 & 3.33 \end{bmatrix} \Omega$$



Applying KVL to the loops. 1

$$50 = I_1 (5 + j2) - 0 \quad [\because I_2 = 0]$$

$$I_1 = 9.28 \angle -21.80^\circ \text{ A}$$

Applying KVL to loop 2

$$0 = (j2 + 4 + (-j2)) I_2 - j2 I_1 - (j2) I_3$$

$$0 = (j2 I_1) - (j2 I_3)$$

~~$$j2 I_1 = j2 I_3$$~~

$$-j2 I_3 = -j2 I_1$$

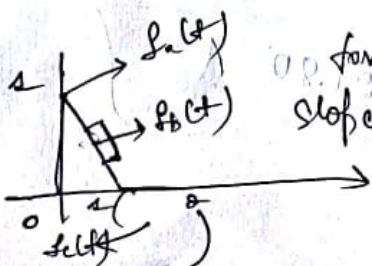
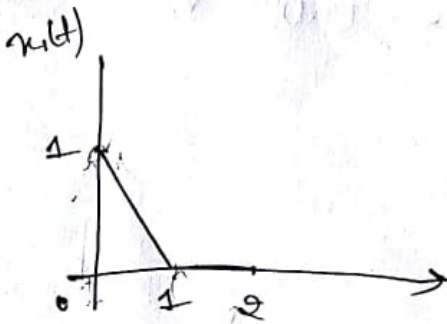
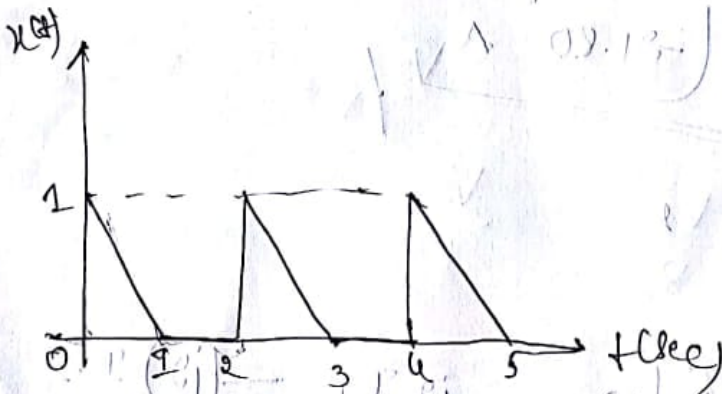
$$I_3 = 9.28 \angle -21.80^\circ \text{ A}$$

Applying KVL to loop 3

$$-V_2 + j\omega I_3 + 2I_3$$

$$-V_2 = I_3(2 - 2j)$$

$$V_2 = 26.24 \angle 113.2^\circ \text{ V}$$



for $f_2(t)$
slope = -1

Since it is a periodic function

$$X(s) = \frac{x_1(s)}{1 - e^{-Ts}}$$

where $T = 2$

$$\therefore X(s) = \frac{x_1(s)}{1 - e^{-2s}} \quad \text{--- (1)}$$

$$x(t) = ut - t^2 + (t-1)u(t-1)$$

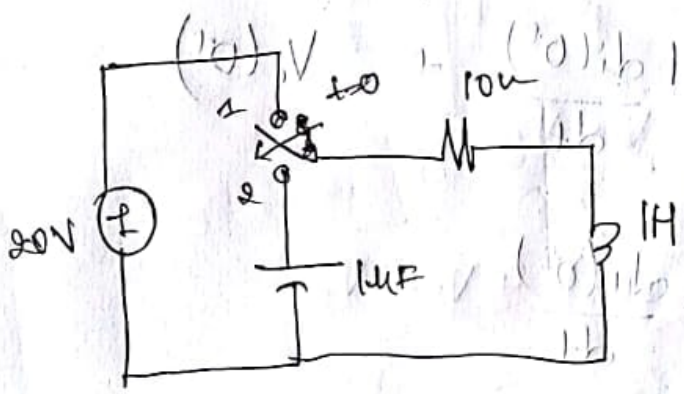
using Laplace transform on both sides

$$X(s) = \frac{1}{s} - \frac{1}{s^2} + \frac{1}{s^2} e^{-s}$$

substituting in eqn (1)

