

two extreme positions of pitching is 12 degrees.

Equilibrium of Two Force Members

A member under the action of two forces will be in equilibrium if

- The forces are of the same magnitude,
- The forces act along the same line, and the forces are in opposite directions

Equilibrium of Three Force Members

A member under the action of three forces will be in equilibrium if

- The resultant of the forces is zero, and
- The lines of action of the forces intersect at a point (known as *point of concurrency).*

Figure (a) indicates an example for the three force member and (b) and (c) indicates the force polygon to check for the static equilibrium.

Member with two forces and a torque

A member under the action of two forces and an applied torque will be in equilibrium if

- The forces are equal in magnitude, parallel in direction and opposite in sense and
- The forces form a couple which is equal and opposite to the applied torque.

Figure shows a member acted upon by two equal forces **F1**, and **F2** and an applied torque **T** for equilibrium,

$$
T = F_1 h = F_2 h
$$

Where *T*, F_1 *and* F_2 *are the magnitudes of T***,** F_1 *and* F_2 respectively.

T is clockwise whereas the couple formed by **F1**, and **F²** is counter-clockwise.

In a four-link mechanism shown in Fig., torque T_3 and T_4 have magnitudes of 30 N-m and 20 N-m respectively. The link lengths are $AD = 800$ mm, $AB = 300$ mm, $BC = 700$ mm and $CD = 400$ mm. For the static equilibrium of the mechanism, determine the required input torque T_2

Neglecting torque T_3

Torque T_4 on the link 4 is balanced by a couple having two equal, parallel and opposite forces at C and *D*. As the link 3 is a two-force member, F_{43} and therefore, F_{34} and F_{14} will be parallel to *BC.*

$$
F_{34} = F_{14} = \frac{T_4}{h_{4a}} = \frac{20}{0.383} = 52.2 \text{ N}
$$

and $F_{34} = F_{43} = F_{23} = F_{32} = F_{12} = 52.2$ N

 $T_{2a} = F_{32}$ x $h_{2a} = 52.2$ x 0.274 = 14.3 N.m counter-clockwise.

Neglecting torque T_4

F⁴³ is along CD. The diagram is self-explanatory.

 $F_{43} = F_{23} = \frac{T_3}{L}$ $\frac{T_3}{h_{3b}} = \frac{30}{0.6}$ $\frac{50}{0.67}$ = 44.8 N ; F₂₃ = F₃₂ = F₁₂ = 44.8 N $T_2 = T_{2a} + T_{2b} = 14.3 + 1.88 = 16.18$ N Counter clockwise

 F_{32} and F_{12} form a CCW couple and hence T_2 acts clock wise.

Gyroscopic Couple

•Consider a disc spinning with an angular velocity ω rad/s about the axis of spin OX, in anticlockwise direction when seen from the front, as shown in Fig.

•Since the plane in which the disc is rotating is parallel to the plane YOZ therefore it is called plane of spinning.

Let *I* = Mass moment of inertia of the disc about *OX,* and ω = Angular velocity of the disc.

Angular momentum of the disc = $I\omega$

 \therefore Change in angular momentum

$$
= \overrightarrow{ox} - \overrightarrow{ox} = \overrightarrow{xx} = \overrightarrow{ox}.\delta\theta
$$
...(in the direction of \overrightarrow{xx})
= I. ω . $\delta\theta$

and rate of change of angular momentum

$$
= I \cdot \omega \times \frac{\delta \theta}{dt}
$$

Since the rate of change of angular momentum will result by the application of a couple to the disc, therefore the couple applied to the disc causing precession,

$$
C = \text{Lt} \ I. \omega \times \frac{\delta \theta}{\delta t} = I. \omega \times \frac{d\theta}{dt} = I. \omega. \omega_{\text{p}} \qquad \qquad \dots \left(\because \frac{d\theta}{dt} = \omega_{\text{p}} \right)
$$

4.a

$$
\omega = \frac{2\pi N}{60} = \frac{2\pi \times 720}{60}
$$

= 75.4 rad/s
Angular velocity of precession:
$$
\omega_p = \frac{2\pi N_p}{60}
$$

$$
= \frac{2\pi \times 30}{60} = 3.14 \text{ rad/s}
$$

Moment of inertia:
$$
I = mk^2
$$

$$
= 5 \times 0.07^2 = 0.0245 \text{ kg m}^2
$$
Gyroscopic couple:
$$
C = I \omega \omega_p
$$

$$
= 0.0245 \times 75.4 \times 3.14
$$

$$
= 5.8 \text{ Nm}
$$

5.

Given : R = 60 m ; v = 240 km/hr = $\frac{240 \times 1000}{3600}$ = 66.67 m/s ; m = 450 kg ; k = 0.32 m

 $N = 2000$ r.p.m. or $\omega = 2\pi N/60 = 2\pi x 2000/60 = 209.43$ rad/s

Mass moment of inertia of the rotor, $I = m k^2 = 450 (0.32)^2 = 46.08 \text{ kg} \cdot \text{m}^2$

Angular velocity of precession, $\omega_p = \frac{v}{R}$ $\frac{v}{R} = \frac{66.67}{60}$ $\frac{6.67}{60}$ = 1.11 rad/s

Gyroscopic couple, $C = I \omega \omega_p = 46.08 \times 209.43 \times 1.11 = 10712.09 \text{ N-m}$

Effect

When the aero-plane turns towards left, the effect of the gyroscopic couple is to lift the nose upwards and tail downwards.

When the engine or propeller rotates in clockwise direction when viewed from the rear or tail end and the aeroplane takes a right turn, the effect of the reactive gyroscopic couple will be to dip the nose and raise the tail of the aeroplane.

6. Given: *m =* 3500 kg ; *k = 045* m; $N = 3000$ r.p.m. or $\omega = 2\pi x \cdot 3000/60 = 314.2$ rad/s

i. *When the ship is steering to the left*

Given: $R = 100$ m; $v = km/h = 10$ m/s

Mass moment of inertia of the rotor, $I = m k^2 = 3500 (0.45)^2 = 708.75 \text{ kg} \cdot \text{m}^2$

Angular velocity of precession, $\omega_p = \frac{v}{R}$ $\frac{v}{R} = \frac{10}{100}$ $\frac{10}{100}$ = 0.1 rad/s.

Gyroscopic couple, $C = I \omega \omega_p = 708.75 \times 314.2 \times 0.1 = 22\,270 \text{ N-m} = 22.27 \text{ kN-m}.$

ii. When the ship is pitching with the bow falling Given: $t_p = 40$ s Total angular displacement between the two extreme positions of pitching is 12 *(i.e* $2\phi = 12^{\circ}$ *)*, therefore amplitude of swing,

 $\phi = 12/2 = 6^{\circ}$; $6^{\circ} = \frac{6 \times \pi}{100}$ $\frac{6 \times n}{180}$ = 0.105 rad

Angular velocity of the simple harmonic motion,

$$
\omega_1 = \frac{2\pi}{t_p} = \frac{2\pi}{40} = 0.157 \, r/s
$$

Maximum angular velocity of precession,

$$
\omega_p = \phi \omega_1 = 0.105 \times 0.157 = 0.0165 \, rad/s
$$

Gyroscopic couple, $C = I \omega \omega_p$ $= 708.75 \times 3142 \times 0.0165 = 3675 \text{ N-m} = 3.675 \text{ kN-m}.$

When the bow is falling *(i.e. when the pitching is downward),* the effect of the reactive gyroscopic couple is to **move the ship towards port side.**