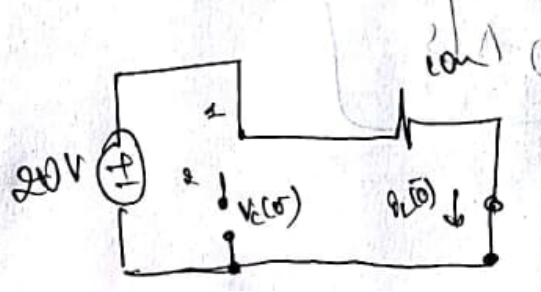
$$X(s) = \frac{\frac{1}{s} - \frac{1}{s^2} + \frac{1}{s^2} e^{-s}}{1 - e^{-s}}$$

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$$L \frac{di}{dt} = \dots$$

At $t=0^-$, switch is at position 1. Steady state. Also i is



Applying KVL

$$i_L(0^-) = \frac{20}{10} = 2A = i_L(0^-)$$

$$\text{Also } v_C(0^-) = 0V = v_C(0^-)$$

Q. (ii) At $t=0^+$, switch is not position 2



Applying KVL to the loop,

$$0 = i(t)R + L \frac{di(t)}{dt} + \frac{1}{C} \int i(t) dt \quad \text{--- (1)}$$

At $t=0^+$

$$0 = i(0^+)10 + \frac{1}{C} \frac{dQ(0^+)}{dt} + V_C(0^+)$$

$$0 = 2 \times 10^{-3} \text{ A} + \frac{dQ(0^+)}{dt}$$

$$-20 = \frac{dQ(0^+)}{dt}$$

$$\frac{dQ(0^+)}{dt} = -20 \text{ A/s}$$

Differential equation of (1) is

$$0 = \frac{di(t)}{dt} R + L \frac{d^2 i(t)}{dt^2} + \frac{i(t)}{C} \quad (1)$$

At $t = 0^+$

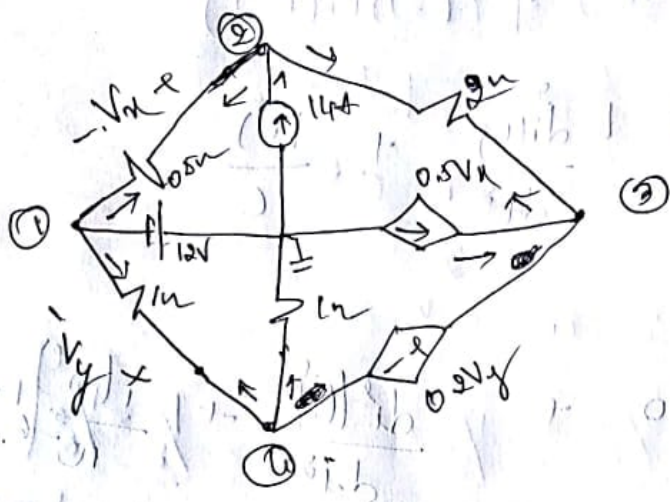
$$0 = \frac{di(0^+)}{dt} L + \frac{i(0^+)}{10^{-6}}$$

$$0 = (-20) \cdot 10 + \frac{di^2(0^+)}{dt^2} \left[\frac{2}{10^{-6}} \right]$$

$$\frac{d^2 i(0^+)}{dt^2} = \frac{200 - 2 \times 10}{2.0}$$

$$\frac{d^2 i(0^+)}{dt^2} = 1.99 \times 10^6 \text{ A/s}^2$$

5



$$V_1 = -12V$$

Applying nodal analysis at ②.

$$14 = \frac{V_2 - V_1}{0.5} + \frac{V_2 - V_3}{2}$$

$$14 = \frac{2(V_2 + 12)}{1} + \frac{V_2 - V_3}{2}$$

$$28 = 4(V_2 + 12) + (V_2 - V_3)$$

$$28 = 5V_2 - V_3 + 48$$

$$5V_2 - V_3 = -20 \quad \text{--- (1)}$$

Applying super node ③ & ④

$$V_3 - V_4 = 0.2V_y$$

$$V_y = V_u - V_l$$

$$N_y = 1.2 V_u + 1.2 V_l$$

$$V_3 - V_4 = 0.2 (N_u + 1.2)$$

$$V_3 - V_u = 0.2 V_u + 2.4 \quad (1)$$

$$V_3 - 1.2 V_u = 2.4$$



$$0.5 V_m = \frac{V_3 - V_2}{2} + \frac{V_4}{1} + \frac{V_u - V_l}{1}$$

$$V_u = V_3 - V_l$$

$$V_m = V_2 + 1.2$$

$$0.5 (V_2 + 1.2) = \frac{V_3 - V_2}{2} + \frac{V_u}{1} + \frac{V_u + 1.2}{1}$$

$$V_2 + 1.2 = V_3 - V_2 + 2V_u + 2V_u + 2.4$$

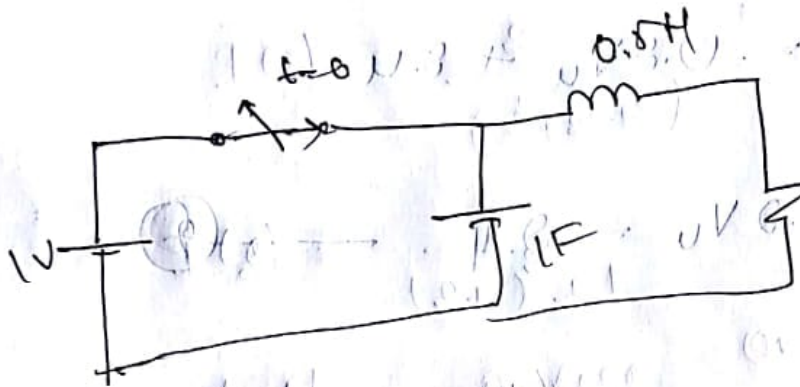
$$V_3 - 2V_2 + 2V_u = -1.2$$

Solving eqn (1) & (3)

$$V_2 = -4.6 \text{ V}$$

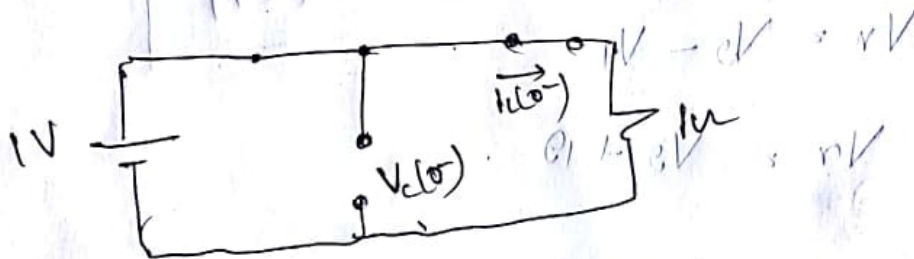
$$V_3 = -3.05 \text{ V}$$

$$V_4 = -4.54 \text{ V}$$



$i(t=0^+) = 0$
using Laplace for

(a) At $t=0^-$, it is in steady state; switch is closed



Applying KVL

$$V_c(t) = i(t) = 1 \text{ A} = i(t=0^+)$$

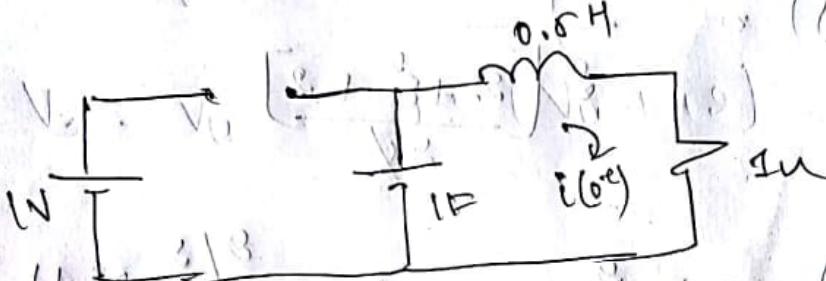
$V_3 = 0 \text{ V}$

$$V_c(t) = 1 \text{ V} = V_c(t=0^+)$$

(b)

Case (i)

At $t = 0^+$, switch is open



Applying KVL

$$0 = i(t)R + L \frac{di(t)}{dt} + \int_{-\infty}^t i(t) dt$$

~~$i(t) = 0$~~

$$0 = i(t) + 0.5 \frac{di(t)}{dt}$$

Using Laplace transform on both sides

$$0 = I(s)R + LsI(s) + \frac{1}{Cs} \left[\int_{-\infty}^{0^-} I(t) dt + \int_{0^-}^{\infty} I(t) dt \right]$$

$$0 = I(s) + 0.5sI(s) - \frac{1}{s} + \frac{1}{Cs} I(s)$$

$$0 = I(s) \left[1 + 0.5s + \frac{1}{s} \right] - \frac{1}{s}$$

$$\frac{1}{s} = \left(1 + \frac{0.5}{s} + \frac{1}{s} \right) I(s)$$

$$I(s) = \frac{1}{s \left(\frac{1+s}{2} + \frac{1}{s} \right)}$$

$$I(s) = \frac{1}{s \left[\frac{2s + s^2 + 2}{2} \right]}$$

$$I(s) = \frac{2}{(s^2 + 2s + 2)}$$

$$I(s) = \frac{2}{(s+1)^2 + 1}$$

using Laplace inverse on above eqn

$$i(t) = 2 \sin t e^{-t}$$

$$i(t) = e^{-t} \cos t + e^{-t} \sin t$$

$$\frac{1}{s} + \frac{1}{s} = \frac{2}{s} \Rightarrow (2)E = 0 \Rightarrow (2)E = 0$$

$$\left[\begin{array}{c|c} 1 & 3 \times 0 \\ \hline 2 & 1 \end{array} \right] (2)E = 0$$

$$(2)E = \left(\begin{array}{c|c} 1 & 3 \times 0 \\ \hline 2 & 1 \end{array} \right)$$

7

h parameters of T

By definition of T

we need

$$V_1 = AV_2 - BI_2 \quad \text{--- (1)}$$

$$V_1 = h_{11}I_1 + h_{12}V_2$$

$$I_1 = CV_2 - DI_2 \quad \text{--- (2)}$$

$$I_2 = h_{21}I_1 + h_{22}V_2$$

from eqn (2)

$$I_1 = CV_2 - DI_2$$

substituting eqn (1) $DI_2 = CV_2 - I_1$

$$I_2 = \frac{C}{D}V_2 - \frac{I_1}{D}$$

And $AV_2 - BI_2$

$$I_2 = -\frac{1}{D}I_1 + \frac{C}{D}V_2 \quad \text{--- (5)}$$

from (1)

$$V_1 = AV_2 - BI_2$$

$$V_1 = AV_2 - B \left[-\frac{1}{D}I_1 + \frac{C}{D}V_2 \right]$$

$$V_1 = AV_2 + \frac{B}{D}I_1 - \frac{BC}{D}V_2$$

$$V_1 = \frac{B}{D} I_1 + \left(\frac{AD - BC}{D} \right) V_2 \quad \text{--- (6)}$$

From eqn (3) & (4) (5) & (6)

$$h = \begin{bmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{bmatrix} = \begin{bmatrix} B/D & \Delta T/D \\ -1/D & C/D \end{bmatrix}$$

Rank of h

$$\Delta T = AD - BC$$

By definition of h

$$V_1 = h_{11} I_1 + h_{12} V_2 \quad \text{--- (1)}$$

$$I_2 = h_{21} I_1 + h_{22} V_2 \quad \text{--- (2)}$$

We need

$$V_1 = A V_2 - B I_2 \quad \text{--- (3)}$$

$$I_1 = C V_2 - D I_2 \quad \text{--- (4)}$$

from (2)

$$I_2 = h_{21} I_1 + h_{22} V_2$$

$$I_1 = \frac{1}{h_{21}} I_2 - \frac{h_{22}}{h_{21}} V_2 \quad \text{--- (5)}$$

Substituting in eqn (1)

$$V_1 = h_{11} \left[\frac{I_2}{h_{21}} - \frac{h_{22}}{h_{21}} V_2 \right] + h_{12} V_2$$

$$(d) V_1 = \frac{h_1 I_a}{h_{e1}} + \frac{h_1 h_{e2}}{h_{e1}} V_2 + h_{e2} V_2$$

$$V_1 = \left(\frac{\Delta h}{h_{e1}} \right) V_2 + \frac{h_1 I_a}{h_{e1}} \quad (6)$$

from eqn 3, 4, 5 & 6

$$T = \begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} -\frac{\Delta h}{h_{e1}} & -\frac{h_1}{h_{e1}} \\ -\frac{h_{e2}}{h_{e1}} & -\frac{1}{h_{e1}} \end{bmatrix}$$

Law of

(1) $V_1 = V_2$
 (2) $V_1 = V_2$
 (3) $V_1 = V_2$

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 (2) $V_1 = V_2$
 (3) $V_1 = V_2$

from (2)

(2)

$V_1 = V_2$

$V_1 = V_2$

(1) $V_1 = V_2$